

Process P		Process Q	
Step	Action	Step	Action
p ₀	Request (D)	q ₀	Request (T)
p ₁	Lock (D)	q ₁	Lock (T)
p ₂	Request (T)	q ₂	Request (D)
p ₃	Lock (T)	q ₃	Lock (D)
p ₄	Perform function	q ₄	Perform function
p ₅	Unlock (D)	q ₅	Unlock (T)
p ₆	Unlock (T)	q ₆	Unlock (D)

Figure 6.4 Example of Two Processes Competing for Reusable Resources

	R1	R2	R3
P1	3	2	2
P2	6	1	3
P3	3	1	4
P4	4	2	2

Claim Matrix

	R1	R2	R3
P1	1	0	0
P2	6	1	2
P3	2	1	1
P4	0	0	2

Allocation Matrix

R1	R2	R3
9	3	6

Resource Vector

R1	R2	R3
0	1	1

Available Vector

(a) Initial state

	R1	R2	R3
P1	3	2	2
P2	0	0	0
P3	3	1	4
P4	4	2	2

Claim Matrix

	R1	R2	R3
P1	1	0	0
P2	0	0	0
P3	2	1	1
P4	0	0	2

Allocation Matrix

R1	R2	R3
6	2	3

Available Vector

(b) P2 runs to completion

	R1	R2	R3
P1	0	0	0
P2	0	0	0
P3	3	1	4
P4	4	2	2

Claim Matrix

	R1	R2	R3
P1	0	0	0
P2	0	0	0
P3	2	1	1
P4	0	0	2

Allocation Matrix

R1	R2	R3
7	2	3

Available Vector

(c) P1 runs to completion

	R1	R2	R3
P1	0	0	0
P2	0	0	0
P3	0	0	0
P4	4	2	2

Claim Matrix

	R1	R2	R3
P1	0	0	0
P2	0	0	0
P3	0	0	0
P4	0	0	2

Allocation Matrix

R1	R2	R3
9	3	4

Available Vector

(d) P3 runs to completion

Figure 6.6 Determination of a Safe State

	R1	R2	R3
P1	3	2	2
P2	6	1	3
P3	3	1	4
P4	4	2	2

Claim Matrix

	R1	R2	R3
P1	1	0	0
P2	5	1	1
P3	2	1	1
P4	0	0	2

Allocation Matrix

R1	R2	R3
9	3	6

Resource Vector

R1	R2	R3
1	1	2

Available Vector

(a) Initial state

	R1	R2	R3
P1	3	2	2
P2	6	1	3
P3	3	1	4
P4	4	2	2

Claim Matrix

	R1	R2	R3
P1	2	0	1
P2	5	1	1
P3	2	1	1
P4	0	0	2

Allocation Matrix

R1	R2	R3
0	1	1

Available Vector

(b) P1 requests one unit each of R1 and R3

Figure 6.7 Determination of an Unsafe State