Information-Theoretic Modeling

Lecture 3: Mathematical Preliminaries

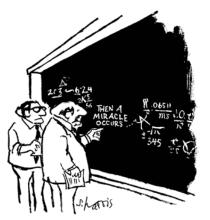
Teemu Roos

Department of Computer Science, University of Helsinki

Fall 2009



Lecture 3: Mathematical Preliminaries



"I think you should be more explicit here in step two."

- Calculus
 - Limits and Convergence
 - Convexity





- Calculus
 - Limits and Convergence
 - Convexity
- 2 Probability
 - Probability Space and Random Variables
 - Joint and Conditional Distributions
 - Expectation
 - Law of Large Numbers





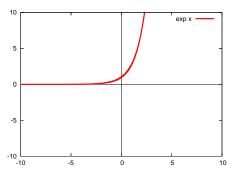
- Calculus
 - Limits and Convergence
 - Convexity
- 2 Probability
 - Probability Space and Random Variables
 - Joint and Conditional Distributions
 - Expectation
 - Law of Large Numbers
- Inequalities
 - Jensen's Inequality
 - Gibbs's Inequality





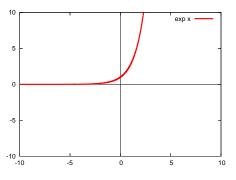
- Calculus
 - Limits and Convergence
 - Convexity
- 2 Probability
 - Probability Space and Random Variables
 - Joint and Conditional Distributions
 - Expectation
 - Law of Large Numbers
- Inequalities
 - Jensen's Inequality
 - Gibbs's Inequality

Exponent Function



Exponent function exp : $\mathbb{R} \to \mathbb{R}^+$, exp $k = e^k = \overbrace{e \times e \times \ldots \times e}$: multiplicative growth (nuclear reaction, "interest on interest", …)

Exponent Function

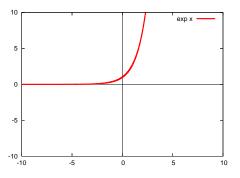


Exponent function exp : $\mathbb{R} \to \mathbb{R}^+$, exp $k = e^k = \overbrace{e \times e \times \ldots \times e}$: multiplicative growth (nuclear reaction, "interest on interest", …)

$$\exp x \cdot \exp y = \exp(x + y)$$



Exponent Function

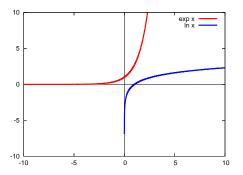


Exponent function exp : $\mathbb{R} \to \mathbb{R}^+$, exp $k = e^k = \overbrace{e \times e \times \ldots \times e}$: multiplicative growth (nuclear reaction, "interest on interest", …)

$$\exp x \cdot \exp y = \exp(x+y)$$

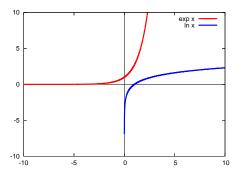
Derivative
$$\frac{d \exp x}{dx} = \exp x$$
.

Examples: Logarithm



Natural logarithm In : $\mathbb{R}^+ \to \mathbb{R}$, $\ln \exp x = x$: time to grow to x, number of digits (\log_{10}).

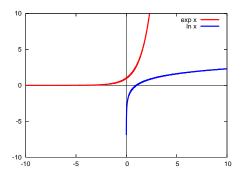
Examples: Logarithm



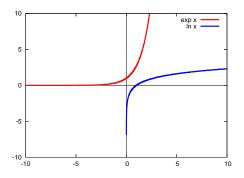
Natural logarithm In : $\mathbb{R}^+ \to \mathbb{R}$, $\ln \exp x = x$: time to grow to x, number of digits (\log_{10}).

General (base a) logarithm,
$$\log_a a^x = x$$
:

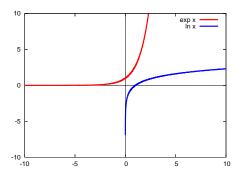
$$\log_a x = \frac{1}{\ln a} \ln x$$



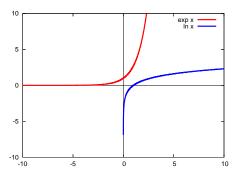
$$\ln xy = \ln x + \ln y$$



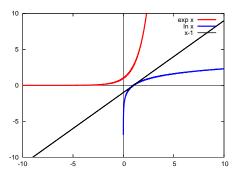
$$\ln xy = \ln x + \ln y \quad \ln x^r = r \ln x$$



$$\ln xy = \ln x + \ln y \quad \ln x^r = r \ln x \quad \ln \frac{1}{x} = -\ln x$$



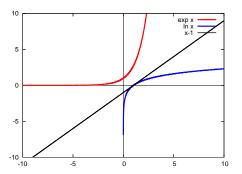
$$\ln xy = \ln x + \ln y \quad \ln x^r = r \ln x \quad \ln \frac{1}{x} = -\ln x \quad \ln \frac{x}{y} = \ln x - \ln y$$



$$\ln xy = \ln x + \ln y \qquad \ln x^r = r \ln x \qquad \ln \frac{1}{x} = -\ln x \qquad \ln \frac{x}{y} = \ln x - \ln y$$

 $\ln x \le x - 1$ with equality if and only if x = 1 (NB: doesn't work with $\log_2 x$ if $a \ne e$)





$$\ln xy = \ln x + \ln y$$

$$\ln x^r = r \ln x$$

$$\ln \frac{1}{x} = -\ln x$$

$$\ln xy = \ln x + \ln y \quad \ln x^r = r \ln x \quad \ln \frac{1}{x} = -\ln x \quad \ln \frac{x}{y} = \ln x - \ln y$$

$$\ln x \le x - 1$$
 with equality if and only if $x = 1$ (NB: doesn't work with $\log_2 x$ if $a \ne e$)

$$\frac{d\ln x}{dx} = \frac{1}{x}$$

Limits and Convergence

• A sequence of values $(x_i:i\in\mathbb{N})$ converges to limit L, $\lim_{i\to\infty}x_i=L$, iff for any $\epsilon>0$ there exists a number $N\in\mathbb{N}$ such that

$$|x_i - L| < \epsilon$$
 for all $i \ge N$.

Limits and Convergence

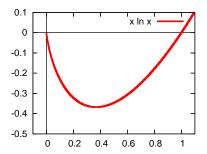
• A sequence of values $(x_i:i\in\mathbb{N})$ converges to limit L, $\lim_{i\to\infty}x_i=L$, iff for any $\epsilon>0$ there exists a number $N\in\mathbb{N}$ such that

$$|x_i - L| < \epsilon$$
 for all $i \ge N$.

• f(x) has a limit L as x approaches c, $\lim_{x\to c} f(x) = L$, (from above c^+ /below c^-) iff for any $\epsilon > 0$ there exists a number $\delta > 0$ such that

$$|f(x) - L| < \epsilon$$
 for all $\begin{cases} c < x < c + \delta & \text{`above'} \\ c - \delta < x < c & \text{`below'} \\ 0 < |x - c| < \delta & - \end{cases}$

Example: Logarithm Again



Even though $x \ln x$ is undefined at x = 0, we have (by l'Hôpital's rule):

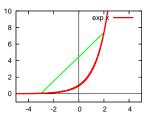
$$\lim_{x \to 0^+} x \ln x = 0 .$$



Convexity

Function $f: \mathcal{X} \to \mathbb{R}$ is said to be **convex** iff for any $x, y \in \mathcal{X}$ and any $t \in [0, 1]$, we have

$$f(tx + (1-t)y) \le tf(x) + (1-t)f(y)$$
.



Convexity

Function $f: \mathcal{X} \to \mathbb{R}$ is said to be **convex** iff for any $x, y \in \mathcal{X}$ and any $t \in [0, 1]$, we have

$$f(tx + (1-t)y) \le tf(x) + (1-t)f(y)$$
.

Function f is **strictly convex** iff the above inequality holds strictly ('<' instead of ' \leq ').

Convexity

Function $f: \mathcal{X} \to \mathbb{R}$ is said to be **convex** iff for any $x, y \in \mathcal{X}$ and any $t \in [0, 1]$, we have

$$f(tx + (1-t)y) \le tf(x) + (1-t)f(y)$$
.

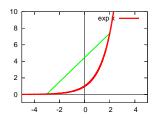
Function f is **strictly convex** iff the above inequality holds strictly ('<' instead of ' \leq ').

Function f is (strictly) **concave** iff the above holds for -f.



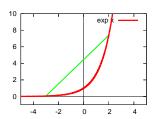
Theorem

Theorem



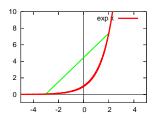
Example:
$$f'(x) = \frac{d \exp x}{dx} = \exp x$$

Theorem



Example:
$$f'(x) = \frac{d \exp x}{dx} = \exp x \implies f''(x) = \exp x > 0.$$

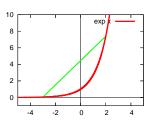
Theorem



Example:
$$f'(x) = \frac{d \exp x}{dx} = \exp x \implies f''(x) = \exp x > 0$$
. Hence exp is strictly convex.

Theorem

If function f has a second derivative f'', and f'' is non-negative (≥ 0) for all x, then f is convex. If f'' is positive (> 0) for all x, then f is *strictly* convex.



e^x is conve^x!

Example:
$$f'(x) = \frac{d \exp x}{dx} = \exp x \implies f''(x) = \exp x > 0$$
. Hence exp is strictly convex.

Probability Space and Random Variables Joint and Conditional Distributions Expectation Law of Large Numbers

Probability



A.N. Kolmogorov, 1903-1987



- Calculus
 - Limits and Convergence
 - Convexity
- 2 Probability
 - Probability Space and Random Variables
 - Joint and Conditional Distributions
 - Expectation
 - Law of Large Numbers
- Inequalities
 - Jensen's Inequality
 - Gibbs's Inequality

Probability Space and Random Variables Joint and Conditional Distributions Expectation Law of Large Numbers

Probability Space

A probability space (Ω, \mathcal{F}, P) is defined by

A probability space (Ω, \mathcal{F}, P) is defined by

ullet the **sample space** Ω whose elements are called outcomes ω ,

A probability space (Ω, \mathcal{F}, P) is defined by

- ullet the **sample space** Ω whose elements are called outcomes ω ,
- a sigma algebra \mathcal{F} of subsets of Ω , whose elements are called **events** E, and

A probability space (Ω, \mathcal{F}, P) is defined by

- ullet the **sample space** Ω whose elements are called outcomes ω ,
- a sigma algebra \mathcal{F} of subsets of Ω , whose elements are called **events** E, and
- a measure P which determines the **probabilities of events**, $P: \mathcal{F} \rightarrow [0,1].$

A probability space (Ω, \mathcal{F}, P) is defined by

- ullet the **sample space** Ω whose elements are called outcomes ω ,
- a sigma algebra \mathcal{F} of subsets of Ω , whose elements are called **events** E, and
- a measure P which determines the **probabilities of events**, $P: \mathcal{F} \rightarrow [0,1].$

Measure P has to satisfy the **probability axioms**: $P(E) \ge 0$ for all $E \in \mathcal{F}$, $P(\Omega) = 1$, and $P(E_1 \cup E_2 \cup \ldots) = \sum_i P(E_i)$ if (E_i) is a countable sequence of *disjoint* events.

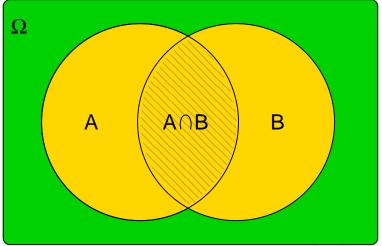
A probability space (Ω, \mathcal{F}, P) is defined by

- ullet the **sample space** Ω whose elements are called outcomes ω ,
- a sigma algebra \mathcal{F} of subsets of Ω , whose elements are called **events** E, and
- a measure P which determines the **probabilities of events**, $P: \mathcal{F} \rightarrow [0,1].$

Measure P has to satisfy the **probability axioms**: $P(E) \ge 0$ for all $E \in \mathcal{F}$, $P(\Omega) = 1$, and $P(E_1 \cup E_2 \cup \ldots) = \sum_i P(E_i)$ if (E_i) is a countable sequence of *disjoint* events.

These axioms imply the usual rules of **probability calculus**, e.g., $P(A \cup B) = P(A) + P(B) - P(A \cap B)$, $P(\Omega \setminus E) = 1 - P(E)$, etc.

Venn Diagrams



• The **conditional probability** of event *B* given that event *A* occurs is defined as

$$P(B \mid A) = \frac{P(A \cap B)}{P(A)}$$
 for A such that $P(A) > 0$.

• The **conditional probability** of event *B* given that event *A* occurs is defined as

$$P(B \mid A) = \frac{P(A \cap B)}{P(A)}$$
 for A such that $P(A) > 0$.

$$P(A \cap B) = P(A) \times P(B \mid A) = P(B) \times P(A \mid B) .$$

The conditional probability of event B given that event A occurs is defined as

$$P(B \mid A) = \frac{P(A \cap B)}{P(A)}$$
 for A such that $P(A) > 0$.

- $P(A \cap B) = P(A) \times P(B \mid A) = P(B) \times P(A \mid B) .$
- **3** Bayes' rule: $P(B \mid A) = \frac{P(A \mid B) \times P(B)}{P(A)}$.

The conditional probability of event B given that event A occurs is defined as

$$P(B \mid A) = \frac{P(A \cap B)}{P(A)}$$
 for A such that $P(A) > 0$.

- ② $P(A \cap B) = P(A) \times P(B \mid A) = P(B) \times P(A \mid B)$.
- **3** Bayes' rule: $P(B \mid A) = \frac{P(A \mid B) \times P(B)}{P(A)}$.
- Chain rule:

$$P(\bigcap_{i=1}^{N} E_{i}) = \prod_{i=1}^{N} P(E_{i} \mid \bigcap_{j=1}^{i-1} E_{j})$$

$$= P(E_{1}) \times P(E_{2} \mid E_{1}) \times P(E_{3} \mid E_{1} \cap E_{2}) \times \dots$$

$$\times P(E_{N} \mid E_{1} \cap \dots \cap E_{N-1}).$$

Technically, a random variable is a (measurable) function $X:\Omega\to\mathbb{R}$ from the sample space to the reals.

Technically, a random variable is a (measurable) function $X:\Omega\to\mathbb{R}$ from the sample space to the reals.

The probability measure P on Ω determines the distribution of X:

$$P_X(A) = \Pr[X \in A] = P(\{\omega : X(\omega) \in A\})$$
,

where $A \subseteq \mathbb{R}$.

Technically, a random variable is a (measurable) function $X:\Omega\to\mathbb{R}$ from the sample space to the reals.

The probability measure P on Ω determines the distribution of X:

$$P_X(A) = \Pr[X \in A] = P(\{\omega : X(\omega) \in A\})$$
,

where $A \subseteq \mathbb{R}$.

It is often more natural to relabel the outcomes and denote them, for instance, by letters, A, B, C, ..., or words red, black, ...

Technically, a random variable is a (measurable) function $X:\Omega\to\mathbb{R}$ from the sample space to the reals.

The probability measure P on Ω determines the distribution of X:

$$P_X(A) = \Pr[X \in A] = P(\{\omega : X(\omega) \in A\})$$
,

where $A \subseteq \mathbb{R}$.

It is often more natural to relabel the outcomes and denote them, for instance, by letters, A, B, C, ..., or words red, black, ...

In practice, we often forget about the underlying probability space Ω , and just speak of random variable X and its distribution P_X .

The distribution of a random variable can always be represented as a cumulative distribution function (cdf) $F_X(x) = \Pr[X \le x]$.

The distribution of a random variable can always be represented as a cumulative distribution function (cdf) $F_X(x) = \Pr[X \le x]$.

In addition:

• A **discrete** random variable X with countable alphabet \mathcal{X} has a *probability mass function* (pmf) p_X such that $\Pr[X = x] = p_X(x)$.

The distribution of a random variable can always be represented as a cumulative distribution function (cdf) $F_X(x) = \Pr[X \le x]$.

In addition:

- A discrete random variable X with countable alphabet \mathcal{X} has a probability mass function (pmf) p_X such that $\Pr[X = x] = p_X(x)$.
- A **continuous** random variable Y has a *probability density* function (pdf) f_Y such that $\Pr[Y \in A] = \int_A f_Y(x) dy$.

The distribution of a random variable can always be represented as a cumulative distribution function (cdf) $F_X(x) = \Pr[X \le x]$.

In addition:

- A discrete random variable X with countable alphabet \mathcal{X} has a probability mass function (pmf) p_X such that $\Pr[X = x] = p_X(x)$.
- A continuous random variable Y has a probability density function (pdf) f_Y such that $\Pr[Y \in A] = \int_A f_Y(x) dy$.

There are also *mixed* random variables that are neither discrete nor continuous. They don't have a pmf or pdf, but they do have a cdf.

The distribution of a random variable can always be represented as a cumulative distribution function (cdf) $F_X(x) = \Pr[X \le x]$.

In addition:

- A discrete random variable X with countable alphabet \mathcal{X} has a probability mass function (pmf) p_X such that $\Pr[X = x] = p_X(x)$.
- A continuous random variable Y has a probability density function (pdf) f_Y such that $\Pr[Y \in A] = \int_A f_Y(x) dy$.

There are also *mixed* random variables that are neither discrete nor continuous. They don't have a pmf or pdf, but they do have a cdf.

We often omit the subscripts X, Y, \ldots and write p(x), f(y), etc.



Since random variables are functions, we can define more random variables as functions of random variables: if f is a function, and X and Y are r.v.'s, then $f(X): \Omega \to \mathbb{R}$ is a r.v., X+Y is a r.v., etc.

Since random variables are functions, we can define more random variables as functions of random variables: if f is a function, and X and Y are r.v.'s, then $f(X): \Omega \to \mathbb{R}$ is a r.v., X+Y is a r.v., etc.

Example: Let r.v. X be the outcome of a die.



• The pmf of X is given by $p_X(x) = 1/6$ for all $x \in \{1, 2, 3, 4, 5, 6\}$.

Since random variables are functions, we can define more random variables as functions of random variables: if f is a function, and X and Y are r.v.'s, then $f(X): \Omega \to \mathbb{R}$ is a r.v., X+Y is a r.v., etc.

Example: Let r.v. X be the outcome of a die.



- The pmf of X is given by $p_X(x) = 1/6$ for all $x \in \{1, 2, 3, 4, 5, 6\}$.
- The pmf of r.v. X^2 is given by $p_{X^2}(x) = 1/6$ for all $x \in \{1, 4, 9, 16, 25, 36\}$.

Since random variables are functions, we can define more random variables as functions of random variables: if f is a function, and X and Y are r.v.'s, then $f(X): \Omega \to \mathbb{R}$ is a r.v., X+Y is a r.v., etc.

Example: Let r.v. X be the outcome of a die.



- The pmf of X is given by $p_X(x) = 1/6$ for all $x \in \{1, 2, 3, 4, 5, 6\}$.
- The pmf of r.v. X^2 is given by $p_{X^2}(x) = 1/6$ for all $x \in \{1, 4, 9, 16, 25, 36\}$.

In particular, a pmf p_X is a function, and hence, $p_X(X)$ is also a random variable. Further, $p_X^2(X)$, $\ln p_X(X)$, etc. are random variables.

The probabilistic behavior of two or more random variables is described by multivariate distributions.

The **joint distribution** of r.v.'s X and Y is

$$P_{X,Y}(A,B) = \Pr[X \in A \land Y \in B]$$

= $P(\{\omega : X(\omega) \in A, Y(\omega) \in B\})$.

The probabilistic behavior of two or more random variables is described by multivariate distributions.

The **joint distribution** of r.v.'s X and Y is

$$P_{X,Y}(A,B) = \Pr[X \in A \land Y \in B]$$

= $P(\{\omega : X(\omega) \in A, Y(\omega) \in B\})$.

For each multivariate distribution $P_{X,Y}$, there are unique **marginal** distributions P_X and P_Y such that

$$P_X(A) = P_{X,Y}(A,\mathbb{R}), \qquad P_Y(B) = P_{X,Y}(\mathbb{R},B)$$
,

The probabilistic behavior of two or more random variables is described by multivariate distributions.

The **joint distribution** of r.v.'s X and Y is

$$P_{X,Y}(A,B) = \Pr[X \in A \land Y \in B]$$

= $P(\{\omega : X(\omega) \in A, Y(\omega) \in B\})$.

For each multivariate distribution $P_{X,Y}$, there are unique **marginal** distributions P_X and P_Y such that

$$P_X(A) = P_{X,Y}(A,\mathbb{R}), \qquad P_Y(B) = P_{X,Y}(\mathbb{R},B)$$
,

pmf:
$$p_Y(y) = \sum_{x \in \mathcal{X}} p_{X,Y}(x,y)$$
 pdf: $f_Y(y) = \int_{\mathbb{R}} f_{X,Y}(x,y) dx$.

The **conditional distribution** is defined similar to *conditional probability*:

$$P_{Y|X}(B \mid A) = \frac{P_{X,Y}(A,B)}{P_X(A)}$$
 for A such that $P_X(A) > 0$.

The **conditional distribution** is defined similar to *conditional probability*:

$$P_{Y|X}(B \mid A) = \frac{P_{X,Y}(A,B)}{P_X(A)}$$
 for A such that $P_X(A) > 0$.

For discrete/continuous variables we have:

• discrete r.v.'s:

$$p_{Y|X}(y \mid x) = \frac{p_{X,Y}(x,y)}{p_{X}(x)}$$
, $p_{X}(x) > 0$,

The **conditional distribution** is defined similar to *conditional* probability:

$$P_{Y|X}(B \mid A) = \frac{P_{X,Y}(A,B)}{P_X(A)}$$
 for A such that $P_X(A) > 0$.

For discrete/continuous variables we have:

• discrete r.v.'s:

$$p_{Y|X}(y \mid x) = \frac{p_{X,Y}(x,y)}{p_X(x)}, \quad p_X(x) > 0,$$

• continuous r.v.'s:

$$f_{Y|X}(y \mid x) = \frac{f_{X,Y}(x,y)}{f_{X}(x)}$$
, $f_{X}(x) > 0$.



Independence

Variable X is said to be **independent** of variable Y ($X \perp \!\!\!\perp Y$) iff

$$P_{X,Y}(A,B) = P_X(A) \times P_Y(B)$$
 for all $A,B \subseteq \mathbb{R}$.

Independence

Variable X is said to be **independent** of variable Y ($X \perp \!\!\!\perp Y$) iff

$$P_{X,Y}(A,B) = P_X(A) \times P_Y(B)$$
 for all $A,B \subseteq \mathbb{R}$.

This is equivalent to

$$P_{X|Y}(A \mid B) = P_X(A)$$
 for all B such that $P(B) > 0$,

Independence

Variable X is said to be **independent** of variable Y ($X \perp \!\!\! \perp Y$) iff

$$P_{X,Y}(A,B) = P_X(A) \times P_Y(B)$$
 for all $A,B \subseteq \mathbb{R}$.

This is equivalent to

$$P_{X|Y}(A \mid B) = P_X(A)$$
 for all B such that $P(B) > 0$,

and

$$P_{Y|X}(B \mid A) = P_Y(B)$$
 for all A such that $P(A) > 0$.

In words, knowledge about one variable tells nothing about the other. Note that independence is symmetric, $X \perp\!\!\!\perp Y \Leftrightarrow Y \perp\!\!\!\perp X$.



The **expectation** (or expected value, or mean) of a discrete random variable is given by

$$E[X] = \sum_{x \in \mathcal{X}} p(x) x .$$

The **expectation** (or expected value, or mean) of a discrete random variable is given by

$$E[X] = \sum_{x \in \mathcal{X}} p(x) x .$$

The expectation of a continuous random variable is given by

$$E[X] = \int_{\mathcal{X}} f(x) \, x \, dx .$$

The **expectation** (or expected value, or mean) of a discrete random variable is given by

$$E[X] = \sum_{x \in \mathcal{X}} p(x) x .$$

The expectation of a continuous random variable is given by

$$E[X] = \int_{\mathcal{X}} f(x) \, x \, dx .$$

In both cases, it is possible that $E[X] = \pm \infty$.

The **expectation** (or expected value, or mean) of a discrete random variable is given by

$$E[X] = \sum_{x \in \mathcal{X}} p(x) x .$$

The expectation of a continuous random variable is given by

$$E[X] = \int_{\mathcal{X}} f(x) \, x \, dx .$$

In both cases, it is possible that $E[X] = \pm \infty$.

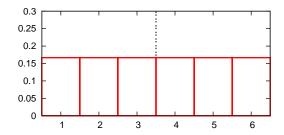
$$E[kX] = kE[X]$$
 $E[X + Y] = E[X] + E[Y]$

$$E[XY] = E[X]E[Y]$$
 if $X \perp \!\!\!\perp Y$



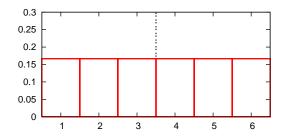


Let $X_1, X_2,...$ be a sequence of independent outcomes of a die, so that $p_{X_i}(x) = 1/6$ for all $i \in \mathbb{N}, x \in \{1, 2, 3, 4, 5, 6\}$.





Let $X_1, X_2,...$ be a sequence of independent outcomes of a die, so that $p_{X_i}(x) = 1/6$ for all $i \in \mathbb{N}, x \in \{1, 2, 3, 4, 5, 6\}$.



$$E[X_i] = \sum_{i=1}^{6} \frac{1}{6} x = \frac{21}{6} = 3.5$$
 for all $i \in \mathbb{N}$.

Let $S_n = \sum_{i=1}^n X_i$ be the sum of the first n outcomes.

Let $S_n = \sum_{i=1}^n X_i$ be the sum of the first n outcomes.

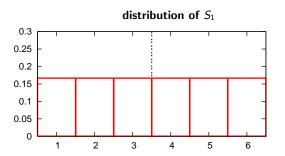
The distribution of S_n is given by

$$P_{S_n}(x) = \frac{\text{\# of ways to get sum } x \text{ with } n \text{ dice}}{6^n}$$

Let $S_n = \sum_{i=1}^n X_i$ be the sum of the first n outcomes.

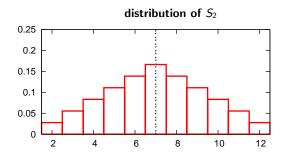
The distribution of S_n is given by

$$P_{S_n}(x) = \frac{\text{\# of ways to get sum } x \text{ with } n \text{ dice}}{6^n}$$



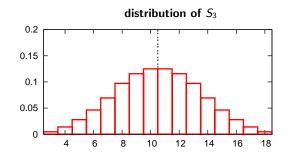
Let $S_n = \sum_{i=1}^n X_i$ be the sum of the first n outcomes.

$$P_{S_n}(x) = \frac{\text{\# of ways to get sum } x \text{ with } n \text{ dice}}{6^n}$$



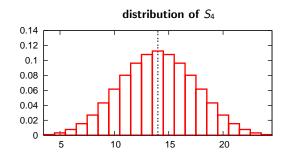
Let $S_n = \sum_{i=1}^n X_i$ be the sum of the first n outcomes.

$$P_{S_n}(x) = \frac{\text{\# of ways to get sum } x \text{ with } n \text{ dice}}{6^n}$$



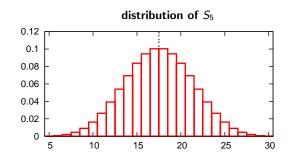
Let $S_n = \sum_{i=1}^n X_i$ be the sum of the first n outcomes.

$$P_{S_n}(x) = \frac{\text{\# of ways to get sum } x \text{ with } n \text{ dice}}{6^n}$$



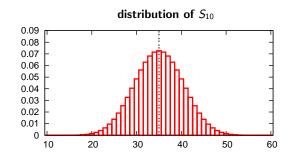
Let $S_n = \sum_{i=1}^n X_i$ be the sum of the first n outcomes.

$$P_{S_n}(x) = \frac{\text{\# of ways to get sum } x \text{ with } n \text{ dice}}{6^n}$$



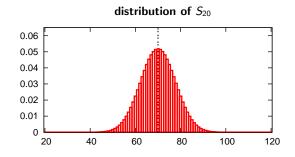
Let $S_n = \sum_{i=1}^n X_i$ be the sum of the first n outcomes.

$$P_{S_n}(x) = \frac{\text{\# of ways to get sum } x \text{ with } n \text{ dice}}{6^n}$$



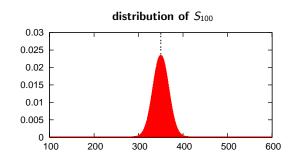
Let $S_n = \sum_{i=1}^n X_i$ be the sum of the first n outcomes.

$$P_{S_n}(x) = \frac{\text{\# of ways to get sum } x \text{ with } n \text{ dice}}{6^n}$$

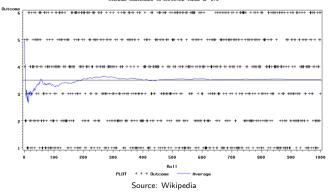


Let $S_n = \sum_{i=1}^n X_i$ be the sum of the first n outcomes.

$$P_{S_n}(x) = \frac{\text{\# of ways to get sum } x \text{ with } n \text{ dice}}{6^n}$$



LAW OF LARGE NUMBERS IN AVERAGE OF DIE ROLLS OVERAGE CONVERGES TO EXPECTED VALUE OF 3.5



Weak Law of Large Numbers

For a sequence of independent and identically distributed (i.i.d.) random variables with finite mean μ , the average $\frac{1}{n}S_n$ converges in probability to μ :

$$\lim_{n\to\infty} \Pr\left[\left|\frac{S_n}{n} - \mu\right| < \epsilon\right] = 1 \quad \text{for all } \epsilon > 0.$$

We will use the LLN to prove a result known as the Asymptotic Equipartition Property (AEP), which is a central result in information theory (see next lecture).

- Calculus
 - Limits and Convergence
 - Convexity
- 2 Probability
 - Probability Space and Random Variables
 - Joint and Conditional Distributions
 - Expectation
 - Law of Large Numbers
- Inequalities
 - Jensen's Inequality
 - Gibbs's Inequality

Jensen's inequality



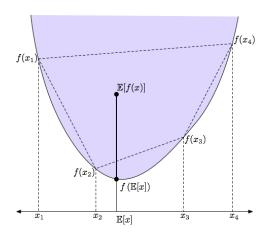
J.L.W.V. Jensen, 1859-1925

Jensen's inequality

If f is a convex function and X is a random variable, then

$$E[f(X)] \geq f(E[X])$$
.

Moreover, if f is strictly convex, the inequality holds as an equality if and only if X = E[X] with probability 1.



Source: Inductio Ex Machina, mark.reid.name/iem/

Jensen's inequality

If f is a convex function and X is a random variable, then

$$E[f(X)] \geq f(E[X])$$
.

Moreover, if f is strictly convex, the inequality holds as an equality if and only if X = E[X] with probability 1.

Jensen's inequality

If f is a convex function and X is a random variable, then

$$E[f(X)] \geq f(E[X])$$
.

Moreover, if f is strictly convex, the inequality holds as an equality if and only if X = E[X] with probability 1.

We give a proof for the first part of the theorem in the special case where X has a finite domain.

Jensen's inequality

If f is a convex function and X is a random variable, then

$$E[f(X)] \ge f(E[X])$$
.

Moreover, if f is strictly convex, the inequality holds as an equality if and only if X = E[X] with probability 1.

We give a proof for the first part of the theorem in the special case where X has a finite domain.

For two mass points, we have $p(x_2) = 1 - p(x_1)$, and the claim holds by definition of convexity:

$$p(x_1) f(x_1) + p(x_2) f(x_2) \ge f(p(x_1) x_1 + p(x_2) x_2)$$
.



$$\sum_{i=1}^{N} p(x_{i}) f(x_{i}) = p(x_{N}) f(x_{N}) + (1 - p(x_{N})) \sum_{i=1}^{N-1} p'(x_{i}) f(x_{i})$$

$$\geq p(x_{N}) f(x_{N}) + (1 - p(x_{N})) f\left(\sum_{i=1}^{N-1} p'(x_{i}) x_{i}\right) (*)$$

$$\geq f\left(p(x_{N}) x_{N} + (1 - p(x_{N})) \sum_{i=1}^{N-1} p'(x_{i}) x_{i}\right) (convexity)$$

$$= f\left(\sum_{i=1}^{N} p(x_{i}) x_{i}\right) ,$$

where
$$p'(x_i) = \frac{p(x_i)}{1 - p(x_N)}$$
.



$$\sum_{i=1}^{N} p(x_{i}) f(x_{i}) = p(x_{N}) f(x_{N}) + (1 - p(x_{N})) \sum_{i=1}^{N-1} p'(x_{i}) f(x_{i})$$

$$\geq p(x_{N}) f(x_{N}) + (1 - p(x_{N})) f\left(\sum_{i=1}^{N-1} p'(x_{i}) x_{i}\right) (*)$$

$$\geq f\left(p(x_{N}) x_{N} + (1 - p(x_{N})) \sum_{i=1}^{N-1} p'(x_{i}) x_{i}\right) (convexity)$$

$$= f\left(\sum_{i=1}^{N} p(x_{i}) x_{i}\right) ,$$

where
$$p'(x_i) = \frac{p(x_i)}{1 - p(x_N)}$$
.



$$\sum_{i=1}^{N} p(x_{i}) f(x_{i}) = p(x_{N}) f(x_{N}) + (1 - p(x_{N})) \sum_{i=1}^{N-1} p'(x_{i}) f(x_{i})$$

$$\geq p(x_{N}) f(x_{N}) + (1 - p(x_{N})) f\left(\sum_{i=1}^{N-1} p'(x_{i}) x_{i}\right) (*)$$

$$\geq f\left(p(x_{N}) x_{N} + (1 - p(x_{N})) \sum_{i=1}^{N-1} p'(x_{i}) x_{i}\right) (convexity)$$

$$= f\left(\sum_{i=1}^{N} p(x_{i}) x_{i}\right) ,$$

where
$$p'(x_i) = \frac{p(x_i)}{1 - p(x_N)}$$
.



$$\sum_{i=1}^{N} p(x_{i}) f(x_{i}) = p(x_{N}) f(x_{N}) + (1 - p(x_{N})) \sum_{i=1}^{N-1} p'(x_{i}) f(x_{i})$$

$$\geq p(x_{N}) f(x_{N}) + (1 - p(x_{N})) f\left(\sum_{i=1}^{N-1} p'(x_{i}) x_{i}\right) (*)$$

$$\geq f\left(p(x_{N}) x_{N} + (1 - p(x_{N})) \sum_{i=1}^{N-1} p'(x_{i}) x_{i}\right) (convexity)$$

$$= f\left(\sum_{i=1}^{N} p(x_{i}) x_{i}\right) ,$$

where
$$p'(x_i) = \frac{p(x_i)}{1 - p(x_N)}$$
.



$$\sum_{i=1}^{N} p(x_{i}) f(x_{i}) = p(x_{N}) f(x_{N}) + (1 - p(x_{N})) \sum_{i=1}^{N-1} p'(x_{i}) f(x_{i})$$

$$\geq p(x_{N}) f(x_{N}) + (1 - p(x_{N})) f\left(\sum_{i=1}^{N-1} p'(x_{i}) x_{i}\right) (*)$$

$$\geq f\left(p(x_{N}) x_{N} + (1 - p(x_{N})) \sum_{i=1}^{N-1} p'(x_{i}) x_{i}\right) (convexity)$$

$$= f\left(\sum_{i=1}^{N} p(x_{i}) x_{i}\right) ,$$

where
$$p'(x_i) = \frac{p(x_i)}{1 - p(x_N)}$$
.



Gibbs' inequality



W. Gibbs, 1839-1903



Gibbs' inequality

For any two discrete probability distributions p and q, we have

$$\sum_{x \in \mathcal{X}} p(x) \log_2 p(x) \ge \sum_{x \in \mathcal{X}} p(x) \log_2 q(x)$$

with equality if and only if p(x) = q(x) for all $x \in \mathcal{X}$.

Proof. Since $\log_2 x = \frac{1}{\ln 2} \ln x$, dividing both sides by $\ln 2$ changes \log_2 to \ln .

Gibbs' inequality

For any two discrete probability distributions p and q, we have

$$\sum_{x \in \mathcal{X}} p(x) \ln p(x) \ge \sum_{x \in \mathcal{X}} p(x) \ln q(x)$$

with equality if and only if p(x) = q(x) for all $x \in \mathcal{X}$.

Proof. Since $\log_2 x = \frac{1}{\ln 2} \ln x$, dividing both sides by $\ln 2$ changes \log_2 to \ln .

Gibbs' inequality

$$\sum_{x \in \mathcal{X}} p(x) \ln p(x) \ge \sum_{x \in \mathcal{X}} p(x) \ln q(x)$$

$$\sum_{x \in \mathcal{X}} p(x) \ln q(x) - \sum_{x \in \mathcal{X}} p(x) \ln p(x) = \sum_{x \in \mathcal{X}} p(x) \left(\ln q(x) - \ln p(x) \right)$$

$$= \sum_{x \in \mathcal{X}} p(x) \ln \frac{q(x)}{p(x)} \qquad \left[\ln x - \ln y = \ln \frac{x}{y} \right]$$

$$\leq \sum_{x \in \mathcal{X}} p(x) \left(\frac{q(x)}{p(x)} - 1 \right) \qquad \left[\ln x \leq x - 1 \right]$$

$$= \sum_{x \in \mathcal{X}} q(x) - \sum_{x \in \mathcal{X}} p(x) = 1 - 1 = 0 . \quad \Box$$

4日 > 4周 > 4目 > 4目 > 三

Gibbs' inequality

$$\sum_{x \in \mathcal{X}} p(x) \ln p(x) \ge \sum_{x \in \mathcal{X}} p(x) \ln q(x)$$

$$\sum_{x \in \mathcal{X}} p(x) \ln q(x) - \sum_{x \in \mathcal{X}} p(x) \ln p(x) = \sum_{x \in \mathcal{X}} p(x) \left(\ln q(x) - \ln p(x) \right)$$

$$= \sum_{x \in \mathcal{X}} p(x) \ln \frac{q(x)}{p(x)} \qquad \left[\ln x - \ln y = \ln \frac{x}{y} \right]$$

$$\leq \sum_{x \in \mathcal{X}} p(x) \left(\frac{q(x)}{p(x)} - 1 \right) \qquad \left[\ln x \leq x - 1 \right]$$

$$= \sum_{x \in \mathcal{X}} q(x) - \sum_{x \in \mathcal{X}} p(x) = 1 - 1 = 0 . \quad \Box$$

Gibbs' inequality

$$\sum_{x \in \mathcal{X}} p(x) \ln p(x) \ge \sum_{x \in \mathcal{X}} p(x) \ln q(x)$$

$$\sum_{x \in \mathcal{X}} p(x) \ln q(x) - \sum_{x \in \mathcal{X}} p(x) \ln p(x) = \sum_{x \in \mathcal{X}} p(x) \left(\ln q(x) - \ln p(x) \right)$$

$$= \sum_{x \in \mathcal{X}} p(x) \ln \frac{q(x)}{p(x)} \qquad \left[\ln x - \ln y = \ln \frac{x}{y} \right]$$

$$\leq \sum_{x \in \mathcal{X}} p(x) \left(\frac{q(x)}{p(x)} - 1 \right) \qquad \left[\ln x \leq x - 1 \right]$$

$$= \sum_{x \in \mathcal{X}} q(x) - \sum_{x \in \mathcal{X}} p(x) = 1 - 1 = 0 . \quad \Box$$

Gibbs' inequality

$$\sum_{x \in \mathcal{X}} p(x) \ln p(x) \ge \sum_{x \in \mathcal{X}} p(x) \ln q(x)$$

$$\sum_{x \in \mathcal{X}} p(x) \ln q(x) - \sum_{x \in \mathcal{X}} p(x) \ln p(x) = \sum_{x \in \mathcal{X}} p(x) \left(\ln q(x) - \ln p(x) \right)$$

$$= \sum_{x \in \mathcal{X}} p(x) \ln \frac{q(x)}{p(x)} \qquad \boxed{\ln x - \ln y = \ln \frac{x}{y}}$$

$$\leq \sum_{x \in \mathcal{X}} p(x) \left(\frac{q(x)}{p(x)} - 1 \right) \qquad \boxed{\ln x \leq x - 1}$$

$$= \sum_{x \in \mathcal{X}} q(x) - \sum_{x \in \mathcal{X}} p(x) = 1 - 1 = 0 . \quad \Box$$

4 D > 4 A > 4 B > 4 B > 4 B >

What's next...

For Friday's lecture about entropy and information, read Chapter 2 of Cover & Thomas (in course folder).

What's next...

For Friday's lecture about entropy and information, read Chapter 2 of Cover & Thomas (in course folder).

Next week:

noiseless source coding theorem,

What's next...

For Friday's lecture about entropy and information, read Chapter 2 of Cover & Thomas (in course folder).

Next week:

- noiseless source coding theorem,
- practical source coding (to be continued).