Bayesian Networks: Belief Propagation (Cont'd)

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Belief Propagation Review and Examples

Outline

Belief Propagation

Review and Examples

Belief Propagation

Review and Examples

Generalized Belief Propagation - Max-Product

Applications to Loopy Graphs

Announcement: The last exercise will be posted online soon.

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Belief Propagation Review and Examples

Review of Last Lecture

We studied an algorithm for computing marginal posterior distributions:

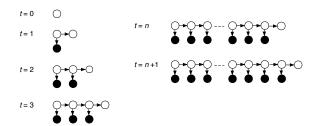
- It works in singly connected networks, which are DAGs whose undirected versions are trees.
- It is suitable for parallel implementation.
- It is recursively derived by
 - (i) dividing the total evidence in pieces, according to the independence structure represented by the DAG, and then
 - (ii) incorporating evidence pieces in either the probability terms $(\pi$ -messages) or the likelihood terms (conditional probability terms; λ -messages).

Queries answerable by the algorithm for a singly connected network:

- $P(X = x | \mathbf{e})$ for a single x;
- $P(X_v = x_v | \mathbf{e})$ for all x_v and $v \in V$;
- Most probable configurations, arg max, p(x & e).

This can be related to finding global optimal solutions by distributed local computation. (Details are given today.)

Practice: Belief Propagation for HMM



Observation variables (black) are instantiated; latent variables (white) are X_1, X_2, \ldots The total evidence at time t is e_t . How would you use message-passing to calculate

- $p(x_t | \mathbf{e}_t), \forall x_t$? (You'll obtain as a special case the so-called forward algorithm.)
- $p(x_{t+1} | \mathbf{e}_t)$, $\forall x_{t+1}$? (This is a prediction problem.)
- $p(x_k | \mathbf{e}_t)$, $\forall x_k, k < t$? (You'll obtain as a special case the so-called backward algorithm.)

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Belief Propagation Review and Examples

Example: Belief Updating

Without observing any evidence, all the π -messages are prior probabilities:

$$\pi_{X_i,Y_i}(x_i) = [p_i, q_i], \quad i = 1, 2, 3; \quad \pi_{Y_0,Y_1}(y_0) = [1, 0],$$

$$\pi_{Y_1,Y_2}(y_1) = [p_1, q_1], \quad \pi_{Y_2,Y_3}(y_2) = [p_1p_2, 1 - p_1p_2],$$

for $x_i = 1, 0$ and $y_i = 1, 0$.

Suppose $e: \{X_2 = 1, Y_3 = 0\}$ is received. Then, X_2 updates its message to Y_2 and Y_2 updates its message to Y_3 :

$$\pi_{X_2,Y_2}(x_2) = [p_2, 0], \quad \pi_{Y_2,Y_3}(y_2) = [p_1p_2, q_1p_2].$$

 λ -messages starting from Y_3 upwards are given by:

$$\lambda_{Y_3,X_3}(x_3) = [p_2q_1, p_2], \qquad \lambda_{Y_3,Y_2}(y_2) = [q_3, 1]; \\ \lambda_{Y_2,X_2}(x_2) = [p_1q_3 + q_1, p_1 + q_1q_3], \qquad \lambda_{Y_2,Y_1}(y_1) = [p_2q_3, p_2]; \\ \lambda_{Y_1,X_1}(x_1) = [p_2q_3, p_2].$$

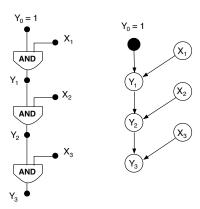
So

$$P(X_3 = 0 | \mathbf{e}) = \frac{q_3 p_2}{p_3 p_2 q_1 + q_3 p_2} = \frac{q_3}{p_3 q_1 + q_3} = \frac{q_3}{1 - p_1 p_3},$$

$$P(X_1 = 0 | \mathbf{e}) = \frac{q_1 p_2}{p_1 p_2 q_3 + q_1 p_2} = \frac{q_1}{p_1 q_3 + q_1} = \frac{q_1}{1 - p_1 p_3}.$$

A Fault-Detection Example

A logic circuit for fault detection and its Bayesian network (Pearl 1988):



- $P(X_i = 1) = p_i$ $P(X_i = 0) = 1 - p_i = q_i$ $Y_i = Y_{i-1} \text{ AND } X_i$.
- $Y_0 = 1$ always.
- X_i is normal if $X_i = 1$, and faulty if $X_i = 0$.
- Normally all variables are on, and a failure occurs if $Y_3 = 0$.

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Belief Propagation Review and Examples

Example: Explanations based on Beliefs

If $q_1 = 0.45$ and $q_3 = 0.4$, we obtain

$$P(X_1 = 0 | \mathbf{e}) = 0.672 > P(X_1 = 1 | \mathbf{e}) = 0.328,$$

 $P(X_3 = 0 | \mathbf{e}) = 0.597 > P(X_3 = 1 | \mathbf{e}) = 0.403.$

Is $I_1 = \{X_1 = 0, X_3 = 0\}$ the most probable explanation of **e**, however?

There are three possible explanations

$$I_1 = \{X_1 = 0, X_3 = 0\}, \quad I_2 = \{X_1 = 0, X_3 = 1\}, \quad I_3 = \{X_1 = 1, X_3 = 0\}.$$

Direct calculation shows

$$P(I_1 | \mathbf{e}) = \frac{q_1 q_3}{1 - p_1 p_3}, \quad P(I_2 | \mathbf{e}) = \frac{q_1 p_3}{1 - p_1 p_3}, \quad P(I_3 | \mathbf{e}) = \frac{p_1 q_3}{1 - p_1 p_3}.$$

So, if $0.5 > q_1 > q_2 > q_3$, then based on the evidence, l_2 is the most probable explanation, while l_1 is the *least* probable explanation.

Outline

Belief Propagation

Generalized Belief Propagation - Max-Product

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Belief Propagation Generalized Belief Propagation - Max-Product

Derivation of the Message Passing Algorithm

Evidence structure: We can express the joint distribution P(X) as

$$p(x) = \prod_{u \in \mathsf{pa}(v)} p(x_{T_{vu}}) \cdot p(x_v \mid x_{\mathsf{pa}(v)}) \cdot \prod_{w \in \mathsf{ch}(v)} p(x_{T_{vw}} \mid x_v). \tag{1}$$

We then enter the evidence e (put each piece in a proper term) to obtain

$$p(x \& \mathbf{e}) = \prod_{u \in \mathsf{pa}(v)} p(x_{T_{vu}} \& \mathbf{e}_{T_{vu}}) \cdot p(x_v \& \mathbf{e}_v \,|\, x_{\mathsf{pa}(v)}) \cdot \prod_{w \in \mathsf{ch}(v)} p(x_{T_{vw}} \& \mathbf{e}_{T_{vw}} \,|\, x_v). \tag{2}$$

(For a detailed derivation of Eqs. (1) and (2), see slides 24-27.)

Max-Product: To solve $\max_{x} p(x \& e)$, we consider maximizing with respect to groups of variables in the following order:

$$\max_{x} \ \Leftrightarrow \ \max_{x_{v}} \max_{x_{\mathsf{pa}(v)}} \max_{x_{\mathsf{T}vu_{1}} \setminus \{u_{1}\}} \cdots \max_{x_{\mathsf{T}vu_{n}} \setminus \{u_{n}\}} \max_{x_{\mathsf{T}vu_{1}}} \cdots \max_{x_{\mathsf{T}vw_{m}}},$$

where $T_{vu} \setminus \{u\}$ denotes the set of nodes in the sub-polytree T_{vu} except for $\{u\}$.

Notice that for any two functions $f_1(x)$, $f_2(x, y)$, we have the identity

$$\max_{x,y} \{ f_1(x) f_2(x,y) \} = \max_{x} \{ f_1(x) \cdot (\max_{y} f_2(x,y)) \}.$$

We will similarly move certain maximization operations inside the products in Eq. (2) to obtain a desirable factor form of $\max_{x} p(x \& e)$.

Recall Notation for Singly Connected Networks

Consider a vertex v.

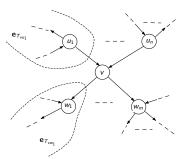
- $pa(v) = \{u_1, \dots, u_n\}, ch(v) = \{w_1, \dots, w_m\}$:
- T_{vu} , $u \in pa(v)$: the sub-polytree containing the parent u, resulting from removing the edge (u, v);
- T_{vw} , $w \in ch(v)$: the sub-polytree containing the child w, resulting from removing the edge (v, w).

For a sub-polytree T, denote

- X_T : the variables associated with nodes in T
- \mathbf{e}_T : the partial evidence of X_T

Divide the total evidence e in pieces:

- $\mathbf{e}_{T_{vu}}, u \in \mathsf{pa}(v);$
- e_v;
- $\mathbf{e}_{T_{vw}}, w \in \operatorname{ch}(v)$.



We want to solve: $\max_{x} p(x \& e)$.

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Belief Propagation Generalized Belief Propagation - Max-Product

Derivation of the Message Passing Algorithm

Consider first the maximization with respect to $x_{T_{vw}}, w \in ch(v)$. We have

$$\max_{x_{T_{vw_1}}} \cdots \max_{x_{T_{vw_m}}} p(x \& \mathbf{e}) = \left(\prod_{u \in \mathsf{pa}(v)} p(x_{T_{vu}} \& \mathbf{e}_{T_{vu}}) \right) \cdot p(x_v \& \mathbf{e}_v \mid x_{\mathsf{pa}(v)}).$$

$$\prod_{w \in \mathsf{ch}(v)} \max_{x_{T_{vw}}} p(x_{T_{vw}} \& \mathbf{e}_{T_{vw}} \mid x_v).$$

Maximizing the above expression with respect to $x_{\mathcal{T}_{vu_1}\setminus\{u_1\}},\dots,x_{\mathcal{T}_{vu_n}\setminus\{u_n\}}$, we obtain

$$\Big(\prod_{u\in\mathsf{pa}(v)}\max_{x_{\mathcal{T}_{vu}}\setminus\{u\}}p\big(x_{\mathcal{T}_{vu}}\&\,\mathbf{e}_{\mathcal{T}_{vu}}\big)\Big)\cdot p\big(x_{v}\&\,\mathbf{e}_{v}\,|\,x_{\mathsf{pa}(v)}\big)\cdot\prod_{w\in\mathsf{ch}(v)}\max_{x_{\mathcal{T}_{vw}}}p\big(x_{\mathcal{T}_{vw}}\&\,\mathbf{e}_{\mathcal{T}_{vw}}\,|\,x_{v}\big).$$

Define

$$\rho^*(x_u \& \mathbf{e}_{T_{vu}}) = \max_{X_{T_{vu}} \setminus \{u\}} p(X_{T_{vu}} \& \mathbf{e}_{T_{vu}}), \qquad \rho^*(\mathbf{e}_{T_{vw}} \mid X_v) = \max_{X_{T_{vw}}} p(X_{T_{vw}}, \mathbf{e}_{T_{vw}} \mid X_v).$$
(3)

We obtain

$$\max_{x} p(x \,\&\, \mathbf{e}) = \max_{x_{v}} \Big(\max_{x_{\mathsf{pa}(v)}} \prod_{u \in \mathsf{pa}(v)} p^{*}(x_{u} \,\&\, \mathbf{e}_{T_{vu}}) \cdot p(x_{v} \,\&\, \mathbf{e}_{v} \,|\, x_{\mathsf{pa}(v)}) \Big) \cdot \prod_{w \in \mathsf{ch}(v)} p^{*}(\mathbf{e}_{T_{vw}} \,|\, x_{v}).$$

We will call the expression inside 'max x_{ν} ' the max-margin of X_{ν} , denoted $p^*(x_v \& e)$.

Derivation of the Message Passing Algorithm

Thus we obtain

$$\max_{x} p(x \& \mathbf{e}) = \max_{x_{v}} p^{*}(x_{v} \& \mathbf{e})$$

where

$$p^{*}(x_{v} \& \mathbf{e}) = \left(\max_{X_{\mathsf{pa}(v)}} \prod_{u \in \mathsf{pa}(v)} p^{*}(x_{u} \& \mathbf{e}_{T_{vu}}) \cdot p(x_{v} \& \mathbf{e}_{v} \mid x_{\mathsf{pa}(v)}) \right) \cdot \prod_{w \in \mathsf{ch}(v)} p^{*}(\mathbf{e}_{T_{vw}} \mid x_{v}).$$
(4)

If v can receive messages

• $\pi_{\mu\nu}^*$ from all parents, where

$$\pi_{u,v}^*(x_u) = p^*(x_u \& e_{T_{vu}}), \ \forall x_u,$$

• λ_{w}^{*} from all children, where

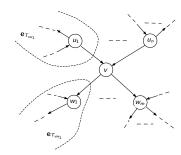
$$\lambda_{w,v}^*(x_v) = p^*(\mathbf{e}_{T_{vw}} | x_v), \quad \forall x_v,$$

then v can calculate its max-margin

$$p^*(x_v \& \mathbf{e}), \forall x_v,$$

and from which

$$\max_{x_v} p^*(x_v \& \mathbf{e}) = \max_{x} p(x \& \mathbf{e}).$$





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Bayesian Networks: Belief Propagation (Cont'd)

Belief Propagation Generalized Belief Propagation - Max-Product

Derivation of the Message Passing Algorithm

Now we only need to check if v can compose messages for its parents and children to calculate their max-margins.

• A parent u needs $p^*(\mathbf{e}_{T_{uv}}|x_u)$ for all x_u based on the partial evidence $\mathbf{e}_{T_{uv}}$ from the sub-polytree on v's side with respect to u:

$$p^*(\mathbf{e}_{T_{uv}} | x_u) = \max_{x_T} p(x_{T_{uv}} \& \mathbf{e}_{T_{uv}} | x_u).$$

Indeed it is given by

$$p^{*}(\mathbf{e}_{T_{uv}} | x_{u}) = \max_{x_{v}} \left\{ \left(\max_{x_{pa(v)\setminus\{u\}}} p(x_{v} \& \mathbf{e}_{v} | x_{pa(v)}) \cdot \prod_{u' \in pa(v)\setminus\{u\}} p^{*}(x_{u'} \& \mathbf{e}_{T_{vu'}}) \right) \right.$$

$$\left. \cdot \prod_{w \in ch(v)} p^{*}(\mathbf{e}_{T_{vw}} | x_{v}) \right\}$$

$$= \max_{x_{v}} \left\{ \left(\max_{x_{pa(v)\setminus\{u\}}} p(x_{v} | x_{pa(v)}) \ell_{v}(x_{v}) \cdot \prod_{u' \in pa(v)\setminus\{u\}} \pi_{u',v}^{*}(x_{u'}) \right) \right.$$

$$\left. \cdot \prod_{w \in ch(v)} \lambda_{w,v}^{*}(x_{v}) \right\}.$$
(5)

So this is the message $\lambda_{v,u}^*(x_u)$ that v needs to send to u; it can be composed once v receives the messages from all the other linked nodes.

Bayesian Networks: Belief Propagation (Cont'd)

(For the details of derivation of Eq. (5), see slide 28.)

Bayesian Networks: Belief Propagation (Cont'd)

Meanings of the Messages and Max-Margin

- $p^*(x_u \& e_{T_{vu}})$: If $X_u = x_u$, there exists some configuration of $x_{T_{vu}}$ which best explains the partial evidence $e_{T_{min}}$ with this probability.
- $p^*(\mathbf{e}_{T_{vv}}|x_v)$: If $X_v = x_v$, there exists some configuration of $x_{T_{vv}}$ which best explains the partial evidence $e_{T_{vw}}$ conditional on X_v , with this
- $p^*(x_v \& e)$: If $X_v = x_v$, there exists some configuration of the rest of the variables which best explains the evidence e with this probability.

How to obtain $x^* \in \arg\max_{x} p(x \& e)$?

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- If x^* is unique, then the solutions $x_v^* \in \arg\max_{v} p^*(x_v \& e)$ for all v form the global optimal solution (best explanation) x^* .
- If x^* is not unique, then we will need to trace out a solution from some node v. This shows that for each $x_v^* \in \arg\max_{x_v} p^*(x_v \& \mathbf{e})$, v should record the corresponding best values $x_{pa(v)}^*$ of the parents in the maximization problem defining $p^*(x_v \& e)$ [Eq. (4)]:

$$\max_{X_{\mathsf{pa}(v)}} \prod_{u \in \mathsf{pa}(v)} p^*(x_u \& \mathbf{e}_{T_{vu}}) \cdot p(x_v^* \& \mathbf{e}_v \,|\, x_{\mathsf{pa}(v)}).$$

Belief Propagation Generalized Belief Propagation - Max-Product

Derivation of the Message Passing Algorithm

• A child w needs $p^*(x_v \& e_{T_{wv}})$ for all x_v , which incorporates the partial evidence $\mathbf{e}_{T_{wv}}$ from the sub-polytree on v's side with respect to w:

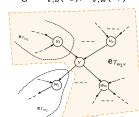
$$p^*(x_v \& e_{T_{wv}}) = \max_{x_{T_{wv}} \setminus \{y\}} p(x_{T_{wv}} \& e_{T_{wv}}).$$

By a similar calculation as in the previous slides, one can show that

$$\begin{split} \rho^*(x_v \,\&\, e_{\mathcal{T}_{\mathsf{WV}}}) &= \Big(\max_{\mathsf{x}_{\mathsf{pa}(v)}} \rho\big(x_v \,|\, x_{\mathsf{pa}(v)}\big) \,\ell_v(x_v) \cdot \prod_{u \in \mathsf{pa}(v)} \pi^*_{u,v}(x_u) \Big) \\ &\cdot \prod_{w' \in \mathsf{ch}(v) \setminus \{w\}} \lambda^*_{w',v}(x_v). \end{split}$$

So this is the message $\pi_{v,w}^*(x_v)$ that v needs to send to w; it can be composed once v receives the messages from all the other linked nodes.

Illustration of the partial evidence that the messages $\lambda_{v,u}^*(x_u)$, $\pi_{v,w}^*(x_v)$ carry:



Max-Product Message Passing Algorithm Summary

Each node v

• sends to each u of its parents

$$\begin{split} \lambda_{v,u}^*(x_u) &= \max_{x_v} \bigg\{ \max_{x_{\mathsf{pa}(v)\setminus\{u\}}} \rho(x_v \,|\, x_{\mathsf{pa}(v)}) \, \ell_v(x_v) \cdot \prod_{u' \in \mathsf{pa}(v)\setminus\{u\}} \pi_{u',v}^*(x_{u'}) \\ &\cdot \prod_{w \in \mathsf{ch}(v)} \lambda_{w,v}^*(x_v) \bigg\}, \qquad \forall x_u; \end{split}$$

• sends to each w of its children

$$\pi_{v,w}^*(x_v) = \prod_{w' \in \mathsf{ch}(v) \setminus \{w\}} \lambda_{w',v}^*(x_v) \cdot \max_{x_{\mathsf{pa}(v)}} p(x_v \,|\, x_{\mathsf{pa}(v)}) \, \ell_v(x_v) \cdot \prod_{u \in \mathsf{pa}(v)} \pi_{u,v}^*(x_u), \quad \forall x_v;$$

• when receiving all messages from parents and children, calculates

$$\rho^*(x_v \& \mathbf{e}) = \Big(\prod_{w \in \mathsf{ch}(v)} \lambda_{w,v}^*(x_v)\Big) \cdot \max_{x_{\mathsf{pa}(v)}} \prod_{u \in \mathsf{pa}(v)} \pi_{u,v}^*(x_u) \cdot \rho(x_v \,|\, x_{\mathsf{pa}(v)}) \,\ell_v(x_v), \quad \forall x_v.$$

This is identical to the algorithm in the last lecture, with maximization replacing the summation.

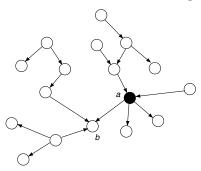
To obtain a $x^* \in \arg\max_{x} p(x \& \mathbf{e})$:

- If x^* is unique, then it is given by $x_v^* \in \arg\max_{x_v} p^*(x_v \& e)$ for all v.
- If x^* is not unique, we can start from any node v, fix x_v^* and then trace out the solutions at other nodes. 4□ > 4団 > 4 豆 > 4 豆 > 0 Q @

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Belief Propagation Generalized Belief Propagation - Max-Product

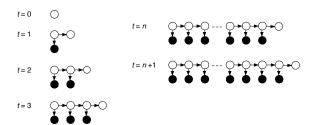
Discussion on Differences between Algorithms



Node a is instantiated. Node b never receives any evidence. New pieces of evidence arrive to other nodes.

- Does a need to update messages to all the linked nodes for belief updating? for finding the most probable configuration?
- Does b need to update messages to all the linked nodes for belief updating? for finding the most probable configuration?

HMM Example



How would you use message-passing to calculate

• $\max_{x} p(x_1, ..., x_t | \mathbf{e}_t)$? (You'll obtain as a special case the Viterbi algorithm.)

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Belief Propagation Applications to Loopy Graphs

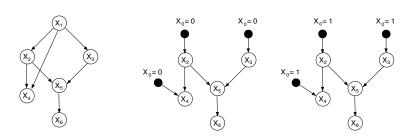
Outline

Belief Propagation

Applications to Loopy Graphs

Illustration of Conditioning

Example (Pearl, 1988): Instantiating variable X_1 renders the network singly connected.



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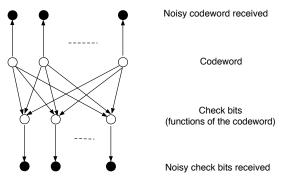
Belief Propagation Applications to Loopy Graphs

Further Reading

1. Judea Pearl. Probabilistic Reasoning in Intelligent Systems, Morgan Kaufmann, 1988. Chap. 5.

Turbo Decoding Example

Modified from McEliece et al., 1998:



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Belief Propagation Applications to Loopy Graphs

Details of Derivation for Eq. (1)

1. First we argue that $X_{T_{vu}}, u \in pa(v)$ are mutually independent. Abusing notation, for a sub-polytree T, we use T also for the set of nodes in T. Since G is singly connected, the subgraph $G_{An\left(\bigcup_{u\in pa(v)}T_{vu}\right)}$ consists of n=|pa(v)| disconnected components, $T_{vu}, u \in pa(v)$. For any two disjoint subsets $U_1, U_2 \subseteq pa(v)$, the set of nodes $\bigcup_{u \in U_1} T_{vu}$ and $\bigcup_{u \in U_2} T_{vu}$ are disconnected, implying that

$$X_{\bigcup_{u\in U_1}T_{vu}}\perp X_{\bigcup_{u\in U_2}T_{vu}}$$

for any disjoint subsets U_1, U_2 . This shows that $X_{T_{vu}}, u \in pa(v)$ are mutually independent, so

$$p(x_{T_{vu_1}},\ldots,x_{T_{vu_n}}) = \prod_{u \in pa(v)} p(x_{T_{vu}}).$$

2. Next, choosing any well-ordering such that all the nodes in T_{vu} , $u \in pa(v)$ have smaller numbers than v, we can argue by (DO) that

$$p(x_{v} | x_{T_{vu_1}}, \dots, x_{T_{vu_n}}) = p(x_{v} | x_{pa(v)}).$$

Combining this with the preceding equation, we have

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$$p(x_{T_{vu_1}}, \dots, x_{T_{vu_n}}, x_v) = \prod_{u \in pa(v)} p(x_{T_{vu}}) \cdot p(x_v \,|\, x_{pa(v)}).$$

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Details of Derivation for Eq. (1)

3. Finally, we consider $X_{T_{vw}}, w \in \operatorname{ch}(v)$. Since G is singly connected, from G^m we see that v separates nodes in $T_{vw}, w \in \operatorname{ch}(v)$ from nodes in $T_{vu}, u \in \operatorname{pa}(v)$. Therefore.

$$\{X_{T_{vw}}, w \in \mathsf{ch}(v)\} \perp \{X_{T_{vu}}, u \in \mathsf{pa}(v)\} \mid X_v.$$

Furthermore, removing the node v, the subgraph of G^m induced by T_{vw} , $w \in \operatorname{ch}(v)$ is disconnected and has $m = |\operatorname{ch}(v)|$ components, each corresponding to a T_{vw} . So arguing as in the first step, we have that given X_v , the variables $X_{T_{vv}}$, $w \in \operatorname{ch}(v)$ are mutually independent. This gives us Eq. (1):

$$p(x) = \prod_{u \in pa(v)} p(x_{T_{vu}}) \cdot p(x_v \,|\, x_{pa(v)}) \cdot \prod_{w \in ch(v)} p(x_{T_{vw}} \,|\, x_v).$$

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Belief Propagation Applications to Loopy Graphs

Details of Derivation for Eq. (2)

Using short-hand notation for probabilities of events (defined in Lec. 9), we have

$$\begin{aligned} p(x) \cdot \mathbf{e}(x) &= p(x \& \mathbf{e}), \\ p(x_{V} \mid x_{\mathsf{pa}(V)}) \cdot \mathbf{e}_{V}(x_{V}) &= p(x_{V} \& \mathbf{e}_{V} \mid x_{\mathsf{pa}(V)}), \\ p(x_{T_{Vu}}) \cdot \mathbf{e}_{T_{Vu}}(x_{T_{Vu}}) &= p(x_{T_{vu}} \& \mathbf{e}_{T_{vu}}), \\ p(x_{T_{vw}} \mid x_{V}) \cdot \mathbf{e}_{T_{vw}}(x_{T_{vw}}) &= p(x_{T_{vw}} \& \mathbf{e}_{T_{vw}} \mid x_{V}). \end{aligned}$$

So, we may write $P(X = x, \mathbf{e}) = p(x) \cdot \mathbf{e}(x)$ as

$$p(x \& \mathbf{e}) = \prod_{u \in pa(v)} p(x_{T_{vu}} \& \mathbf{e}_{T_{vu}}) \cdot p(x_v \& \mathbf{e}_v \, | \, x_{pa(v)}) \cdot \prod_{w \in ch(v)} p(x_{T_{vw}} \& \mathbf{e}_{T_{vw}} \, | \, x_v),$$

which is Eq. (2).

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Details of Derivation for Eq. (2)

Recall that the total evidence e has a factor form:

$$\mathbf{e}(x) = \prod_{v \in V} \ell_v(x_v).$$

For a given node v, we can also express e in terms of the pieces of evidence, e_v , $\mathbf{e}_{T_{vu}}, u \in \mathsf{pa}(v) \text{ and } \mathbf{e}_{T_{vw}}, w \in \mathsf{ch}(v) \text{ as}$

$$\mathbf{e}(x) = \Big(\prod_{u \in \mathsf{pa}(v)} \mathbf{e}_{\mathcal{T}_{vu}}(x_{\mathcal{T}_{vu}})\Big) \cdot \mathbf{e}_{v}(x_{v}) \cdot \prod_{w \in \mathsf{ch}(v)} \mathbf{e}_{\mathcal{T}_{vw}}(x_{\mathcal{T}_{vw}}),$$

where

$$e_{\mathcal{T}_{vu}}(x_{\mathcal{T}_{vu}}) = \prod_{v' \in \mathcal{T}_{vu}} \ell_{v'}(x_{v'}), \quad e_{v}(x_{v}) = \ell_{v}(x_{v}), \quad e_{\mathcal{T}_{vw}}(x_{\mathcal{T}_{vw}}) = \prod_{v' \in \mathcal{T}_{vw}} \ell_{v'}(x_{v'}).$$

We now combine each piece of evidence with the respective term in p(x), which by Eq. (1) is

$$p(x) = \prod_{u \in \mathsf{pa}(v)} p(x_{T_{vu}}) \cdot p(x_v \mid x_{\mathsf{pa}(v)}) \cdot \prod_{w \in \mathsf{ch}(v)} p(x_{T_{vw}} \mid x_v),$$

to obtain

$$p(x) \cdot \mathbf{e}(x) = \prod_{u \in \mathsf{pa}(v)} p(x_{T_{vu}}) \, \mathbf{e}_{T_{vu}}(x_{T_{vu}}) \cdot p(x_v \, | \, x_{\mathsf{pa}(v)}) \, \mathbf{e}_v(x_v) \cdot \prod_{w \in \mathsf{ch}(v)} p(x_{T_{vw}} \, | \, x_v) \mathbf{e}_{T_{vw}}(x_{T_{vw}}).$$

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Belief Propagation Applications to Loopy Graphs

Details of Derivation for Eq. (5)

We derive the expression for $p^*(\mathbf{e}_{T_{uv}}|x_u)$. Similar to the derivation of Eqs. (1)-(2),

$$p(x_{T_{uv}} \& e_{T_{uv}} | x_u) = \prod_{u' \in pa(v) \setminus \{u\}} p(x_{T_{vu'}} \& e_{T_{vu'}}) \cdot p(x_v \& e_v | x_{pa(v)}) \cdot \prod_{w \in ch(v)} p(x_{T_{vw}} \& e_{T_{vw}} | x_v).$$

Also,

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$$\max_{\mathsf{X}T_{\mathit{UV}}} \;\; \Leftrightarrow \;\; \max_{\mathsf{X}_{\mathit{V}}} \max_{\mathsf{X}_{\mathsf{pa}(\mathit{V}}) \backslash \left\{u\right\}} \max_{\mathsf{X}_{\mathit{T}_{\mathit{VU}}} \backslash \left\{u'\right\}} \max_{\mathsf{X}_{\mathit{T}_{\mathit{VW}}} \atop \mathsf{W} \in \mathsf{ch}(\mathit{V})} \max_{\mathsf{X}_{\mathit{T}_{\mathit{W}}} \atop \mathsf{W} \in \mathsf{ch}(\mathit{V})} \min_{\mathsf{X}_{\mathit{T}_{\mathit{W}}} \atop \mathsf{W} \in \mathsf{ch}(\mathsf{V})} \min_{\mathsf{X}_{\mathit{W}}} \min_{\mathsf{X}_{$$

Moving certain maximization operations inside the products, we obtain

$$p^*(\mathbf{e}_{\mathcal{T}_{uv}} \,|\, x_u) = \max_{x_v} \max_{x_{\mathsf{pa}(v) \setminus \{u\}}} p(x_v \& \mathbf{e}_v \,|\, x_{\mathsf{pa}(v)}) \cdot \prod_{u' \in \mathsf{pa}(v) \setminus \{u\}} p^*(x_{u'} \& \mathbf{e}_{\mathcal{T}_{vu'}}) \cdot \prod_{w \in \mathsf{ch}(v)} p^*(\mathbf{e}_{\mathcal{T}_{vw}} \,|\, x_v).$$

By the definitions of messages in slide 13, this is

$$p^*(e_{T_{uv}}|x_u) = \max_{x_v} \left(\max_{x_{\mathsf{pa}(v)\setminus\{u\}}} p(x_v|x_{\mathsf{pa}(v)}) \ell_v(x_v) \cdot \prod_{u'\in\mathsf{pa}(v)\setminus\{u\}} \pi^*_{u',v}(x_{u'}) \right) \cdot \prod_{w\in\mathsf{ch}(v)} \lambda^*_{w,v}(x_v).$$