## Bayesian Networks: Belief Propagation (Cont'd)

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# Outline

#### **Belief Propagation**

Review and Examples

Generalized Belief Propagation - Max-Product

Applications to Loopy Graphs

Announcement: The last exercise will be posted online soon.

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# Outline

#### **Belief Propagation**

#### Review and Examples

Generalized Belief Propagation – Max-Product

Applications to Loopy Graphs

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## Review of Last Lecture

We studied an algorithm for computing marginal posterior distributions:

- It works in singly connected networks, which are DAGs whose undirected versions are trees.
- It is suitable for parallel implementation.
- It is recursively derived by

(i) dividing the total evidence in pieces, according to the independence structure represented by the DAG, and then

(ii) incorporating evidence pieces in either the probability terms ( $\pi$ -messages) or the likelihood terms (conditional probability terms;  $\lambda$ -messages).

Queries answerable by the algorithm for a singly connected network:

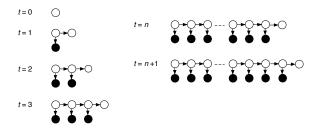
- $P(X = x | \mathbf{e})$  for a single x;
- $P(X_v = x_v | \mathbf{e})$  for all  $x_v$  and  $v \in V$ ;
- Most probable configurations,  $\arg \max_{x} p(x \& \mathbf{e})$ .

This can be related to finding global optimal solutions by distributed local computation. (Details are given today.)

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# Practice: Belief Propagation for HMM



Observation variables (black) are instantiated; latent variables (white) are  $X_1, X_2, \ldots$ . The total evidence at time t is  $\mathbf{e}_t$ . How would you use message-passing to calculate

•  $p(x_t | \mathbf{e}_t), \forall x_t$ ?

(You'll obtain as a special case the so-called forward algorithm.)

- $p(x_{t+1} | \mathbf{e}_t), \forall x_{t+1}$ ? (This is a prediction problem.)
- $p(x_k | \mathbf{e}_t), \forall x_k, k < t?$

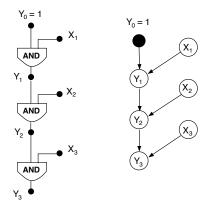
(You'll obtain as a special case the so-called backward algorithm.)

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### A Fault-Detection Example

A logic circuit for fault detection and its Bayesian network (Pearl 1988):



- $P(X_i = 1) = p_i,$   $P(X_i = 0) = 1 - p_i = q_i,$  $Y_i = Y_{i-1}$  AND  $X_i.$
- Y<sub>0</sub> = 1 always.
- X<sub>i</sub> is normal if X<sub>i</sub> = 1, and faulty if X<sub>i</sub> = 0.
- Normally all variables are on, and a failure occurs if Y<sub>3</sub> = 0.

#### Example: Belief Updating

Without observing any evidence, all the  $\pi$ -messages are prior probabilities:

$$\begin{aligned} \pi_{X_i,Y_i}(x_i) &= \begin{bmatrix} p_i \,,\, q_i \end{bmatrix}, \quad i = 1, 2, 3; \quad \pi_{Y_0,Y_1}(y_0) = \begin{bmatrix} 1 \,,\, 0 \end{bmatrix} \\ \pi_{Y_1,Y_2}(y_1) &= \begin{bmatrix} p_1 \,,\, q_1 \end{bmatrix}, \quad \pi_{Y_2,Y_3}(y_2) = \begin{bmatrix} p_1 p_2 \,,\, 1 - p_1 p_2 \end{bmatrix}, \end{aligned}$$

for  $x_i = 1, 0$  and  $y_i = 1, 0$ .

Suppose  $e : \{X_2 = 1, Y_3 = 0\}$  is received. Then,  $X_2$  updates its message to  $Y_2$  and  $Y_2$  updates its message to  $Y_3$ :

$$\pi_{X_2,Y_2}(x_2) = [p_2, 0], \quad \pi_{Y_2,Y_3}(y_2) = [p_1p_2, q_1p_2].$$

 $\lambda$ -messages starting from  $Y_3$  upwards are given by:

$$\begin{split} \lambda_{Y_3,X_3}(x_3) &= \begin{bmatrix} p_2 q_1 \,,\, p_2 \end{bmatrix}, & \lambda_{Y_3,Y_2}(y_2) = \begin{bmatrix} q_3 \,,\, 1 \end{bmatrix}; \\ \lambda_{Y_2,X_2}(x_2) &= \begin{bmatrix} p_1 q_3 + q_1 \,,\, p_1 + q_1 q_3 \end{bmatrix}, & \lambda_{Y_2,Y_1}(y_1) = \begin{bmatrix} p_2 q_3 \,,\, p_2 \end{bmatrix}; \\ \lambda_{Y_1,X_1}(x_1) &= \begin{bmatrix} p_2 q_3 \,,\, p_2 \end{bmatrix}. \end{split}$$

So

$$P(X_3 = 0 | \mathbf{e}) = \frac{q_3 p_2}{p_3 p_2 q_1 + q_3 p_2} = \frac{q_3}{p_3 q_1 + q_3} = \frac{q_3}{1 - p_1 p_3},$$
  

$$P(X_1 = 0 | \mathbf{e}) = \frac{q_1 p_2}{p_1 p_2 q_3 + q_1 p_2} = \frac{q_1}{p_1 q_3 + q_1} = \frac{q_1}{1 - p_1 p_3}.$$

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#### Example: Explanations based on Beliefs

If  $q_1 = 0.45$  and  $q_3 = 0.4$ , we obtain

$$P(X_1 = 0 | \mathbf{e}) = 0.672 > P(X_1 = 1 | \mathbf{e}) = 0.328,$$
  

$$P(X_3 = 0 | \mathbf{e}) = 0.597 > P(X_3 = 1 | \mathbf{e}) = 0.403.$$

Is  $I_1 = \{X_1 = 0, X_3 = 0\}$  the most probable explanation of **e**, however?

There are three possible explanations

$$I_1 = \{X_1 = 0, X_3 = 0\}, \quad I_2 = \{X_1 = 0, X_3 = 1\}, \quad I_3 = \{X_1 = 1, X_3 = 0\}.$$

Direct calculation shows

$$P(I_1 | \mathbf{e}) = rac{q_1 q_3}{1 - \rho_1 \rho_3}, \quad P(I_2 | \mathbf{e}) = rac{q_1 \rho_3}{1 - \rho_1 \rho_3}, \quad P(I_3 | \mathbf{e}) = rac{\rho_1 q_3}{1 - \rho_1 \rho_3}.$$

So, if  $0.5 > q_1 > q_2 > q_3$ , then based on the evidence,  $l_2$  is the most probable explanation, while  $l_1$  is the *least* probable explanation.

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#### Outline

#### **Belief Propagation**

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#### Generalized Belief Propagation - Max-Product

Applications to Loopy Graphs

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# Recall Notation for Singly Connected Networks

Consider a vertex v.

- $pa(v) = \{u_1, \ldots, u_n\}, ch(v) = \{w_1, \ldots, w_m\};$
- *T<sub>vu</sub>*, *u* ∈ pa(*v*): the sub-polytree containing the parent *u*, resulting from removing the edge (*u*, *v*);
- *T<sub>vw</sub>*, *w* ∈ ch(*v*): the sub-polytree containing the child *w*, resulting from removing the edge (*v*, *w*).

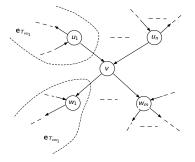
#### For a sub-polytree T, denote

- X<sub>T</sub>: the variables associated with nodes in T
- $\mathbf{e}_T$ : the partial evidence of  $X_T$

Divide the total evidence e in pieces:

- $\mathbf{e}_{T_{vu}}, u \in pa(v);$
- **e**<sub>v</sub>;
- $\mathbf{e}_{T_{vw}}, w \in ch(v).$

We want to solve:  $\max_{x} p(x \& e)$ .



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**Evidence structure**: We can express the joint distribution P(X) as

$$p(x) = \prod_{u \in pa(v)} p(x_{T_{vu}}) \cdot p(x_v | x_{pa(v)}) \cdot \prod_{w \in ch(v)} p(x_{T_{vw}} | x_v).$$
(1)

We then enter the evidence e (put each piece in a proper term) to obtain

$$p(x \& \mathbf{e}) = \prod_{u \in pa(v)} p(x_{T_{vu}} \& \mathbf{e}_{T_{vu}}) \cdot p(x_v \& \mathbf{e}_v | x_{pa(v)}) \cdot \prod_{w \in ch(v)} p(x_{T_{vw}} \& \mathbf{e}_{T_{vw}} | x_v).$$
(2)

(For a detailed derivation of Eqs. (1) and (2), see slides 24-27.)

**Max-Product**: To solve  $\max_{x} p(x \& e)$ , we consider maximizing with respect to groups of variables in the following order:

$$\max_{x} \Leftrightarrow \max_{x_{v}} \max_{x_{pa(v)}} \max_{x_{\tau vu_{1}} \setminus \{u_{1}\}} \cdots \max_{x_{\tau vu_{n}} \setminus \{u_{n}\}} \max_{x_{\tau vw_{1}}} \cdots \max_{x_{\tau vw_{m}}},$$

where  $T_{vu} \setminus \{u\}$  denotes the set of nodes in the sub-polytree  $T_{vu}$  except for  $\{u\}$ . Notice that for any two functions  $f_1(x), f_2(x, y)$ , we have the identity

$$\max_{x,y} \{f_1(x)f_2(x,y)\} = \max_x \{f_1(x) \cdot (\max_y f_2(x,y))\}.$$

We will similarly move certain maximization operations inside the products in Eq. (2) to obtain a desirable factor form of  $\max_{x} p(x \& e)$ .

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Consider first the maximization with respect to  $x_{T_{vw}}$ ,  $w \in ch(v)$ . We have

$$\max_{x_{T_{vw_1}}} \cdots \max_{x_{T_{vw_m}}} p(x \& \mathbf{e}) = \left(\prod_{u \in \mathsf{pa}(v)} p(x_{T_{vu}} \& \mathbf{e}_{T_{vu}})\right) \cdot p(x_v \& \mathbf{e}_v | x_{\mathsf{pa}(v)}) \cdot \prod_{w \in \mathsf{ch}(v)} \max_{x_{T_{vw}}} p(x_{T_{vw}} \& \mathbf{e}_{T_{vw}} | x_v).$$

Maximizing the above expression with respect to  $x_{\mathcal{T}_{vu_1}\setminus\{u_1\}},\ldots,x_{\mathcal{T}_{vu_n}\setminus\{u_n\}},$  we obtain

$$\Big(\prod_{u\in\mathsf{pa}(v)}\max_{x_{\mathcal{T}_{vu}\setminus\{u\}}}p(x_{\mathcal{T}_{vu}}\&\mathbf{e}_{\mathcal{T}_{vu}})\Big)\cdot p(x_v\&\mathbf{e}_v\,|\,x_{\mathsf{pa}(v)})\cdot\prod_{w\in\mathsf{ch}(v)}\max_{x_{\mathcal{T}_{vw}}}p(x_{\mathcal{T}_{vw}}\&\mathbf{e}_{\mathcal{T}_{vw}}\,|\,x_v).$$

Define

$$p^{*}(x_{u} \& \mathbf{e}_{T_{vu}}) = \max_{x_{T_{vu} \setminus \{u\}}} p(x_{T_{vu}} \& \mathbf{e}_{T_{vu}}), \qquad p^{*}(\mathbf{e}_{T_{vw}} | x_{v}) = \max_{x_{T_{vw}}} p(x_{T_{vw}}, \mathbf{e}_{T_{vw}} | x_{v}).$$
(3)

We obtain

$$\max_{x} p(x \& \mathbf{e}) = \max_{x_{v}} \left( \max_{x_{pa(v)}} \prod_{u \in pa(v)} p^{*}(x_{u} \& \mathbf{e}_{T_{vu}}) \cdot p(x_{v} \& \mathbf{e}_{v} | x_{pa(v)}) \right) \cdot \prod_{w \in ch(v)} p^{*}(\mathbf{e}_{T_{vw}} | x_{v}).$$

We will call the expression inside 'max  $x_v$ ' the max-margin of  $X_v$ , denoted  $p^*(x_v \& \mathbf{e})$ .

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Thus we obtain

$$\max_{x} p(x \& \mathbf{e}) = \max_{x_v} p^*(x_v \& \mathbf{e})$$

where

$$p^{*}(x_{v} \& \mathbf{e}) = \left(\max_{x_{\mathsf{pa}(v)}} \prod_{u \in \mathsf{pa}(v)} p^{*}(x_{u} \& \mathbf{e}_{T_{vu}}) \cdot p(x_{v} \& \mathbf{e}_{v} \mid x_{\mathsf{pa}(v)})\right) \cdot \prod_{w \in \mathsf{ch}(v)} p^{*}(\mathbf{e}_{T_{vw}} \mid x_{v}).$$
(4)

If v can receive messages

•  $\pi^*_{u,v}$  from all parents, where

$$\pi^*_{u,v}(x_u) = \boldsymbol{p}^*(x_u \& \mathbf{e}_{T_{vu}}), \quad \forall x_u,$$

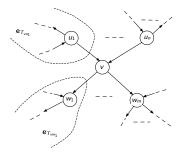
•  $\lambda_{w,v}^*$  from all children, where  $\lambda_{w,v}^*(x_v) = p^*(\mathbf{e}_{T_{vw}} | x_v), \quad \forall x_v,$ 

then v can calculate its max-margin

$$p^*(x_v \& \mathbf{e}), \forall x_v,$$

and from which

$$\max_{x_v} p^*(x_v \& \mathbf{e}) = \max_{x} p(x \& \mathbf{e}).$$



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# Meanings of the Messages and Max-Margin

- $p^*(x_u \& \mathbf{e}_{T_{vu}})$ : If  $X_u = x_u$ , there exists some configuration of  $x_{T_{vu}}$  which best explains the partial evidence  $\mathbf{e}_{T_{vu}}$  with this probability.
- $p^*(\mathbf{e}_{T_{vw}} | x_v)$ : If  $X_v = x_v$ , there exists some configuration of  $x_{T_{vw}}$  which best explains the partial evidence  $\mathbf{e}_{T_{vw}}$  conditional on  $X_v$ , with this probability.
- p\*(x<sub>v</sub> & e): If X<sub>v</sub> = x<sub>v</sub>, there exists some configuration of the rest of the variables which best explains the evidence e with this probability.

How to obtain  $x^* \in \arg \max_x p(x \& \mathbf{e})$ ?

- If x<sup>\*</sup> is unique, then the solutions x<sup>\*</sup><sub>v</sub> ∈ arg max<sub>xv</sub> p<sup>\*</sup>(x<sub>v</sub> & e) for all v form the global optimal solution (best explanation) x<sup>\*</sup>.
- If x<sup>\*</sup> is not unique, then we will need to trace out a solution from some node v. This shows that for each x<sup>\*</sup><sub>v</sub> ∈ arg max<sub>x<sub>v</sub></sub> p<sup>\*</sup>(x<sub>v</sub> & e), v should record the corresponding best values x<sup>\*</sup><sub>pa(v)</sub> of the parents in the maximization problem defining p<sup>\*</sup>(x<sub>v</sub> & e) [Eq. (4)]:

$$\max_{x_{\mathsf{pa}(v)}} \prod_{u \in \mathsf{pa}(v)} p^*(x_u \& \mathbf{e}_{T_{vu}}) \cdot p(x_v^* \& \mathbf{e}_v | x_{\mathsf{pa}(v)}).$$

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Now we only need to check if v can compose messages for its parents and children to calculate their max-margins.

A parent u needs p<sup>\*</sup>(e<sub>Tuv</sub> | x<sub>u</sub>) for all x<sub>u</sub> based on the partial evidence e<sub>Tuv</sub> from the sub-polytree on v's side with respect to u:

$$p^*(\mathbf{e}_{T_{uv}} | x_u) = \max_{x_{T_{uv}}} p(x_{T_{uv}} \& \mathbf{e}_{T_{uv}} | x_u).$$

Indeed it is given by

$$p^{*}(\mathbf{e}_{T_{uv}} | x_{u}) = \max_{x_{v}} \left\{ \left( \max_{x_{pa(v) \setminus \{u\}}} p(x_{v} \& \mathbf{e}_{v} | x_{pa(v)}) \cdot \prod_{u' \in pa(v) \setminus \{u\}} p^{*}(x_{u'} \& \mathbf{e}_{T_{vu'}}) \right) \\ \cdot \prod_{w \in ch(v)} p^{*}(\mathbf{e}_{T_{vw}} | x_{v}) \right\}$$
(5)
$$= \max_{x_{v}} \left\{ \left( \max_{x_{pa(v) \setminus \{u\}}} p(x_{v} | x_{pa(v)}) \ell_{v}(x_{v}) \cdot \prod_{u' \in pa(v) \setminus \{u\}} \pi^{*}_{u',v}(x_{u'}) \right) \\ \cdot \prod_{w \in ch(v)} \lambda^{*}_{w,v}(x_{v}) \right\}.$$

So this is the message  $\lambda_{v,u}^*(x_u)$  that v needs to send to u; it can be composed once v receives the messages from all the other linked nodes.

(For the details of derivation of Eq. (5), see slide 28.)

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A child w needs p\*(xv & eTwv) for all xv, which incorporates the partial evidence eTwv from the sub-polytree on v's side with respect to w:

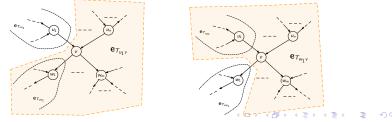
$$p^*(x_v \& \mathbf{e}_{\mathcal{T}_{WV}}) = \max_{x_{\mathcal{T}_{WV} \setminus \{v\}}} p(x_{\mathcal{T}_{WV}} \& \mathbf{e}_{\mathcal{T}_{WV}}).$$

By a similar calculation as in the previous slides, one can show that

$$p^*(x_v \& \mathbf{e}_{T_{wv}}) = \left(\max_{x_{\mathsf{pa}(v)}} p(x_v | x_{\mathsf{pa}(v)}) \ell_v(x_v) \cdot \prod_{u \in \mathsf{pa}(v)} \pi^*_{u,v}(x_u)\right)$$
$$\cdot \prod_{w' \in \mathsf{ch}(v) \setminus \{w\}} \lambda^*_{w',v}(x_v).$$

So this is the message  $\pi^*_{v,w}(x_v)$  that v needs to send to w; it can be composed once v receives the messages from all the other linked nodes.

Illustration of the partial evidence that the messages  $\lambda_{v,u}^*(x_u)$ ,  $\pi_{v,w}^*(x_v)$  carry:



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Bayesian Networks: Belief Propagation (Cont'd)

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# Max-Product Message Passing Algorithm Summary Each node v

• sends to each *u* of its parents

$$\begin{split} \lambda_{\nu,u}^*(x_u) &= \max_{x_\nu} \left\{ \max_{\substack{x_{\mathsf{pa}(\nu) \setminus \{u\}}} p(x_\nu \,|\, x_{\mathsf{pa}(\nu)}) \,\ell_\nu(x_\nu) \cdot \prod_{u' \in \mathsf{pa}(\nu) \setminus \{u\}} \pi_{u',\nu}^*(x_{u'}) \right. \\ &\left. \cdot \prod_{w \in \mathsf{ch}(\nu)} \lambda_{w,\nu}^*(x_\nu) \right\}, \qquad \forall x_u; \end{split}$$

sends to each w of its children

$$\pi^*_{v,w}(x_v) = \prod_{w' \in \mathsf{ch}(v) \setminus \{w\}} \lambda^*_{w',v}(x_v) \cdot \max_{x_{\mathsf{pa}(v)}} p(x_v \,|\, x_{\mathsf{pa}(v)}) \,\ell_v(x_v) \cdot \prod_{u \in \mathsf{pa}(v)} \pi^*_{u,v}(x_u), \quad \forall x_v;$$

· when receiving all messages from parents and children, calculates

$$p^*(x_v \& \mathbf{e}) = \Big(\prod_{w \in ch(v)} \lambda^*_{w,v}(x_v)\Big) \cdot \max_{\mathsf{x}_{\mathsf{pa}(v)}} \prod_{u \in \mathsf{pa}(v)} \pi^*_{u,v}(x_u) \cdot p(x_v \mid \mathsf{x}_{\mathsf{pa}(v)}) \ell_v(x_v), \quad \forall x_v.$$

This is identical to the algorithm in the last lecture, with maximization replacing the summation.

To obtain a  $x^* \in \arg \max_x p(x \& \mathbf{e})$ :

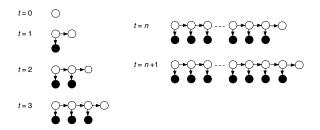
- If  $x^*$  is unique, then it is given by  $x_v^* \in \arg \max_{x_v} p^*(x_v \& e)$  for all v.
- If x\* is not unique, we can start from any node v, fix xv and then trace out the solutions at other nodes.

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## HMM Example



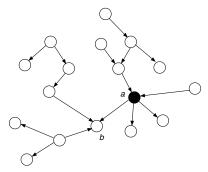
How would you use message-passing to calculate

•  $\max_{x} p(x_1, ..., x_t | \mathbf{e}_t)$ ?

(You'll obtain as a special case the Viterbi algorithm.)

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## Discussion on Differences between Algorithms



Node a is instantiated. Node b never receives any evidence. New pieces of evidence arrive to other nodes.

- Does *a* need to update messages to all the linked nodes for belief updating? for finding the most probable configuration?
- Does *b* need to update messages to all the linked nodes for belief updating? for finding the most probable configuration?

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# Outline

#### **Belief Propagation**

Review and Examples

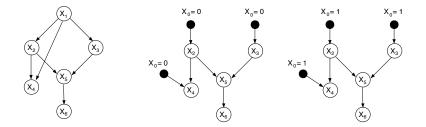
Generalized Belief Propagation – Max-Product

Applications to Loopy Graphs

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# Illustration of Conditioning

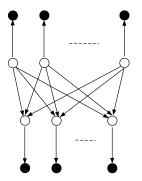
Example (Pearl, 1988): Instantiating variable  $X_1$  renders the network singly connected.



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## Turbo Decoding Example

Modified from McEliece et al., 1998:



Noisy codeword received

Codeword

Check bits (functions of the codeword)

Noisy check bits received

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## Further Reading

1. Judea Pearl. *Probabilistic Reasoning in Intelligent Systems*, Morgan Kaufmann, 1988. Chap. 5.

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# Details of Derivation for Eq. (1)

1. First we argue that  $X_{T_{vu}}, u \in pa(v)$  are mutually independent. Abusing notation, for a sub-polytree T, we use T also for the set of nodes in T. Since G is singly connected, the subgraph  $G_{An}(\bigcup_{u \in pa(v)} T_{vu})$  consists of n = |pa(v)| disconnected components,  $T_{vu}, u \in pa(v)$ . For any two disjoint subsets  $U_1, U_2 \subseteq pa(v)$ , the set of nodes  $\bigcup_{u \in U_1} T_{vu}$  and  $\bigcup_{u \in U_2} T_{vu}$  are disconnected, implying that

$$X_{\bigcup_{u\in U_1}T_{vu}}\perp X_{\bigcup_{u\in U_2}T_{vu}}$$

for any disjoint subsets  $U_1, U_2$ . This shows that  $X_{T_{vu}}, u \in pa(v)$  are mutually independent, so

$$p(x_{T_{vu_1}},\ldots,x_{T_{vu_n}})=\prod_{u\in pa(v)}p(x_{T_{vu}}).$$

2. Next, choosing any well-ordering such that all the nodes in  $T_{vu}$ ,  $u \in pa(v)$  have smaller numbers than v, we can argue by (DO) that

$$p(x_v | x_{T_{vu_1}}, \ldots, x_{T_{vu_n}}) = p(x_v | x_{pa(v)}).$$

Combining this with the preceding equation, we have

$$p(x_{T_{vu_1}},\ldots,x_{T_{vu_n}},x_v) = \prod_{u \in \mathsf{pa}(v)} p(x_{T_{vu}}) \cdot p(x_v | x_{\mathsf{pa}(v)}).$$

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Bayesian Networks: Belief Propagation (Cont'd)

### Details of Derivation for Eq. (1)

3. Finally, we consider  $X_{T_{vw}}, w \in ch(v)$ . Since G is singly connected, from  $G^m$  we see that v separates nodes in  $T_{vw}, w \in ch(v)$  from nodes in  $T_{vu}, u \in pa(v)$ . Therefore,

$$\{X_{\mathcal{T}_{vw}}, w \in \mathsf{ch}(v)\} \perp \{X_{\mathcal{T}_{vu}}, u \in \mathsf{pa}(v)\} \mid X_v.$$

Furthermore, removing the node v, the subgraph of  $G^m$  induced by  $T_{vw}, w \in ch(v)$  is disconnected and has m = |ch(v)| components, each corresponding to a  $T_{vw}$ . So arguing as in the first step, we have that given  $X_v$ , the variables  $X_{T_{vw}}, w \in ch(v)$  are mutually independent. This gives us Eq. (1):

$$p(x) = \prod_{u \in \mathsf{pa}(v)} p(x_{T_{vu}}) \cdot p(x_v | x_{\mathsf{pa}(v)}) \cdot \prod_{w \in \mathsf{ch}(v)} p(x_{T_{vw}} | x_v).$$

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# Details of Derivation for Eq. (2)

Recall that the total evidence e has a factor form:

$$\mathbf{e}(x)=\prod_{\nu\in V}\ell_{\nu}(x_{\nu}).$$

For a given node v, we can also express e in terms of the pieces of evidence,  $\mathbf{e}_{v, v}$ ,  $\mathbf{e}_{T_{vu}}$ ,  $u \in \operatorname{pa}(v)$  and  $\mathbf{e}_{T_{vw}}$ ,  $w \in \operatorname{ch}(v)$  as

$$\mathbf{e}(x) = \left(\prod_{u \in \mathsf{pa}(v)} \mathbf{e}_{T_{vu}}(x_{T_{vu}})\right) \cdot \mathbf{e}_{v}(x_{v}) \cdot \prod_{w \in \mathsf{ch}(v)} \mathbf{e}_{T_{vw}}(x_{T_{vw}})$$

where

$$\mathbf{e}_{T_{vu}}(x_{T_{vu}}) = \prod_{v' \in T_{vu}} \ell_{v'}(x_{v'}), \quad \mathbf{e}_{v}(x_{v}) = \ell_{v}(x_{v}), \quad \mathbf{e}_{T_{vw}}(x_{T_{vw}}) = \prod_{v' \in T_{vw}} \ell_{v'}(x_{v'}).$$

We now combine each piece of evidence with the respective term in p(x), which by Eq. (1) is

$$p(x) = \prod_{u \in \mathsf{pa}(v)} p(x_{\mathcal{T}_{vu}}) \cdot p(x_v \mid x_{\mathsf{pa}(v)}) \cdot \prod_{w \in \mathsf{ch}(v)} p(x_{\mathcal{T}_{vw}} \mid x_v),$$

to obtain

$$p(x) \cdot \mathbf{e}(x) = \prod_{u \in pa(v)} p(x_{T_{vu}}) \mathbf{e}_{T_{vu}}(x_{T_{vu}}) \cdot p(x_v | x_{pa(v)}) \mathbf{e}_v(x_v) \cdot \prod_{w \in ch(v)} p(x_{T_{vw}} | x_v) \mathbf{e}_{T_{vw}}(x_{T_{vw}}).$$

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Belief Propagation Applications to Loopy Graphs

# Details of Derivation for Eq. (2)

Using short-hand notation for probabilities of events (defined in Lec. 9), we have

$$p(x) \cdot \mathbf{e}(x) = p(x \& \mathbf{e}),$$

$$p(x_{V} | x_{pa(v)}) \cdot \mathbf{e}_{v}(x_{v}) = p(x_{v} \& \mathbf{e}_{v} | x_{pa(v)}),$$

$$p(x_{T_{vu}}) \cdot \mathbf{e}_{T_{vu}}(x_{T_{vu}}) = p(x_{T_{vu}} \& \mathbf{e}_{T_{vu}}),$$

$$p(x_{T_{vw}} | x_{v}) \cdot \mathbf{e}_{T_{vw}}(x_{T_{vw}}) = p(x_{T_{vw}} \& \mathbf{e}_{T_{vw}} | x_{v}).$$

So, we may write  $P(X = x, \mathbf{e}) = p(x) \cdot \mathbf{e}(x)$  as

$$p(x \& \mathbf{e}) = \prod_{u \in \mathsf{pa}(v)} p(x_{T_{vu}} \& \mathbf{e}_{T_{vu}}) \cdot p(x_v \& \mathbf{e}_v | x_{\mathsf{pa}(v)}) \cdot \prod_{w \in \mathsf{ch}(v)} p(x_{T_{vw}} \& \mathbf{e}_{T_{vw}} | x_v),$$

which is Eq. (2).

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# Details of Derivation for Eq. (5)

We derive the expression for  $p^*(\mathbf{e}_{T_{uv}}|x_u)$ . Similar to the derivation of Eqs. (1)-(2),

$$p(x_{T_{uv}} \& \mathbf{e}_{T_{uv}} | x_u) = \prod_{u' \in pa(v) \setminus \{u\}} p(x_{T_{vu'}} \& \mathbf{e}_{T_{vu'}}) \cdot p(x_v \& \mathbf{e}_v | x_{pa(v)})$$
$$\cdot \prod_{w \in ch(v)} p(x_{T_{vw}} \& \mathbf{e}_{T_{vw}} | x_v).$$

Also,

$$\begin{array}{cccc} \max_{x_{\mathcal{T}_{uv}}} & \Leftrightarrow & \max_{x_v} \max_{x_{\mathsf{pa}(v) \setminus \{u\}}} \max_{v_{\mathcal{T}_{vu'} \setminus \{u'\}}} \max_{v_{\mathcal{T}_{vw}}} & x_{\mathcal{T}_{vw}} \\ & u' \in \mathsf{pa}(v) & w \in \mathsf{ch}(v) \end{array}$$

Moving certain maximization operations inside the products, we obtain

$$p^*(\mathbf{e}_{T_{uv}} | x_u) = \max_{x_v} \max_{x_{\mathsf{pa}(v) \setminus \{u\}}} p(x_v \& \mathbf{e}_v | x_{\mathsf{pa}(v)}) \cdot \prod_{u' \in \mathsf{pa}(v) \setminus \{u\}} p^*(x_{u'} \& \mathbf{e}_{T_{vu'}})$$
$$\cdot \prod_{w \in \mathsf{ch}(v)} p^*(\mathbf{e}_{T_{vw}} | x_v).$$

By the definitions of messages in slide 13, this is

$$p^{*}(\mathbf{e}_{T_{uv}} | x_{u}) = \max_{x_{v}} \left( \max_{x_{\mathsf{pa}(v) \setminus \{u\}}} p(x_{v} | x_{\mathsf{pa}(v)}) \ell_{v}(x_{v}) \cdot \prod_{u' \in \mathsf{pa}(v) \setminus \{u\}} \pi^{*}_{u',v}(x_{u'}) \right)$$
$$\cdot \prod_{w \in \mathsf{ch}(v)} \lambda^{*}_{w,v}(x_{v}).$$

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