# Information-Theoretic Modeling <br> Lecture 2: Mathematical Preliminaries 

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## Lecture 2: Mathematical Preliminaries


"I think you should be more explicit here in step two."
(1) Calculus

- Limits and Convergence
- Convexity
(2) Probability
- Probability Space and Random Variables
- Joint and Conditional Distributions
- Expectation
- Law of Large Numbers
(3) Inequalities
- Jensen's Inequality
- Gibbs's Inequality



## Exponent Function



Exponent function $\exp : \mathbb{R} \rightarrow \mathbb{R}^{+}, \exp k=e^{k}=\overbrace{e \times e \times \ldots \times e}$ : multiplicative growth (nuclear reaction, "interest on interest", ...)
$\exp x \cdot \exp y=\exp (x+y) \quad$ Derivative $\frac{d \exp x}{d x}=\exp x$.

Outline

## Examples: Logarithm



Natural logarithm $\ln : \mathbb{R}^{+} \rightarrow \mathbb{R}, \ln \exp x=x:$
time to grow to $x$, number of digits $\left(\log _{10}\right)$.
General (base a) logarithm, $\log _{a} a^{x}=x: \quad \log _{a} x=\frac{1}{\ln a} \ln x$

Outline

## Logarithm Function



$$
\begin{aligned}
& \ln x y=\ln x+\ln y \quad \ln x^{r}=r \ln x \quad \ln \frac{1}{x}=-\ln x \quad \ln \frac{x}{y}=\ln x-\ln y \\
& \quad \frac{d \ln x}{d x}=\frac{1}{x}
\end{aligned}
$$

## Limits and Convergence

- A sequence of values $\left(x_{i}: i \in \mathbb{N}\right)$ converges to limit $L$, $\lim _{i \rightarrow \infty} x_{i}=L$, iff for any $\epsilon>0$ there exists a number $N \in \mathbb{N}$ such that

$$
\left|x_{i}-L\right|<\epsilon \quad \text { for all } i \geq N .
$$

- $f(x)$ has a limit $L$ as $x$ approaches $c, \lim _{x \rightarrow c} f(x)=L$, (from above $c^{+} /$below $c^{-}$) iff for any $\epsilon>0$ there exists a number $\delta>0$ such that

$$
|f(x)-L|<\epsilon \quad \text { for all } \begin{cases}c<x<c+\delta & \text { 'above' } \\ c-\delta<x<c & \text { 'below' } \\ 0<|x-c|<\delta & -\end{cases}
$$

## Example: Logarithm Again



Even though $x \ln x$ is undefined at $x=0$, we have (by l'Hôpital's rule):

$$
\lim _{x \rightarrow 0^{+}} x \ln x=0
$$

## Convexity

Function $f: \mathcal{X} \rightarrow \mathbb{R}$ is said to be convex iff for any $x, y \in \mathcal{X}$ and any $0 \leq t \leq 1$ we have

$$
f(t x+(1-t) y) \leq t f(x)+(1-t) f(y)
$$

Function $f$ is strictly convex iff the above inequality holds strictly ( $<$ ' instead of ' $\leq$ ') when $0<t<1$.

Function $f$ is (strictly) concave iff the above holds for $-f$.

## Convexity and Derivatives

## Theorem

If function $f$ has a second derivative $f^{\prime \prime}$, and $f^{\prime \prime}$ is non-negative $(\geq 0)$ for all $x$, then $f$ is convex. If $f^{\prime \prime}$ is positive $(>0)$ for all $x$, then $f$ is strictly convex.

$e^{x}$ is conve ${ }^{x}$ !

Example: $f^{\prime}(x)=\frac{d \exp x}{d x}=\exp x \Rightarrow f^{\prime \prime}(x)=\exp x>0$. Hence exp is strictly convex.

## Probability


A.N. Kolmogorov, 1903-1987
(1) Calculus

- Limits and Convergence
- Convexity
(2) Probability
- Probability Space and Random Variables
- Joint and Conditional Distributions
- Expectation
- Law of Large Numbers
(3) Inequalities
- Jensen's Inequality
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## Probability Space

A probability space $(\Omega, \mathcal{F}, P)$ is defined by

- the sample space $\Omega$ whose elements are called outcomes $\omega$,
- a sigma algebra $\mathcal{F}$ of subsets of $\Omega$, whose elements are called events $E$, and
- a measure $P$ which determines the probabilities of events, $P: \mathcal{F} \rightarrow[0,1]$.

Measure $P$ has to satisfy the probability axioms: $P(E) \geq 0$ for all $E \in \mathcal{F}, P(\Omega)=1$, and $P\left(E_{1} \cup E_{2} \cup \ldots\right)=\sum_{i} P\left(E_{i}\right)$ if $\left(E_{i}\right)$ is a countable sequence of disjoint events.

These axioms imply the usual rules of probability calculus, e.g., $P(A \cup B)=P(A)+P(B)-P(A \cap B), P(\Omega \backslash E)=1-P(E)$, etc.

## Venn Diagrams

## $\Omega$



## Probability Calculus

(1) The conditional probability of event $B$ given that event $A$ occurs is defined as

$$
P(B \mid A)=\frac{P(A \cap B)}{P(A)} \quad \text { for } A \text { such that } P(A)>0
$$

(2) $P(A \cap B)=P(A) \cdot P(B \mid A)=P(B) \cdot P(A \mid B)$.
(3) Bayes' rule: $P(B \mid A)=\frac{P(A \mid B) \cdot P(B)}{P(A)}$.
(9) Chain rule:

$$
\begin{aligned}
P\left(\cap_{i=1}^{N} E_{i}\right)= & \prod_{i=1}^{N} P\left(E_{i} \mid \cap_{j=1}^{i-1} E_{j}\right) \\
= & P\left(E_{1}\right) \cdot P\left(E_{2} \mid E_{1}\right) \cdot P\left(E_{3} \mid E_{1} \cap E_{2}\right) \cdot \ldots \\
& \cdot P\left(E_{N} \mid E_{1} \cap \ldots \cap E_{N-1}\right)
\end{aligned}
$$

## Random Variables

Technically, a random variable is a (measurable) function $X: \Omega \rightarrow \mathbb{R}$ from the sample space to the reals.

The probability measure $P$ on $\Omega$ determines the distribution of $X$ :

$$
P_{X}(A)=\operatorname{Pr}[X \in A]=P(\{\omega: X(\omega) \in A\})
$$

where $A \subseteq \mathbb{R}$.
It is often more natural to relabel the outcomes and denote them, for instance, by letters, $A, B, C, \ldots$, or words red, black, $\ldots$

In practice, we often forget about the underlying probability space $\Omega$, and just speak of random variable $X$ and its distribution $P_{X}$.

## Random Variables

The distribution of a random variable can always be represented as a cumulative distribution function (cdf) $F_{X}(x)=\operatorname{Pr}[X \leq x]$.

In addition:

- A discrete random variable $X$ with countable alphabet $\mathcal{X}$ has a probability mass function (pmf) $p_{X}$ such that $\operatorname{Pr}[X=x]=p_{X}(x)$.
- A continuous random variable $Y$ has a probability density function (pdf) $f_{Y}$ such that $\operatorname{Pr}[Y \in A]=\int_{A} f_{Y}(x) d y$.
There are also mixed random variables that are neither discrete nor continuous. They don't have a pmf or pdf, but they do have a cdf.

We often omit the subscripts $X, Y, \ldots$ and write $p(x), f(y)$, etc.

## Random Variables

Since random variables are functions, we can define more random variables as functions of random variables: if $f$ is a function, and $X$ and $Y$ are r.v.'s, then $f(X): \Omega \rightarrow \mathbb{R}$ is a r.v., $X+Y$ is a r.v., etc.

Example: Let r.v. $X$ be the outcome of a die.

- The pmf of $X$ is given by $p_{X}(x)=1 / 6$ for all $x \in\{1,2,3,4,5,6\}$.
- The pmf of r.v. $X^{2}$ is given by $p_{X^{2}}(x)=1 / 6$ for all $x \in\{1,4,9,16,25,36\}$.

In particular, a pmf $p_{X}$ is a function, and hence, $p_{X}(X)$ is also a random variable. Further, $p_{X}^{2}(X), \ln p_{X}(X)$, etc. are random variables.

## Multivariate Distributions

The probabilistic behavior of two or more random variables is described by multivariate distributions.

The joint distribution of r.v.'s $X$ and $Y$ is

$$
\begin{aligned}
P_{X, Y}(A, B) & =\operatorname{Pr}[X \in A \wedge Y \in B] \\
& =P(\{\omega: X(\omega) \in A, Y(\omega) \in B\})
\end{aligned}
$$

For each multivariate distribution $P_{X, Y}$, there are unique marginal distributions $P_{X}$ and $P_{Y}$ such that

$$
\begin{gathered}
P_{X}(A)=P_{X, Y}(A, \mathbb{R}), \quad P_{Y}(B)=P_{X, Y}(\mathbb{R}, B) \\
\text { pmf: } p_{Y}(y)=\sum_{x \in \mathcal{X}} p_{X, Y}(x, y) \quad \text { pdf: } f_{Y}(y)=\int_{\mathbb{R}} f_{X, Y}(x, y) d x
\end{gathered}
$$

## Multivariate Distributions

The conditional distribution is defined similar to conditional probability:

$$
P_{Y \mid X}(B \mid A)=\frac{P_{X, Y}(A, B)}{P_{X}(A)} \quad \text { for } A \text { such that } P_{X}(A)>0
$$

For discrete/continuous variables we have:

- discrete r.v.'s:

$$
p_{Y \mid X}(y \mid x)=\frac{p_{X, Y}(x, y)}{p_{X}(x)}, \quad p_{X}(x)>0
$$

- continuous r.v.'s:

$$
f_{Y \mid X}(y \mid x)=\frac{f_{X, Y}(x, y)}{f_{X}(x)}, \quad f_{X}(x)>0
$$

## Independence

Variable $X$ is said to be independent of variable $Y(X \Perp Y)$ iff

$$
P_{X, Y}(A, B)=P_{X}(A) \cdot P_{Y}(B) \quad \text { for all } A, B \subseteq \mathbb{R}
$$

This is equivalent to

$$
P_{X \mid Y}(A \mid B)=P_{X}(A) \text { for all } B \text { such that } P(B)>0
$$

and

$$
P_{Y \mid X}(B \mid A)=P_{Y}(B) \quad \text { for all } A \text { such that } P(A)>0
$$

In words, knowledge about one variable tells nothing about the other. Note that independence is symmetric, $X \Perp Y \Leftrightarrow Y \Perp X$.

## Expectation

The expectation (or expected value, or mean) of a discrete random variable is given by

$$
E[X]=\sum_{x \in \mathcal{X}} p(x) x
$$

The expectation of a continuous random variable is given by

$$
E[X]=\int_{\mathcal{X}} f(x) x d x
$$

In both cases, it is possible that $E[X]= \pm \infty$.

$$
\begin{aligned}
& E[k X]=k E[X] \quad E[X+Y]=E[X]+E[Y] \\
& E[X Y]=E[X] E[Y] \quad \text { if } X \Perp Y
\end{aligned}
$$

Probability Space and Random Variables

## Law of Large Numbers

Let $X_{1}, X_{2}, \ldots$ be a sequence of independent outcomes of a die, so that $p_{X_{i}}(x)=1 / 6$ for all $i \in \mathbb{N}, x \in\{1,2,3,4,5,6\}$.


$$
E\left[X_{i}\right]=\sum_{x=1}^{6} \frac{1}{6} x=\frac{21}{6}=3.5 \quad \text { for all } i \in \mathbb{N}
$$

## Law of Large Numbers

Let $S_{n}=\sum_{i=1}^{n} X_{n}$ be the sum of the first $n$ outcomes.
The distribution of $S_{n}$ is given by

$$
P_{S_{n}}(x)=\frac{\# \text { of ways to get sum } x \text { with } n \text { dice }}{6^{n}}
$$

distribution of $S_{1}$


Probability Space and Random Variables

## Law of Large Numbers

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$$

distribution of $S_{2}$


## Law of Large Numbers

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$$
P_{S_{n}}(x)=\frac{\# \text { of ways to get sum } x \text { with } n \text { dice }}{6^{n}}
$$

distribution of $S_{3}$


## Law of Large Numbers

Let $S_{n}=\sum_{i=1}^{n} X_{n}$ be the sum of the first $n$ outcomes.
The distribution of $S_{n}$ is given by

$$
P_{S_{n}}(x)=\frac{\# \text { of ways to get sum } x \text { with } n \text { dice }}{6^{n}}
$$

distribution of $S_{4}$


## Law of Large Numbers

Let $S_{n}=\sum_{i=1}^{n} X_{n}$ be the sum of the first $n$ outcomes.
The distribution of $S_{n}$ is given by

$$
P_{S_{n}}(x)=\frac{\# \text { of ways to get sum } x \text { with } n \text { dice }}{6^{n}}
$$

distribution of $S_{5}$


## Law of Large Numbers

Let $S_{n}=\sum_{i=1}^{n} X_{n}$ be the sum of the first $n$ outcomes.
The distribution of $S_{n}$ is given by

$$
P_{S_{n}}(x)=\frac{\# \text { of ways to get sum } x \text { with } n \text { dice }}{6^{n}}
$$



## Law of Large Numbers

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The distribution of $S_{n}$ is given by

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$$



## Law of Large Numbers

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The distribution of $S_{n}$ is given by

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$$



Outline

Probability Space and Random Variables Joint and Conditional Distributions Expectation
Law of Large Numbers

## Law of Large Numbers

## LAW OF LARGE NUMBERS IN AVERAGE OF DIE ROLLS <br> nuerage conuerges to expected unlue of 3.5



Probability Space and Random Variables

## Law of Large Numbers

## Weak Law of Large Numbers

For a sequence of independent and identically distributed (i.i.d.) random variables with finite mean $\mu$, the average $\frac{1}{n} S_{n}$ converges in probability to $\mu$ :

$$
\lim _{n \rightarrow \infty} \operatorname{Pr}\left[\left|\frac{S_{n}}{n}-\mu\right|<\epsilon\right]=1 \quad \text { for all } \epsilon>0
$$

We will use the LLN to prove a result known as the Asymptotic Equipartition Property (AEP), which is a central result in information theory (we'll return to it soon enough).
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Outline

## Jensen's inequality



J.L.W.V. Jensen, 1859-1925

## Inequalities: Jensen

Jensen's inequality
If $f$ is a convex function and $X$ is a random variable, then

$$
E[f(X)] \geq f(E[X]) .
$$

Moreover, if $f$ is strictly convex, the inequality holds as an equality if and only if $X=E[X]$ with probability 1 .

## Inequalities: Jensen



Source: Inductio Ex Machina, mark.reid.name/iem/

## Inequalities: Jensen

## Jensen's inequality

If $f$ is a convex function and $X$ is a random variable, then

$$
E[f(X)] \geq f(E[X])
$$

Moreover, if $f$ is strictly convex, the inequality holds as an equality if and only if $X=E[X]$ with probability 1 .

We give a proof for the first part of the theorem in the special case where $X$ has a finite domain.

For two mass points, we have $p\left(x_{2}\right)=1-p\left(x_{1}\right)$, and the claim holds by definition of convexity:

$$
p\left(x_{1}\right) f\left(x_{1}\right)+p\left(x_{2}\right) f\left(x_{2}\right) \geq f\left(p\left(x_{1}\right) x_{1}+p\left(x_{2}\right) x_{2}\right) .
$$

## Inequalities: Jensen

Induction: Assume that $(*)$ the theorem holds for $N-1$ mass points.

$$
\begin{aligned}
& \begin{aligned}
\sum_{i=1}^{N} p\left(x_{i}\right) f\left(x_{i}\right) & =p\left(x_{N}\right) f\left(x_{N}\right)+\left(1-p\left(x_{N}\right)\right) \sum_{i=1}^{N-1} p^{\prime}\left(x_{i}\right) f\left(x_{i}\right) \\
& \geq p\left(x_{N}\right) f\left(x_{N}\right)+\left(1-p\left(x_{N}\right)\right) f\left(\sum_{i=1}^{N-1} p^{\prime}\left(x_{i}\right) x_{i}\right)(*) \\
& \geq f\left(p\left(x_{N}\right) x_{N}+\left(1-p\left(x_{N}\right)\right) \sum_{i=1}^{N-1} p^{\prime}\left(x_{i}\right) x_{i}\right)(\text { convexity ) } \\
& =f\left(\sum_{i=1}^{N} p\left(x_{i}\right) x_{i}\right)
\end{aligned} \\
& \text { where } p^{\prime}\left(x_{i}\right)= \\
& \frac{p\left(x_{i}\right)}{1-p\left(x_{N}\right)}
\end{aligned}
$$

## Gibbs’ inequality


W. Gibbs, 1839-1903

## Inqualities: Gibbs

Gibbs' inequality
For any two discrete probability distributions $p$ and $q$, we have

$$
\sum_{x \in \mathcal{X}} p(x) \log _{2} p(x) \geq \sum_{x \in \mathcal{X}} p(x) \log _{2} q(x)
$$

with equality if and only if $p(x)=q(x)$ for all $x \in \mathcal{X}$.

Proof (of the inequality part). next slide...

## Inequalities: Gibbs

Gibbs' inequality

$$
\sum_{x \in \mathcal{X}} p(x) \log _{2} p(x) \geq \sum_{x \in \mathcal{X}} p(x) \log _{2} q(x)
$$

$\sum_{x \in \mathcal{X}} p(x) \log _{2} q(x)-\sum_{x \in \mathcal{X}} p(x) \log _{2} p(x)=\sum_{x \in \mathcal{X}} p(x)\left(\log _{2} q(x)-\log _{2} p(x)\right)$

$$
=\sum_{x \in \mathcal{X}} p(x) \log _{2} \frac{q(x)}{p(x)} \quad \log _{2} x-\log _{2} y=\log _{2} \frac{x}{y}
$$

$$
=E\left[\log _{2} \frac{q(x)}{p(x)}\right] \leq \log _{2} E\left[\frac{q(x)}{p(x)}\right]
$$

$$
=\log _{2} \sum_{x \in \mathcal{X}} p(x) \frac{q(x)}{p(x)}=\log _{2} \sum_{x \in \mathcal{X}} q(x)=\log _{2} 1=0
$$

## What's next...

Basic concepts: entropy, mutual information, ...
Theory and applications:

- source coding theory
- noisy channel coding

