



fNML Criterion for Learning Bayesian Network Structures

Tomi Silander
Teemu Roos
Petri Kontkanen
Petri Myllymaki

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Hirtshals

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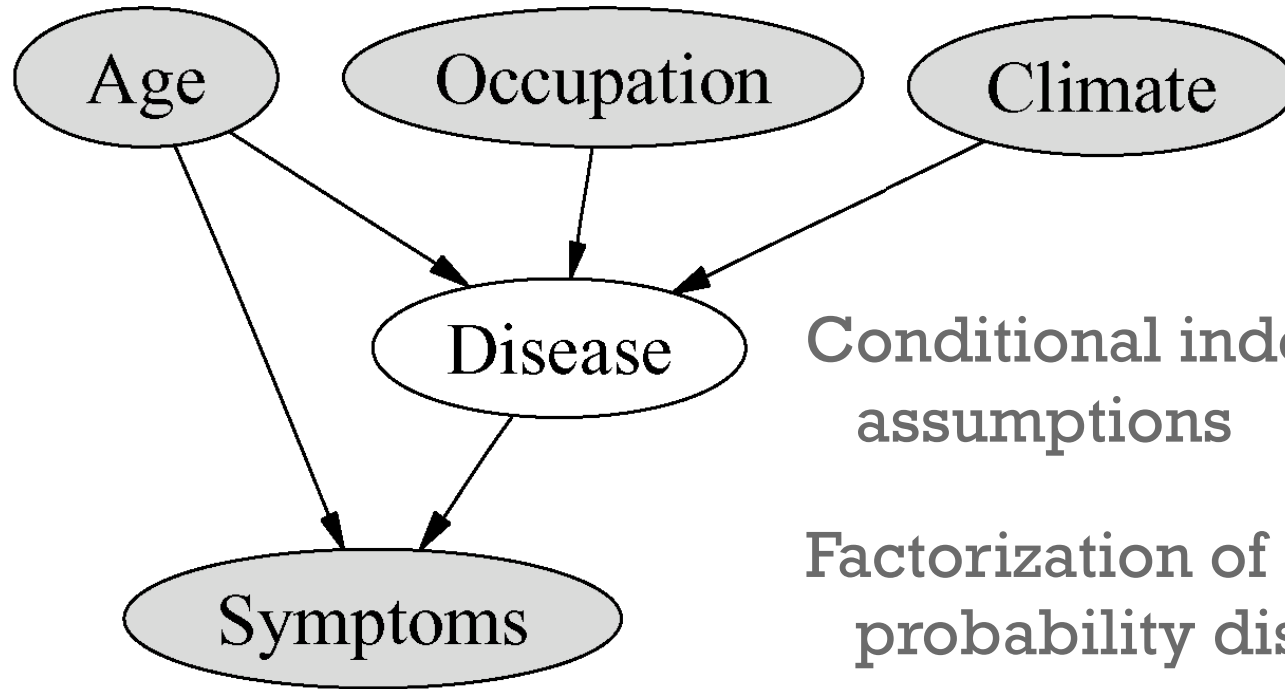
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Outline:

1. Bayesian Networks
- + 2. Model Selection Scores
3. New Stuff: fNML Score

+ Bayesian Networks




Conditional independence assumptions

Factorization of a joint probability distribution:

$$P(x | G) = \prod_{i=1}^m P(x_i | G_i).$$

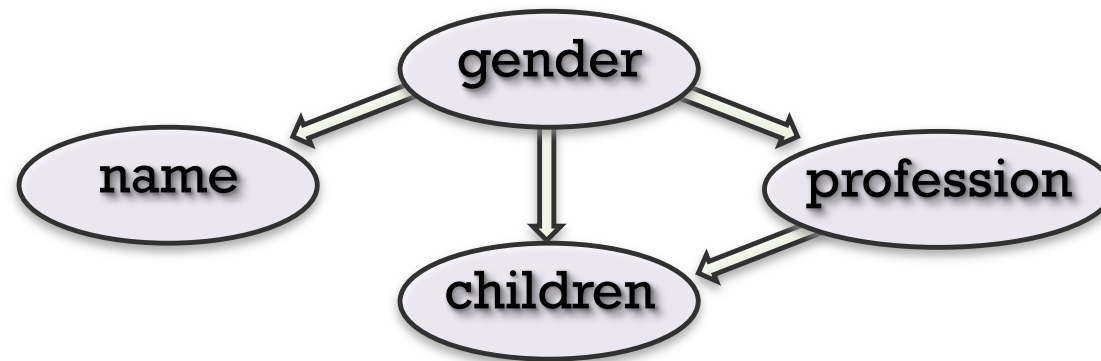
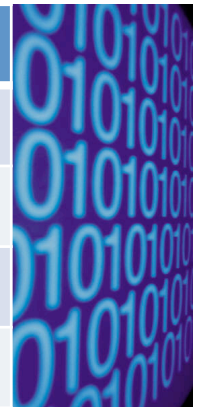
+ Data

NAME	GENDER	PROFESSION	CHILDREN
Teemu	male	researcher	2
Clark	male	reporter	0
Margrethe	female	queen	2
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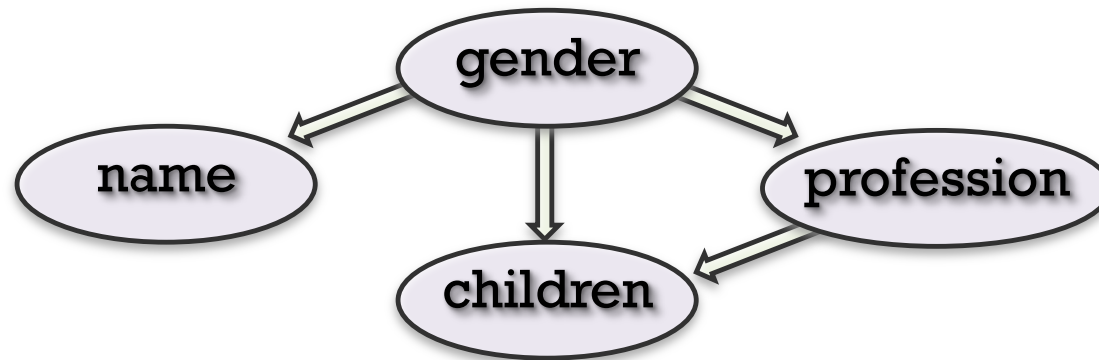
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+ Data

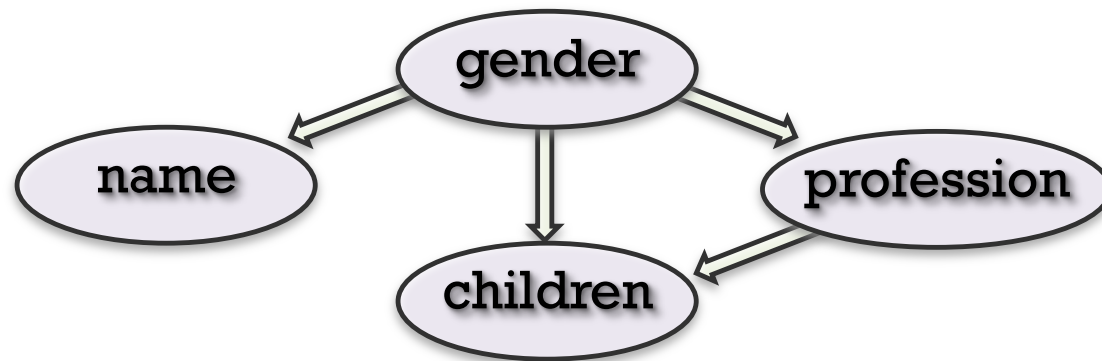
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D_i



Model Selection: + Scores

- Bayes (BDe)
- BIC & AIC
- MDL

+ Bayesian Score

The state-of-the-art model selection criterion:

Bayesian Dirichlet equivalent (BDe) score

Assumes **Dirichlet prior** on model parameters θ .

Evaluate **marginal likelihood** of data given model

$$P(D | G, \alpha) = \int P(D | G, \theta) P(\theta | G, \alpha) d\theta.$$

Depends on **hyper-parameter** α .

+ BIC & AIC

BIC: Asymptotic approximation of **marginal likelihood**:

$$BIC(G, D) = \log \hat{P}(D | G) - \frac{k}{2} \log n.$$

AIC: Asymptotic approximation of estimated **prediction error**:

$$AIC(G, D) = \log \hat{P}(D | G) - k.$$

+ MDL

Minimum Description Length (MDL) Principle:

Choose the model that yields the shortest description of the data together with the model.

Too simple model

data long, model short

"Just right"

data short, model short

Too complex model

data short, model long

+ Flavours of MDL

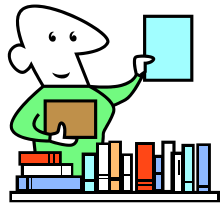


1. "Pedestrian"
Asymptotic two-part code-length same as BIC.

+ Flavours of MDL



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Asymptotic two-part code-length same as BIC.



2. "Sophisticated"
Bayesian marginal likelihood.

+ Flavours of MDL



1. "Pedestrian"
Asymptotic two-part code-length same as BIC.



2. "Sophisticated"
Bayesian marginal likelihood.



3. "Champions League"
Modern (minimax regret optimal) code
normalized maximum likelihood (NML)

Problem: NML computationally very hard.

+ Bayes vs. MDL (minimax regret)

The Bayesian decision principle is **minimization of expected loss**:

$$\min_A E_X[\text{loss}(A, X)]$$

MDL (especially NML) is based on **minimization of worst-case regret**:

$$\min_A \max_X \underbrace{[\text{loss}(A, X) - \min_{A'} \text{loss}(A', X)]}_{\text{"regret"}}$$

New stuff: + fNML Score

- fNML = "factorized NML"
- computation
- consistency

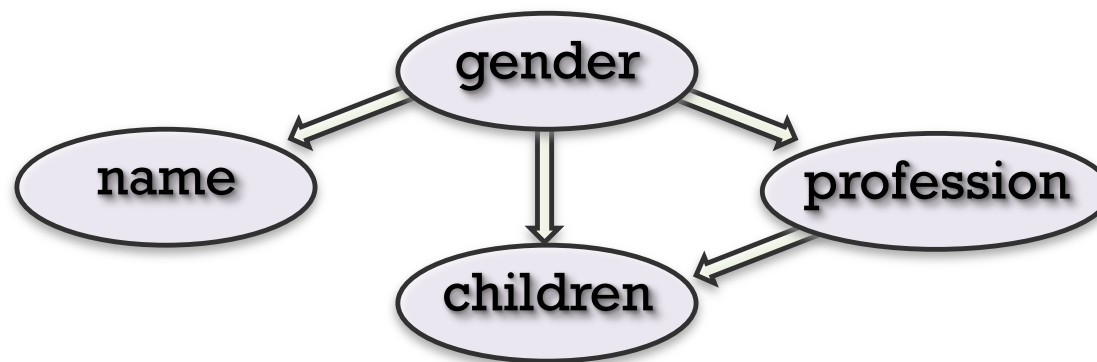
+ fNML Score

We propose a new MDL score, **factorized NML**, which is

1. **easy to compute**,
2. **decomposable** (allowing fast search),
3. **robust** (experimentally).

+ fNML vs. NML: what's new?

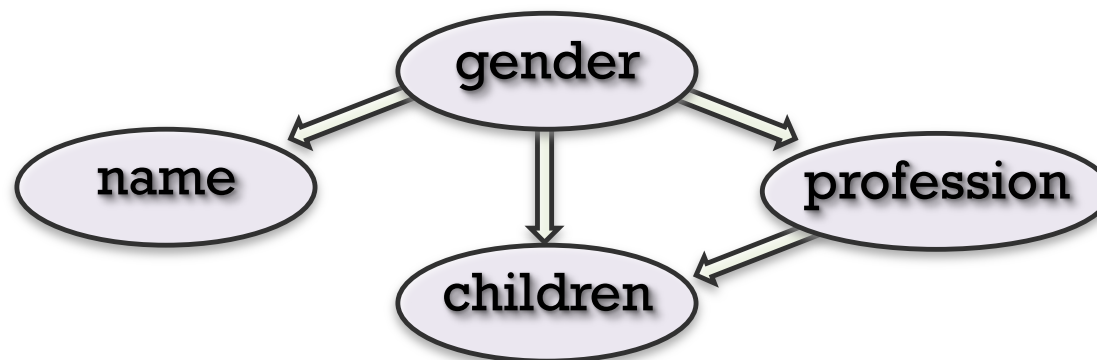
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+ fNML vs. NML: what's new?

NML: Minimax code applied to **whole data** as one block

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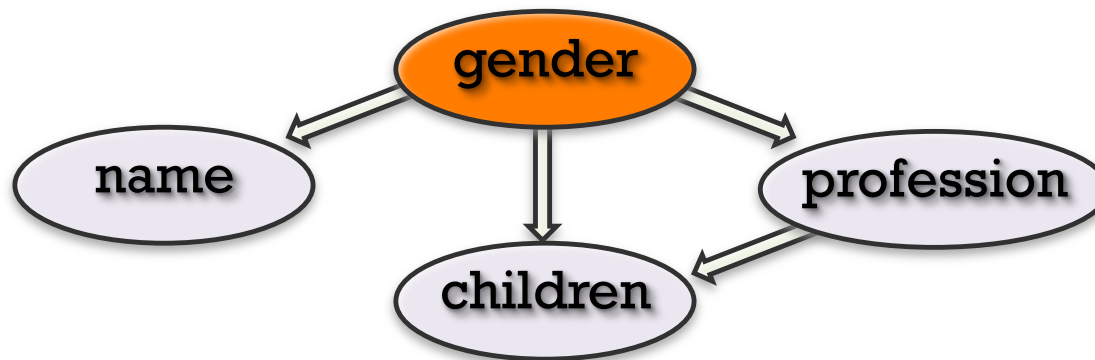


+ fNML vs. NML: what's new?

fNML: minimax code applied
column by column

NAME	GENDER	PROFESSION	CHILDREN
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Margrethe	female	queen	2
:	:	:	:

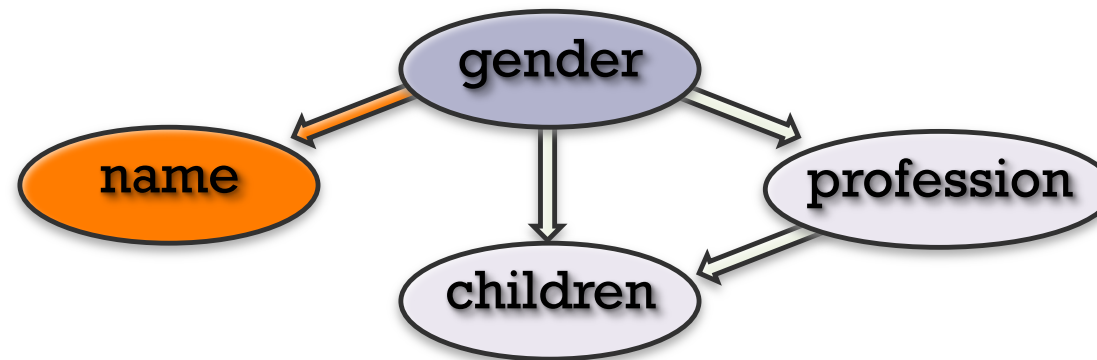
D_2



+ fNML vs. NML: what's new?

fNML: **Conditional** minimax code when parent(s) exist.

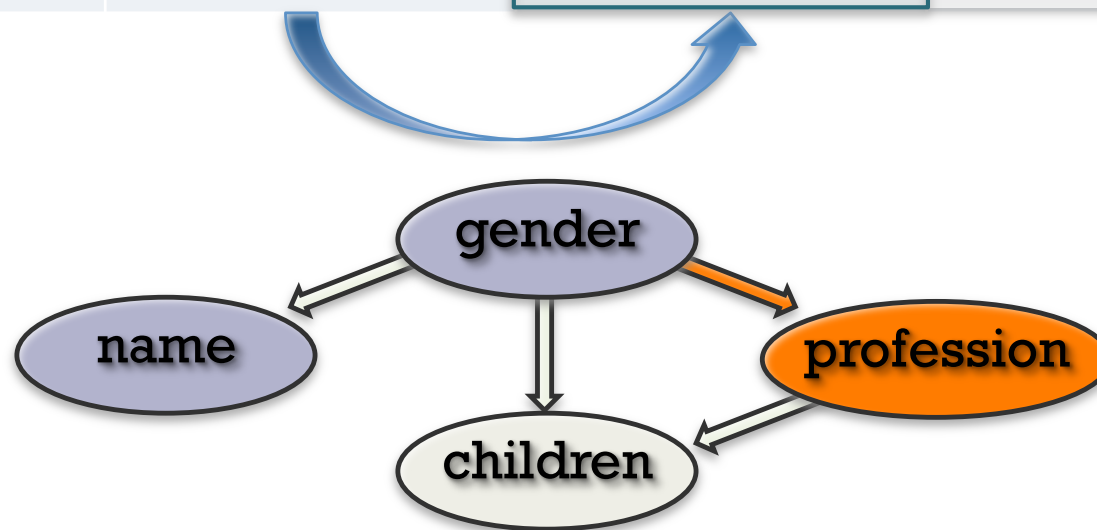
NAME	GENDER	PROFESSION	CHILDREN
Teemu	male	researcher	2
Clark D_1	male	reporter	0
Margrethe	female	queen	2
:	:	:	:



+ fNML vs. NML: what's new?

fNML: **Conditional** minimax code when parent(s) exist.

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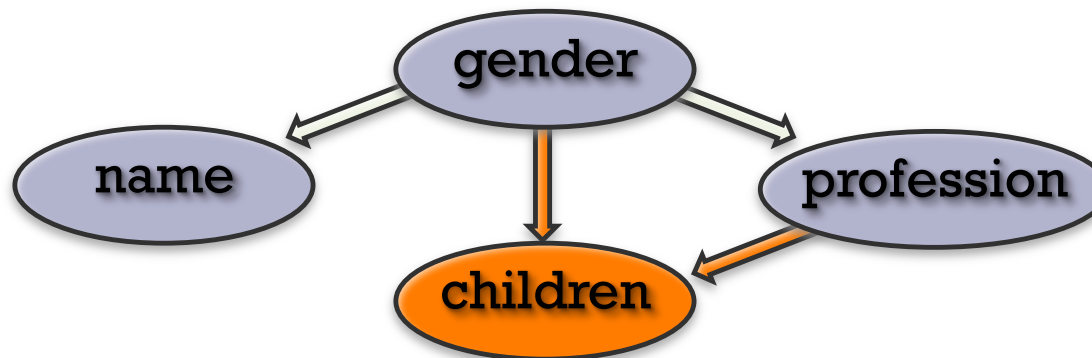


+ fNML vs. NML: what's new?

fNML: **Conditional** minimax code when parent(s) exist.

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D_4



+ fNML vs. NML: what's new?

fNML: **Conditional** minimax code when parent(s) exist.

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:	:	:	:

D_4

Each column is encoded using the minimax code for **multinomials**.

Using fast NML algorithms, this takes $O(n \log n)$ per column.

+ fNML: Consistency

(Haughton, 1988): Any **penalized likelihood** score of the form

$$SCORE(G, D) = \log \hat{P}(D | G) - \frac{k}{2} a_n,$$

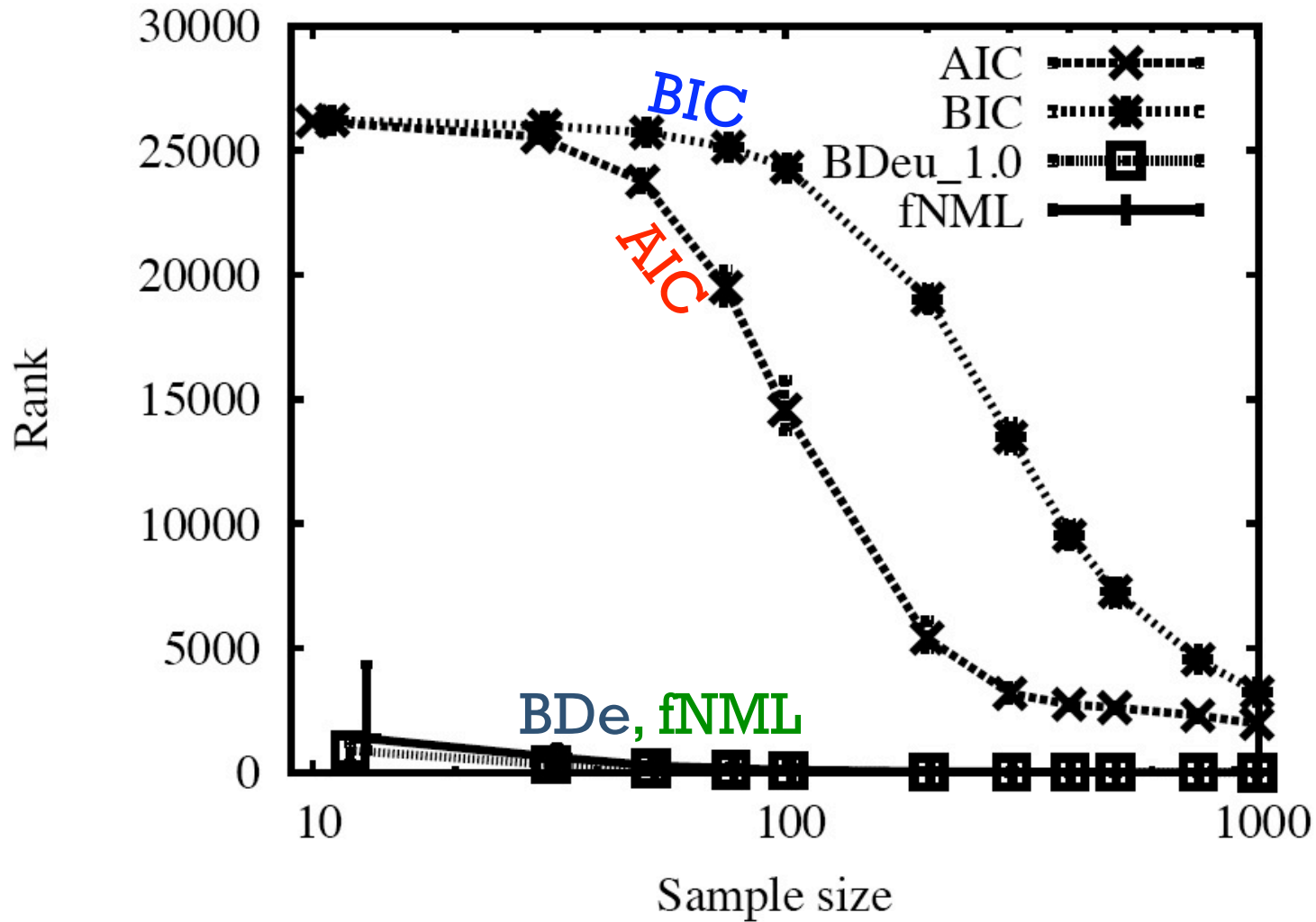
where a_n satisfies $a_n/n \rightarrow 0$ and $a_n \rightarrow \infty$, is **consistent**.

Theorem: fNML behaves asymptotically like BIC, i.e.,

$$a_n = \log n.$$

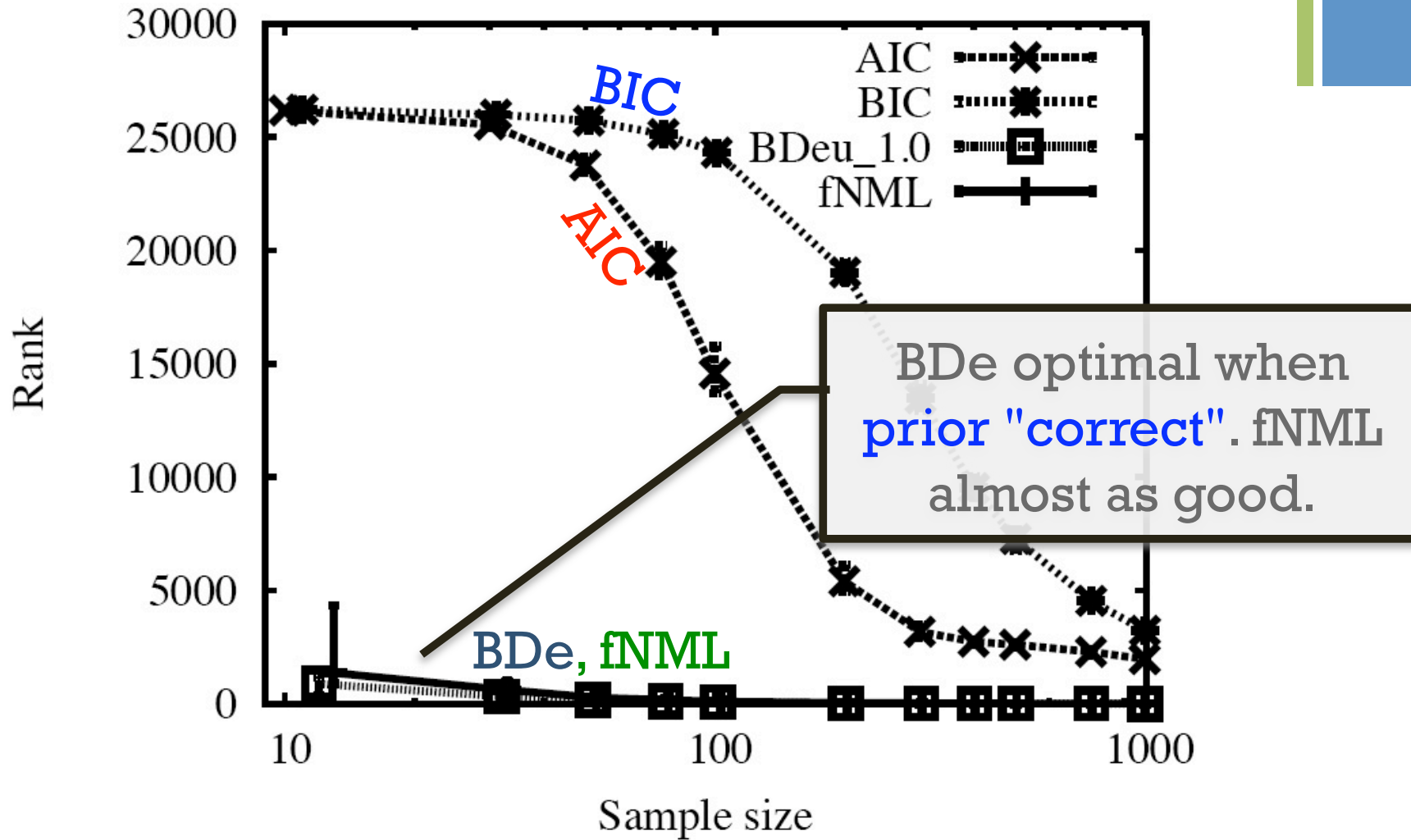
Hence, fNML is consistent.

+ Robustness



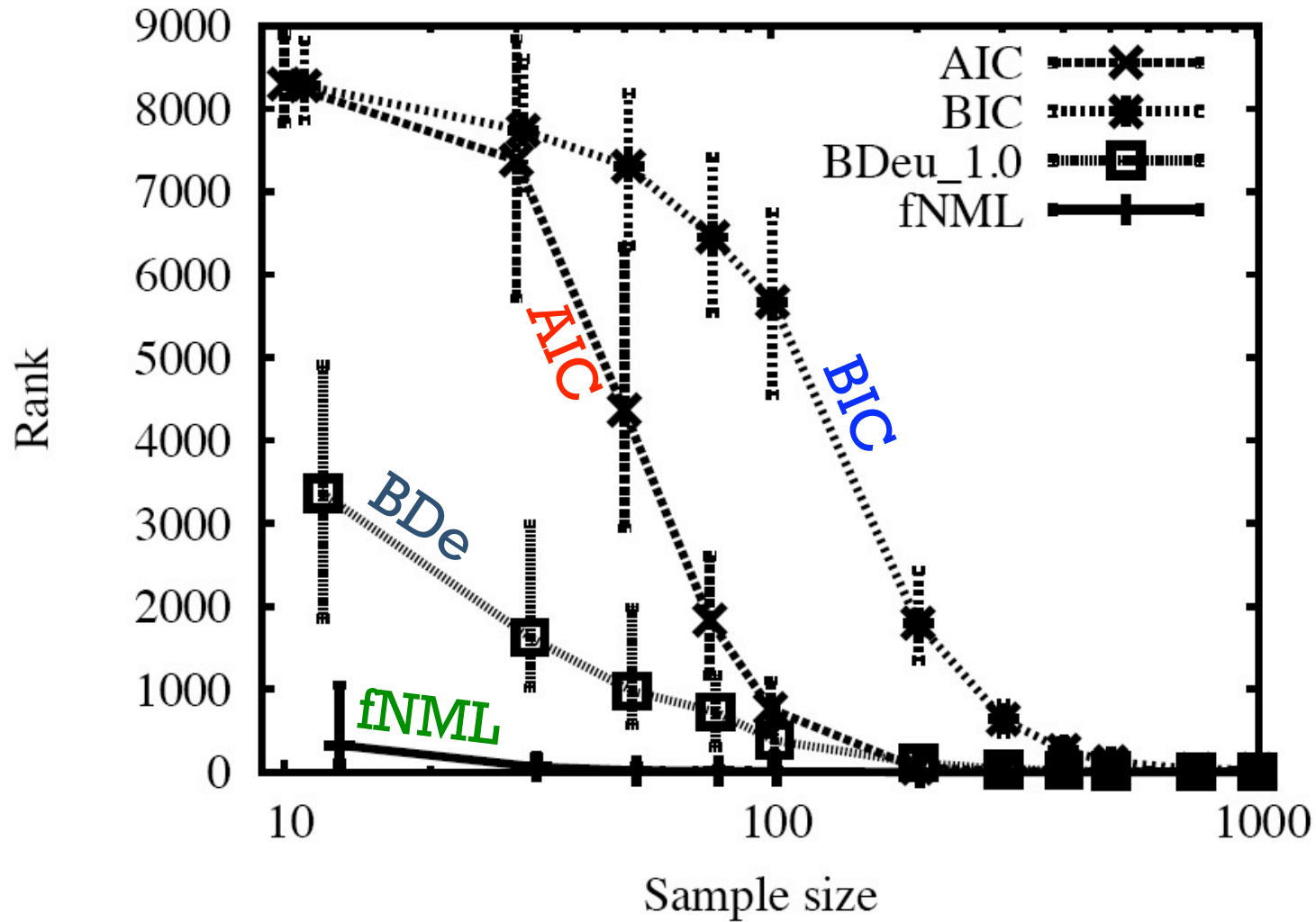
(a) BDeu Scheme

+ Robustness



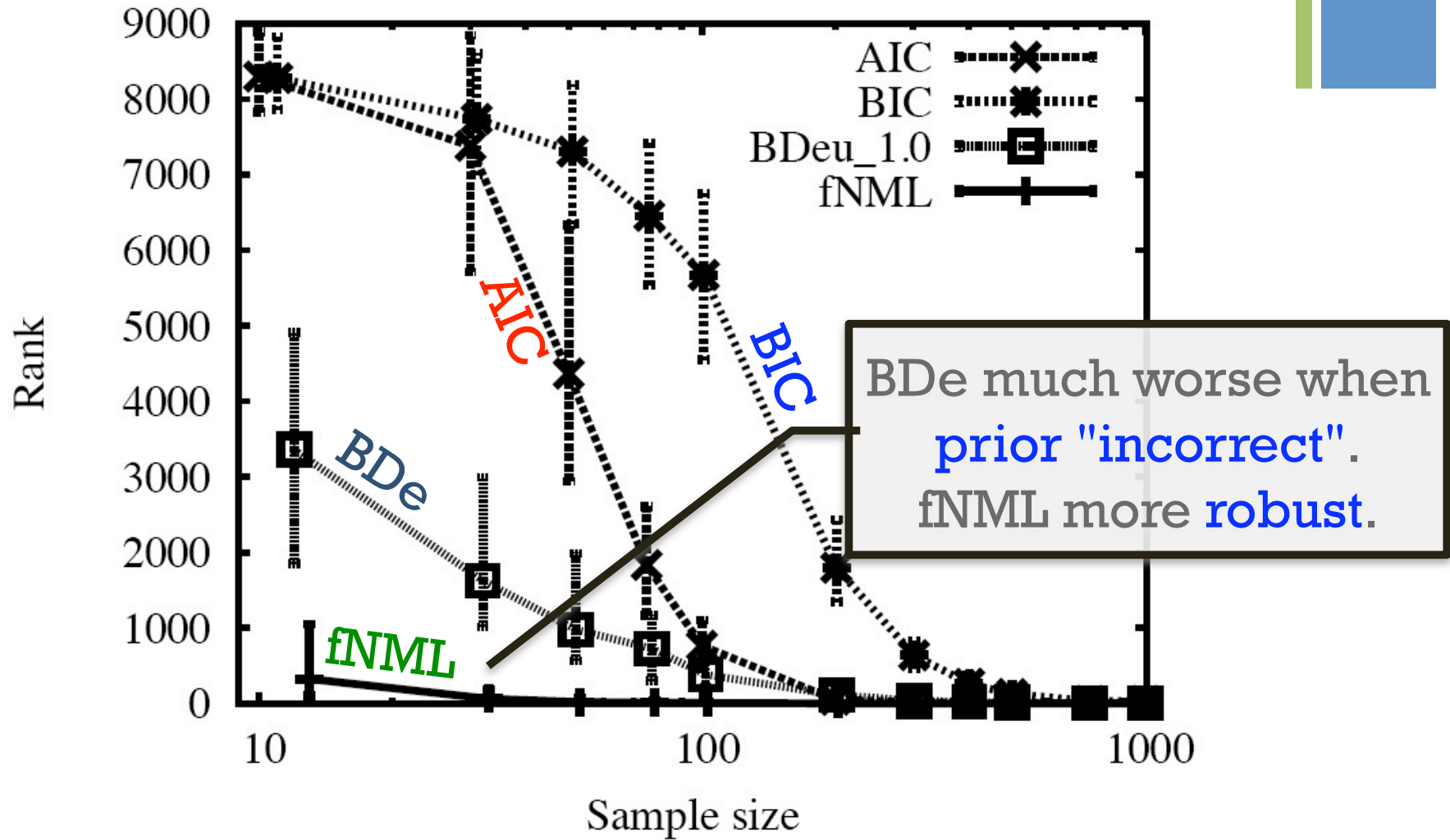
(a) BDeu Scheme

+ Robustness

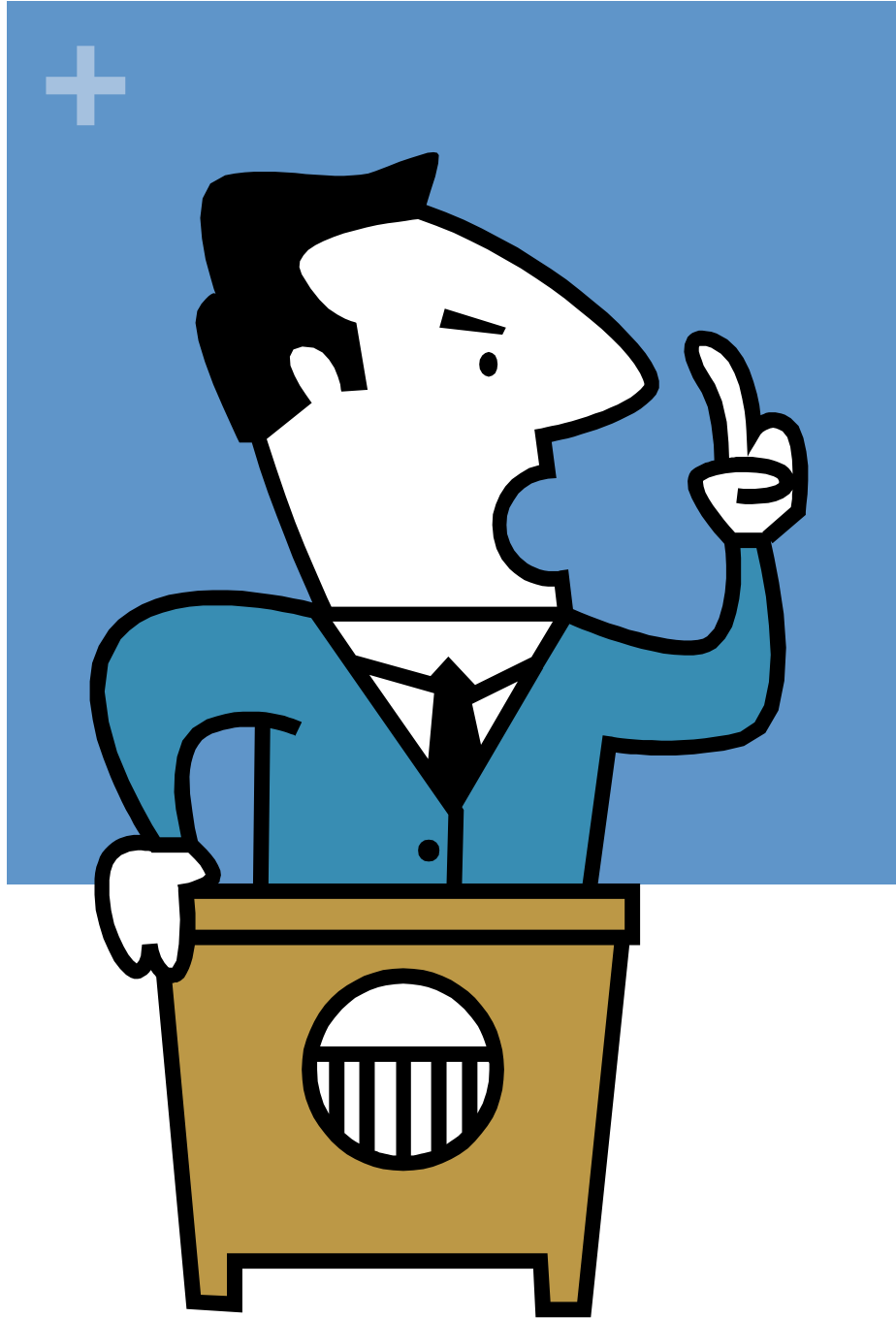


(b) Dir(1/2,...,1/2) Scheme

+ Robustness



(b) Dir(1/2,...,1/2) Scheme



+ Decomposable Scores

Problem: Super-exponential search space.

Solution: Decomposable scores

$$SCORE(G,D) = \sum_{i=1}^m S(D_i, D_{Gi})$$

For decomposable scores, exact search (global optimum) can be done for about $m \leq 30$ nodes (Koivisto & Sood, 2004; Silander and Myllymäki, 2006).