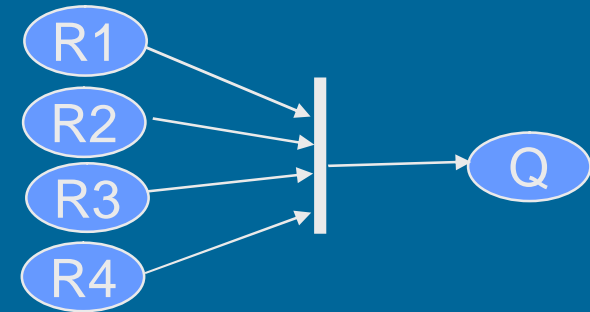


Semaphore Use In Synchronization

Ch 6 [BenA 06]

Consumer Producer Revisited
Readers and Writers
Baton Passing
Private Semaphores
Resource Management

Synchronization with Semaphores



```
sem gate = -3; # must know number of R's (!)
```

```
Process R[i = 1 to 4]
```

```
....  
V(gate); # signal Q  
...
```

```
Process Q
```

```
....  
P (gate)  
...  
# how to prepare for next time?  
# sem_set (gate, -3) ??
```

```
sem g[i = 1 to 4] = 0;
```

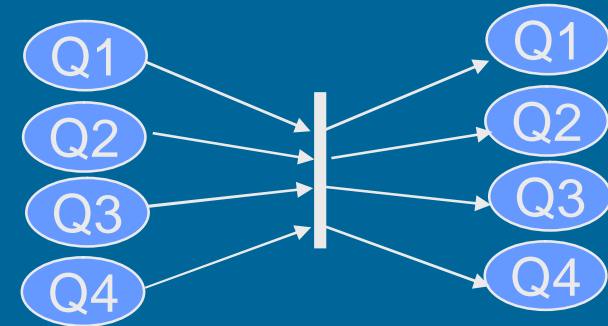
```
Process R[i = 1 to 4]
```

```
....  
V(g[i]); # signal Q  
...
```

```
Process Q
```

```
....  
P(g[1]); P(g[2]); P(g[3]); P(g[4]);  
...  
# Q must know number of R's
```

Barrier Synchronization with Semaphores



```
sem g[i = 1 to 4] = 0;  
cont = 0;
```

```
Process Q[i = 1 to 4]
```

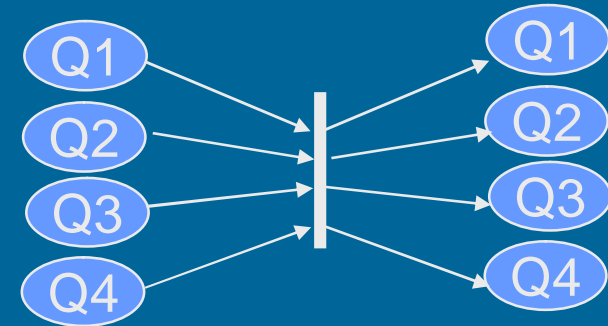
```
....  
V(g[i]); # signal others  
P(cont); # wait for others  
...
```

```
Process Barrier
```

```
....  
P(g[1]); P(g[2]); P(g[3]); P(g[4]); #wait for all  
V(cont); V(cont); V(cont); V(cont); #signal all  
...  
# Barrier must know number of Q's
```

- Barrier is implemented as separate *process*
 - This is just one possibility to implement the barrier
 - Cost of process switches?
 - How many process switches?

Barrier Synchronization with Barrier OS-Primitive



- Specific synchronization primitive in OS
 - Implemented with semaphores...
 - No need for extra process – less process switches

```
barrier br;
```

```
barrier_init (br, 4);      # must be done before use
```

```
process Q[i = 1 to 4]
```

```
....
```

```
barrier_wait (br)      # wait until all have reached this point
```

```
if (pid==1)             # is this ok? is this done in time?
```

```
    barrier_init (br, 4)
```

```
...
```

Communication with Semaphores



```
Sem mutex=1, data_ready = 0;  
Int buffer; # one data item buffer
```

Process W

```
....  
P(mutex)  
  write_buffer(data)  
V(mutex)  
V(data_ready); # signal Q  
...
```

Process R

```
....  
P(data_ready); # wait for data  
P(mutex)  
  read_buffer(data)  
V(mutex)  
....
```

- What is wrong?

W might rewrite data buffer before R reads it

- Might have extra knowledge to avoid the problem

Communication with Semaphores Correctly



```
Sem mutex=1, data_ready = 0, buffer_empty=1;  
Int buffer
```

Process W

```
....  
P(buffer_empty);  
P(mutex)  
  write_buffer(data)  
V(mutex)  
V(data_ready); # signal Q
```

Process R

```
....  
P(data_ready); # wait for data  
P(mutex)  
  read_buffer(data)  
V(mutex)  
V(buffer_empty)
```

- Fast W can not overtake R now
- One reader R, one writer W, binary semaphores
- Communication with buffer in shared memory
 - Use: 1 producer – 1 consumer – size 1 buffer

Producer-Consumer with Binary Semaphores

(Liisa Marttinen)

- Binary semaphore has values 0 and 1
 - OS or programming language library
- Semaphore does not keep count
 - Must have own variable *count* (nr of elements in buffer)
 - Protect it with critical section
- Two important state changes
 - Empty buffer becomes not empty
 - Consumer may need to be awakened
 - Full buffer becomes not full
 - Producer may need to be awakened

mutex

items

space

Simple Solution #1

(Producer-Consumer with Binary Semaphores)

```
typeT buf[n];          /* n element buffer */
int front=0,           /* read from here */
    rear=0,            /* write to this one */
    count=0;          /* nr of items in buf */
sem space=1,           /* need this to write */
    items=0,           /* need this to read */
    mutex=1;          /* need this to update count */
```


Sol. #1

```
process Producer [i=1 to M] {
while(true) {
... produce data ...
P(space); /* wait until space to write*/
P(mutex);
buf[rear] = data; rear = (rear+1) %n; count++;
if (count == 1) V(items); /* first item to empty buffer */
if (count < n) V(space); /* still room for next producer */
V(mutex);
}
}
```

```
process Consumer [i=1 to N] {
while(true) {
P(items); /* wait until items to consume */
P(mutex);
data=buf[front]; front = (front+1) %n; count--;
if (count == n-1) V(space); /* buffer was full */
if (count > 0) V(items); /* still items for next consumer */
V(mutex);
... consume data ...
}
}
```

Evaluate Solution #1

- Simple solution
 - Mutex and synchronization ok
 - Mutex inside space or items
 - Get space first and then mutex
- Buffer reserved for one producer/consumer at a time
 - Does not allow for simultaneous buffer use **Not good**
 - Producer inserts item to “rear”
 - Consumer removes item from “front” **Simultaneously?**
- First waiting producer/consumer advances when signalled
 - Queued in semaphores

Better Solution #2

(Producer-Consumer with Binary Semaphores)

```
typeT buf[n];          /* n element buffer */
int front=0,           /* read from here */
    rear=0,            /* write to this one */
    count=0;           /* nr of items in buf */
sem space=1,           /* need this to write */
    items=0,           /* need this to read */
    mutex=1;          /* need this to update count */
```

Sol. #2

```
process Producer [i=1 to M] {
while(true) {
... produce data ...
P(space); /* wait until space to write*/
buf[rear] = data; rear = (rear+1) %n; /* outside mutex, ok? */
P(mutex);
count++; /* this must be in mutex */
if (count == 1) V(items); /* first item to empty buffer */
if (count < n) V(space); /* still room for next producer */
V(mutex);
} }
}
```

```
process Consumer [i=1 to N] {
while(true) {
P(items); /* wait until items to consume */
data=buf[front]; front = (front+1) %n; /* outside mutex, ok? */
P(mutex);
count--;
if (count == n-1) V(space); /* buffer was full */
if (count > 0) V(items); /* still items for next consumer */
V(mutex);
... consume data ...
} }
}
```

Evaluate Solution #2

- Relatively simple solution
 - Data copying (insert, remove) outside critical section
 - Protected by a semaphore (*items* and *space*)
- Simultaneous insert and remove ops
 - Producer inserts item to “rear”
 - Consumer removes item from “front”
- First waiting producer/consumer advances when signalled
 - Queued in semaphores

Another Solution #3

(Producer-Consumer with Binary Semaphores)

Ehto-
synkro-
nointi

- Use condition synchronization
 - Do P(space) or P(items) only when needed
 - Expensive op?
 - Requires execution state change (kernel/user)?

```
typeT buf[n];    /* n element buffer */
int front=0,     /* read from here */
    rear=0,      /* write to this one */
    count=0,     /* nr of items in buf */
    cwp=0,       /* nr of waiting producers */
    cwc=0;     /* nr of waiting consumers */
sem space=1,    /* need this to write */
    items=0,   /* need this to read */
    mutex=1;  /* need this to update count */
```

Sol. #3

```
process Producer [i=1 to M] {
while(true) {
... produce data ...
P(mutex);
while (count == n) /* usually not true? while, not if !*/
{ cwp++; V(mutex); P(space); P(mutex); cwp-- }
buf[rear] = data; rear = (rear+1) %n; count++;
if (count == 1 && cwc>0) V(items);
if (count < n && cwp>0) V(space);
V(mutex);
} }
```

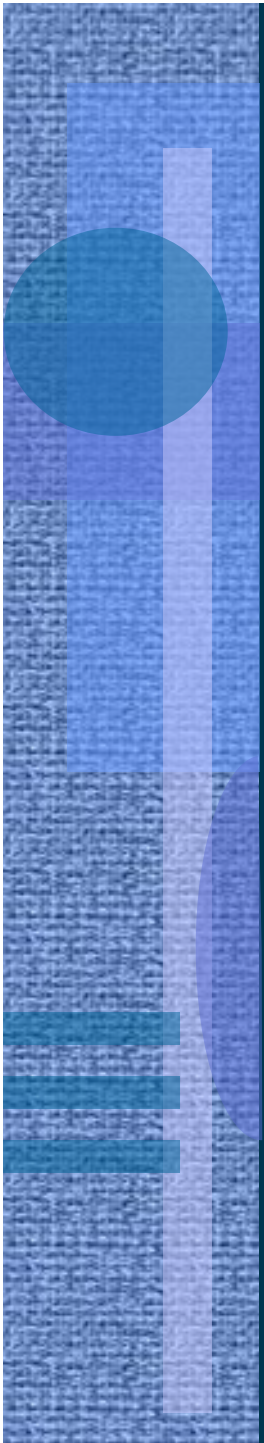
```
process Consumer [i=1 to N] {
while(true) {
P(mutex);
while (count == n) /* while, not if !*/
{ cwc++; V(mutex); P(items); P(mutex); cwc-- }
data=buf[front]; front = (front+1) %n; count--;
if (count == n-1 && cwp>0) V(space);
if (count > 0 && cwc > 0) V(items);
V(mutex);
... consume data ...
} }
```

Evaluate Solution #3

- No simultaneous insert and remove ops
 - Data copying inside critical section
- In general case, only mutex semaphore operations needed
 - Most of the time?
 - Can they be busy-wait semaphores?
- First waiting producer/consumer does not necessarily advance when signalled
 - Someone else may get mutex first
 - E.g., consumer signals (Vspace), another producer gets mutex and places its data in buffer.
 - Need “while” loop in waiting code
 - Unfair solution even with strong semaphores?
 - How to fix?
 - Baton passing (pass critical section to next process)?

Solutions #1, #2, and #3

- Which one is best? Why? When?
- How to maximise concurrency?
 - Separate data transfer (insert, remove) from permission to do it
 - Allow obtaining permission (e.g., code with $P(space)$ and updating *count*) for one process run concurrently with data transfer for another process (e.g., code with $buf[rear] = data; \dots$)
 - Need new mutexes to protect data transfers and index (*rear*, *front*) manipulation
 - Problem: signalling to other producers/consumers should happen in same critical section with updating count, but should happen only after data transfer is completed



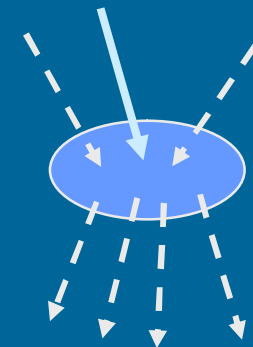
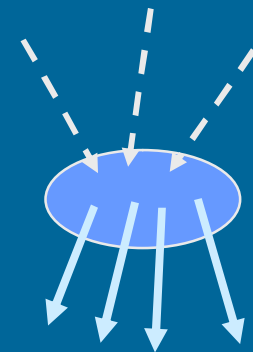
16.11.2008

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18

Readers and Writers Problem

- Shared data structure or data base
- Two types of users: readers and writers
- Readers
 - Many can read at the same time
 - Can not write when someone reads
 - Can not read when someone writes
- Writers
 - Read and modify data
 - Only one can be active at the same time
 - Can be active only when there are no readers



Jeff Magee
example

(Imperial College,
London)

http://www.doc.ic.ac.uk/~jnm/book/book_applets/ReadersWriters.html

reader
entry
protocol

reader
exit
protocol

writer
entry
protocol

writer
exit
protocol

```
sem rw = 1;
process Reader[i = 1 to M] {
  while (true) {
    ...
    P(rw);      # grab exclusive access lock
    read the database;
    V(rw);      # release the lock
  }
}
process Writer[j = 1 to N] {
  while (true) {
    ...
    P(rw);      # grab exclusive access lock
    write the database;
    V(rw);      # release the lock
  }
}
```

(Fig 4.8 [Andr00])

- Simple solution
 - Only one reader or writer at a time (not good)

```
int nr = 0;          # number of active readers
sem rw = 1;         # lock for reader/writer synchronization
```

```
process Reader[i = 1 to M] {
  while (true) {
    ...
    < nr = nr+1;
    if (nr == 1) P(rw); # if first, get lock
    read the database;
    < nr = nr-1;
    if (nr == 0) V(rw); # if last, release lock
  }
}
```

*std
mutex*

Only the first reader waits

Release mutex before P(rw)? (no need)

Writers may starve – not good.
Writers have no chance to cut in between readers.

```
process Writer[j = 1 to N] {
  while (true) {
    ...
    P(rw);
    write the database;
    V(rw);
  }
}
```

Jeff Magee example

How should you adjust the readers to starve writers?

(Fig 4.9 [Andr00])

Readers and Writers with Baton Passing Split Binary Semaphore

- Component semaphores e, r, w
 - Mutex wait in $P(e)$, initially 1
 - Readers wait in $P(r)$ if needed, initially 0
 - Writers wait in $P(w)$ if needed, initially 0
- In critical control areas only one process advances at a time
 - Wait in e, r , or w
- One advances, others wait in e, r or w
 - New reader/writer: wait in $P(e)$
 - Waiting for read turn: $V(e); P(r)$
 - Wait while not holding mutex
 - Waiting for write turn: $V(e); P(w)$
 - Wait while not holding mutex
 - When done, pass the baton (turn) to next one

$$0 \leq e+r+w \leq 1$$

(Fig 4.13 [Andr00])

(Alg. 6.21 [BenA06])

$P(e) \dots V(e)$

$P(e) \dots V(r)$

$P(e) \dots V(w)$

$P(r) \dots V(r)$

$P(r) \dots V(w)$

...

$P(w) \dots V(e)$

...

```

int nr = 0,    ## RW: (nr == 0 or nw == 0) and nw <= 1
    nw = 0;
sem e = 1,    # controls entry to critical sections
    r = 0,    # used to delay readers
    w = 0;    # used to delay writers
                # at all times 0 <= (e+r+w) <= 1
int dr = 0,    # number of delayed readers
    dw = 0;    # number of delayed writers

```

**Andrews Fig. 4.12:
Outline of readers
and writers with
passing the baton.**

```

process Reader[i = 1 to M] {
  while (true) {
    # <await (nw == 0) nr = nr+1;>
    P(e);
    if (nw > 0)
      { dr = dr+1; V(e); P(r); }
    nr = nr+1;
    SIGNAL;
    read the database;
    # <nr = nr-1;>
    P(e);
    nr = nr-1;
    SIGNAL;
  }
}

```

```

process Writer[j = 1 to N] {
  while (true) {
    # <await (nr == 0 and nw == 0) nw = nw+1;>
    P(e);
    if (nr > 0 or nw > 0)
      { dw = dw+1; V(e); P(w); }
    nw = nw+1;
    SIGNAL;
    write the database;
    # <nw = nw-1;>
    P(e);
    nw = nw-1;
    SIGNAL;
  }
}

```

(rStart)

(rExit)

(wStart)

(wExit)

??

~~P(e) ... V(w) ?~~

~~P(r) ... V(w) ?~~

~~P(e) ... V(e) ?~~

~~P(r) ... V(e) ?~~

~~P(e) ... V(w) ?~~

Baton passing = "do not just release CS, give it to someone special..."

Baton passing

- When done your own mutex zone, wake up next ... (one or more semaphores control the same mutex)
 - If reader waiting and no writers: $V(r)$
 - Do not release mutex (currently reserved e, r, or w)
 - New reader will continue with mutex already locked “pass the mutex baton to next reader”
 - No one else can come to mutex zone in between
 - Last waiting reader will close the mutex with $V(e)$
 - Can happen concurrently when reading database
 - Else if writer waiting and no readers: $V(w)$
 - Do not release mutex, pass baton to writer
 - Else (let new process to compete with old ones): $V(e)$
 - Release mutex to let new process in the game (to execute entry or exit protocols)
 - New process gets in mutex only when no old one can be advance
 - Can happen concurrently when reading database

SIGNAL()

Baton Passing with SIGNAL

SIGNAL – CS baton passing, priority on readers

```
if (nw == 0 and dr > 0) {  
    dr = dr - 1;  
    V(r);           # wake up waiting reader  
}  
else if (nr == 0 and nw == 0 and dw > 0) {  
    dw = dw - 1;  
    V(w);           # wake up waiting writer  
}  
else  
    V(e);           # let new process to mix
```

*“pass
the
baton
within
CS”*

*“just
complete
CS”*

*not
possible
in wStart,
rExit*

*not
possible
in rStart*

```

process Reader[i = 1 to M] {
  while (true) {
    # <await (nw == 0) nr = nr+1;>
    P(e);
    if (nw > 0) { dr = dr+1; V(e); P(r); }
    nr = nr+1;
    if (dr > 0) { dr = dr-1; V(r); }
    else V(e);
    read the database;
    # <nr = nr-1;>
    P(e);
    nr = nr-1;
    if (nr == 0 and dw > 0)
      { dw = dw-1; V(w); }
    else V(e);
  }
}

```

```

P(e);
if (nw > 0) { dr = dr+1; V(e); P(r); }
nr = nr+1;
if (dr > 0) { dr = dr-1; V(r); }
else V(e);

```

```

P(e);
nr = nr-1;
if (nr == 0 and dw > 0)
  { dw = dw-1; V(w); }
else V(e);
}

```

```

process Writer[j = 1 to N] {
  while (true) {
    # <await (nr==0 and nw==0) nw = nw+1;>
    P(e);
    if (nr > 0 or nw > 0)
      { dw = dw+1; V(e); P(w); }
    nw = nw+1;
    V(e);
    write the database;
    # <nw = nw-1;>
    P(e);
    nw = nw-1;
    if (dr > 0) { dr = dr-1; V(r); }
    elseif (dw > 0) { dw = dw-1; V(w); }
    else V(e);
  }
}

```

```

P(e);
if (nr > 0 or nw > 0)
  { dw = dw+1; V(e); P(w); }
nw = nw+1;
V(e);

```

```

P(e);
nw = nw-1;
if (dr > 0) { dr = dr-1; V(r); }
elseif (dw > 0) { dw = dw-1; V(w); }
else V(e);
}

```

Fig. 4.13 [Andr00]: readers / writers solution using passing the baton (with SIGNAL code)

next reader

1st reader

1st writer

next writer

Still readers first
 Unnecessary parts of SIGNAL code is removed
 Modify to give writers priority?

Resource Management

- Problem

- Many types of resources
- N units of given resource
- Request allocation: K units
 - Wait suspended until resource available

- Solution

- Semaphore mutex (init 1)
- Semaphore Xavail
 - init N – wait for available resource
 - init 0 - wait for permission to continue

use printer
use webcam
access database
access CS
allocate memory
allocate buffer
use comm port
get user focus
etc. etc.

Simple Bad Solution

```
sem Xmutex = 1, Xavail = N
```

```
Xres_request () # one unit at a time
```

```
  P(Xmutex)
```

```
  P(Xavail) # ok if always
```

```
             # allocate just 1 unit
```

```
  take 1 unit # not simple,
```

```
             # may take long time?
```

```
  V(Xmutex);
```

```
Xres_release ()
```

```
  P(Xmutex)
```

```
  return 1 unit
```

```
  V(Xavail);
```

```
  V(Xmutex);
```

- What is wrong?
 - everything
- Mutex?
- Deadlock?
- Unnecessary delays?
 - Each P() may result in (long) delay?
 - Hold mutex while waiting for resource
 - Very, very bad
 - Others can not get mutex to release resources...

Another Not So Good Solution

sem Xmutex = 1, Xavail = N

```
Xres_request ()  # one unit at a time
  P(Xavail)      # ok if always
                 # allocate just 1 unit
  P(Xmutex)
  take 1 unit    # not simple,
                 # may take long time?
  V(Xmutex);

Xres_release ()
  P(Xmutex)
  return 1 unit
  V(Xmutex);
  V(Xavail);
```

- What is wrong?
 - Works only for resources allocated and freed one unit at a time
- Mutex?
 - Mutex of control data?
 - Mutex of resource allocation data structures?

Resource Management with Baton Passing Split Semaphore

sem Xmutex = 1, Xavail = 0 (not N) ; split semaphore
; (short wait) (long wait)

Xres_request (K) – request K units of given resource

P(Xmutex)

if “not enough free units” { V(Xmutex); P(Xavail); }

take K units ; assume short time

if “requests pending and enough free units” { V(Xavail); }

else V(Xmutex);

Xres_release (K)

P(Xmutex)

return K units

if “requests pending and enough free units” { V(Xavail); }

else V(Xmutex);

CS { { }

CS { { }

baton passing

baton passing

Problems with Resource Management

- Need strong semaphores
- Strong semaphores are FIFO
 - What if 1st in line want 6 units, 2nd wants 3 units, and there are 4 units left?
 - What about priorities?
 - Each priority class has its own semaphore
 - Baton passing within each priority class?
 - How to release just some specific process?
 - Strong semaphore releases 1st in line
 - Answer: private semaphores

Private Semaphore

- Semaphore, to which only one process can ever make a P-operation
 - Initialized to 0, belongs to that process
- Usually part of PCB (process control block) for the process
 - Can create own semaphore arrays for this purpose
- Process makes demands, and then waits in private semaphore for turn
- Most often just one process at a time
 - Usually P(mutex) does not lead to process switches
- Usually still need to wait in private semaphore

Process User

P(mutex)

set up resource demands ----->

V(mutex)

P(me.PrivSem)

Process Server

P(mutex)

locate next process Q to release

V(Q.PrivSem)

V(mutex)

Shortest Job Next (Private Semaphore Use Example)

- Common resource allocation method
 - Here: *time = amount of resource requested*
 - Here: just select next job (with shortest time)
 - Here: just one job (at most) holding the resource at a time
- Use private semaphores

- ```
request(time,id): # requested time, user id
CS {
 P(e);
 if (!free) DELAY(); # wait for your turn
 free = false; # got it!
 V(e); # not SIGNAL(), only 1 at a time
```

- ```
release():      ??
CS {
  P(e);
  free = true;
  SIGNAL();     # who gets the next one?
               # pass baton, or release mutex
```

- DELAY:
 - Place delayed process in queue PAIRS (ordered in ascending requested resource amount order) in correct place
 - $V(e)$ – release mutex
 - Wait for your turn in private semaphore $P(b[ID])$
 - Each process has private semaphore, where only that process waits (initial value 0)
 - PAIRS queue determines order, one always wakes up the process at the head of the queue
 - Priority: smallest resource request first
- SIGNAL (in Release)
 - If someone waiting, take first one (time, ID), and wake up that process: $V(b[ID])$;
 - o/w $V(e)$

PAIRS:	P2	P15	P3	P1	ID
	3	6	17	64	time

Queue can be ordered according to requested cpu-time
 (requested cpu-time is the resource in this example)



Private semaphore b[ID] for each process ID: 0 ..n-1

Process release is dependent on its location in PAIRS.
 When resource becomes free, the 1st process in line may advance.

```

bool free = true;
sem e = 1, b[n] = ([n] 0); # for entry and delay
typedef Pairs = set of (int, int);
Pairs pairs = ∅;
## SJN: pairs is an ordered set ∧ free ⇒ (pairs == ∅)

```

```

request(time, id):
  P(e);
  if (!free) {
    insert (time, id) in pairs;
    V(e);          # release entry lock
    P(b[id]);     # wait to be awakened
  }
  free = false;
  V(e);          # optimized since free is false here

```

```

release():
  P(e);
  free = true;
  if (P != ∅) {
    remove first pair (time, id) from pairs;
    V(b[id]); # pass baton to process id
  }
  else V(e);

```

Andr00 Fig. 4.14
Shortest job next
(cpu scheduling
policy)
allocation using
semaphores.

Semaphore Feature Summary

- Many implementations and semantics
 - Be careful to use
 - E.g., is the (process) scheduler called after each V()?
 - Which one continues with processor, the process executing V() or the process just woken up?
 - Busy wait vs. suspend state?
- Hand coded synchronization solutions
 - Can solve almost any synchronization problem
 - Baton passing is useful and tricky
 - Explicit handover of some resource
 - Be careful to use
 - Do not leave mutex'es open
 - Do not suspend inside mutex
 - Avoid deadlocks
 - Do (multiple) P's and V's in correct order