

**Table 9.1 Types of Scheduling**

Long-term scheduling	The decision to add to the pool of processes to be executed
Medium-term scheduling	The decision to add to the number of processes that are partially or fully in main memory
Short-term scheduling	The decision as to which available process will be executed by the processor
I/O scheduling	The decision as to which process's pending I/O request shall be handled by an available I/O device

## Table 9.2 Scheduling Criteria

<b>User Oriented, Performance Related</b>	
<b>Turnaround time</b>	This is the interval of time between the submission of a process and its completion. Includes actual execution time plus time spent waiting for resources, including the processor. This is an appropriate measure for a batch job.
<b>Response time</b>	For an interactive process, this is the time from the submission of a request until the response begins to be received. Often a process can begin producing some output to the user while continuing to process the request. Thus, this is a better measure than turnaround time from the user's point of view. The scheduling discipline should attempt to achieve low response time and to maximize the number of interactive users receiving acceptable response time.
<b>Deadlines</b>	When process completion deadlines can be specified, the scheduling discipline should subordinate other goals to that of maximizing the percentage of deadlines met.
<b>User Oriented, Other</b>	
<b>Predictability</b>	A given job should run in about the same amount of time and at about the same cost regardless of the load on the system. A wide variation in response time or turnaround time is distracting to users. It may signal a wide swing in system workloads or the need for system tuning to cure instabilities.
<b>System Oriented, Performance Related</b>	
<b>Throughput</b>	The scheduling policy should attempt to maximize the number of processes completed per unit of time. This is a measure of how much work is being performed. This clearly depends on the average length of a process but is also influenced by the scheduling policy, which may affect utilization.
<b>Processor utilization</b>	This is the percentage of time that the processor is busy. For an expensive shared system, this is a significant criterion. In single-user systems and in some other systems, such as real-time systems, this criterion is less important than some of the others.
<b>System Oriented, Other</b>	
<b>Fairness</b>	In the absence of guidance from the user or other system-supplied guidance, processes should be treated the same, and no process should suffer starvation.
<b>Enforcing priorities</b>	When processes are assigned priorities, the scheduling policy should favor higher-priority processes.
<b>Balancing resources</b>	The scheduling policy should keep the resources of the system busy. Processes that will underutilize stressed resources should be favored. This criterion also involves medium-term and long-term scheduling.

**Table 9.4 Process Scheduling Example**

<b>Process</b>	<b>Arrival Time</b>	<b>Service Time</b>
A	0	3
B	2	6
C	4	4
D	6	5
E	8	2

**Table 9.6 Formulas for Single-Server Queues with Two Priority Categories**

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- Assumptions:
1. Poisson arrival rate.
  2. Priority 1 items are serviced before priority 2 items.
  3. First-in-first-out dispatching for items of equal priority.
  4. No item is interrupted while being served.
  5. No items leave the queue (lost calls delayed).

**(a) General Formulas**

$$\begin{aligned} &= \rho_1 + \rho_2 \\ T_s &= \rho_1 T_{s1} + \rho_2 T_{s2} \\ &= \rho_1 + \rho_2 \\ T_s &= \frac{\lambda_1}{\lambda} T_{s1} + \frac{\lambda_2}{\lambda} T_{s2} \\ T_r &= \frac{\lambda_1}{\lambda} T_{r1} + \frac{\lambda_2}{\lambda} T_{r2} \end{aligned}$$

**(b) No interrupts; exponential service times**

$$\begin{aligned} T_{r1} &= T_{s1} + \frac{\rho_1 T_{s1} + \rho_2 T_{s2}}{1 - \rho_1} \\ T_{r2} &= T_{s2} + \frac{T_{r1} - T_{s1}}{1 - \rho} \end{aligned}$$

**(c) Preemptive-resume queuing discipline; exponential service times**

$$\begin{aligned} T_{r1} &= 1 + \frac{\rho_1 T_{s1}}{1 - \rho_1} \\ T_{r2} &= 1 + \frac{1}{1 - \rho} (\rho_1 T_{s1} + \frac{\rho T_s}{1 - \rho}) \end{aligned}$$


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**Table 9.7 Response Time Ranges**

**Greater than 15 seconds**

This rules out conversational interaction. For certain types of applications, certain types of users may be content to sit at a terminal for more than 15 seconds waiting for the answer to a single simple inquiry. However, for a busy person, captivity for more than 15 seconds seems intolerable. If such delays will occur, the system should be designed so that the user can turn to other activities and request the response at some later time.

**Greater than 4 seconds**

These are generally too long for a conversation requiring the operator to retain information in short-term memory (the operator's memory, not the computer's!). Such delays would be very inhibiting in problem-solving activity and frustrating in data entry activity. However, after a major closure, delays from 4 to 15 seconds can be tolerated.

**2 to 4 seconds**

A delay longer than 2 seconds can be inhibiting to terminal operations demanding a high level of concentration. A wait of 2 to 4 seconds at a terminal can seem surprisingly long when the user is absorbed and emotionally committed to complete what he or she is doing. Again, a delay in this range may be acceptable after a minor closure has occurred.

**Less than 2 seconds**

When the terminal user has to remember information throughout several responses, the response time must be short. The more detailed the information remembered, the greater the need for responses of less than 2 seconds. For elaborate terminal activities, 2 seconds represents an important response-time limit.

**Subsecond response time**

Certain types of thought-intensive work, especially with graphics applications, require very short response times to maintain the user's interest and attention for long periods of time.

**Decisecond response time**

A response to pressing a key and seeing the character displayed on the screen or clicking a screen object with a mouse needs to be almost instantaneous—less than 0.1 second after the action. Interaction with a mouse requires extremely fast interaction if the designer is to avoid the use of alien syntax (one with commands, mnemonics, punctuation, etc.) .

**Table 9.8 Notation for Queuing Systems**

$\lambda$  = arrival rate; mean number of arrivals per second

$T_s$  = mean service time for each arrival; amount of time being served, not counting time waiting in the queue

$\rho$  = utilization; fraction of time facility (server or servers) is busy

$w$  = mean number of items waiting to be served

$T_w$  = mean waiting time for (including items that have to wait and items with waiting time = 0)

$r$  = mean number of items resident in system (waiting and being served)

$T_r$  = mean residence time; time an item spends in system (waiting and being served)