

Ex. 1

$$\begin{aligned} 1. p_{\theta}(X) &= \int p_{\theta}(x, s) ds = \int \prod_{t=1}^T p_{\theta}(x_t | s_t) p_{\theta}(s_t) ds = \\ &= \prod_{t=1}^T \int p_{\theta}(x_t | s_t) p_{\theta}(s_t) ds_t = \prod_{t=1}^T p_{\theta}(x_t) =: \prod_{t=1}^T p(x_t; \theta) \end{aligned}$$

$$\begin{aligned} 2. J(\theta) &= \int \log(p(x, s; \theta)) p(s | x; \theta_{k-1}) ds \\ &= \int \log\left(\frac{\prod_{t=1}^T p(x_t | s_t; \theta) \cdot p(s_t; \theta)}{p(x, s; \theta_{k-1})}\right) ds_1 \dots ds_T \\ &= \int \sum_{t=1}^T (\log p(x_t, s_t; \theta)) \cdot \frac{\prod_{t=1}^T p(x_t | s_t; \theta_{k-1}) \cdot p(s_t; \theta_{k-1})}{\prod_{t=1}^T p(x_t; \theta_{k-1})} ds_1 \dots ds_T \\ &= \int \sum_{t=1}^T (\log p(x_t, s_t; \theta)) \cdot \frac{\prod_{t=1}^T \frac{p(x_t | s_t; \theta_{k-1}) \cdot p(s_t; \theta_{k-1})}{p(x_t; \theta_{k-1})}}{p(s_t | x_t; \theta_{k-1})} ds_1 \dots ds_T \\ &= \sum_{t=1}^T \left\{ \int \log p(x_t, s_t; \theta) \cdot \prod_{t=1}^T p(s_t | x_t; \theta_{k-1}) ds_1 \dots ds_T \right\} \\ &= \sum_{t=1}^T \left\{ \underbrace{\int \prod_{\tau=1}^T p(s_{\tau} | x_{\tau}; \theta_{k-1}) ds_{\tau}}_{\prod_{\tau \neq t} \int p(s_{\tau} | x_{\tau}; \theta_{k-1}) ds_{\tau}} \cdot \int \log p(x_t, s_t; \theta) \cdot p(s_t | x_t; \theta_{k-1}) ds_t \right\} \\ &= \sum_{t=1}^T \int \log p(x_t, s_t; \theta) \cdot p(s_t | x_t; \theta_{k-1}) ds_t \end{aligned}$$

For discrete variables the calculation is analogue, when replacing the integral over S with a sum over S .

This expression has a nice interpretation: $\log p(x_t, s_t; \theta)$, which would give the complete log-likelihood when summed-up, is replaced by an estimate, namely the conditional expectation.

$$3. p(r(t) | x(t); \Theta) = \frac{p(r(t), x(t); \Theta)}{p(x(t); \Theta)} =$$

↑
short notation for
all parameters
 $\mu_c, \sigma_c, c=1, \dots, C$

$$= \frac{p(r(t), x(t); \Theta)}{\sum_{r(t)=1}^C p(r(t), x(t); \Theta)} = \frac{q_{tc}}{\sum_{c=1}^C q_{tc}} = q_{tc}^*$$

Ex. 2

For 1. and 2. $x_i = u_i$, $x = u$.

$$1. E(x_i) = \sum_{x_i=0,1} x_i p(x_i) = 0 \cdot \mu_i^0 (1-\mu_i)^1 + 1 \cdot \mu_i^1 (1-\mu_i)^0 = \mu_i$$

$$\begin{aligned} V(x_i) &= E(x_i^2) - E(x_i)^2 = \sum_{x_i=0,1} x_i^2 p(x_i) - \mu_i^2 = 0^2 \cdot \mu_i^0 (1-\mu_i)^1 + 1^2 \mu_i^1 (1-\mu_i)^0 - \mu_i^2 \\ &= \mu_i - \mu_i^2 = \mu_i (1-\mu_i) \end{aligned}$$

$$2. E(x) = E \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} E(x_1) \\ \vdots \\ E(x_n) \end{pmatrix} = \begin{pmatrix} \mu_1 \\ \vdots \\ \mu_n \end{pmatrix} = \mu$$

$$\text{Cov}(x_i, x_j) = E(x_i x_j) - E(x_i) E(x_j) = E(x_i) E(x_j) - E(x_i) E(x_j) = 0$$

x_i, x_j
indep.

$$\text{COV}(x) = \begin{pmatrix} V(x_1) & \text{Cov}(x_1, x_2) & & \\ \text{Cov}(x_1, x_2) & V(x_2) & & \\ & & \ddots & \\ & & & V(x_n) \end{pmatrix} = \text{diag}(\mu_i (1-\mu_i)) =: D_c$$

$$\begin{aligned} 3. E(x) &= \sum_{x \in \{0,1\}^n} x q(x) = \sum_{x \in \{0,1\}^n} x \sum_{c=1}^c \pi_c \rho(x; \mu_c) = \sum_{c=1}^c \pi_c \underbrace{\sum_{x \in \{0,1\}^n} x \rho(x; \mu_c)}_{= \mu_c \text{ (from 2.)}} \\ &= \sum_{c=1}^c \pi_c \mu_c \end{aligned}$$

First note that

$$\begin{aligned} q(x_i) &= \sum_{\substack{x_k \\ k=1, \dots, n \\ k \neq i}} q(x_1, \dots, x_n) = \sum_{\substack{x_k \\ k=1, \dots, n \\ k \neq i}} \sum_{c=1}^c \pi_c \rho(x; \mu_c) = \\ &= \sum_{c=1}^c \pi_c \underbrace{\sum_{\substack{x_k \\ k=1, \dots, n \\ k \neq i}} \rho(x; \mu_c)}_{\rho(x_i; \mu_c)} = \sum_{c=1}^c \pi_c \cdot \rho(x_i; \mu_c) \end{aligned}$$

$$\begin{aligned} E(x_i^2) &= \sum_{x_i=0}^1 x_i^2 q(x_i) = \sum_{x_i=0}^1 x_i^2 \sum_{c=1}^c \pi_c \rho(x_i; \mu_c) = \sum_{c=1}^c \pi_c \underbrace{\sum_{x_i=0}^1 x_i^2 \mu_{ci}^{x_i} (1-\mu_{ci})^{(1-x_i)}}_{\mu_{ci}} \\ &= \sum_{c=1}^c \pi_c \mu_{ci} \end{aligned}$$

$$\begin{aligned}
E(x_i x_j) &= \sum_{x_i=0}^1 \sum_{x_j=0}^1 x_i x_j \sum_{c=1}^C \pi_c \underbrace{p(x_i, x_j; \mu_c)}_{p(x_i; \mu_c) \cdot p(x_j; \mu_c)} \\
&= \sum_{c=1}^C \pi_c \sum_{x_i=0}^1 \sum_{x_j=0}^1 x_i p(x_i; \mu_c) \cdot x_j p(x_j; \mu_c) \\
&= \sum_{c=1}^C \pi_c \underbrace{\left(\sum_{x_i=0}^1 x_i p(x_i; \mu_c) \right)}_{\mu_{ci}} \underbrace{\left(\sum_{x_j=0}^1 x_j p(x_j; \mu_c) \right)}_{\mu_{cj}} \\
&= \sum_{c=1}^C \pi_c \mu_{ci} \mu_{cj}
\end{aligned}$$

$$\text{Cov}(x) = E(x x^T) - E(x) E(x)^T$$

$$= \sum_{c=1}^C \pi_c \begin{pmatrix} \mu_{c1} & \mu_{c1}\mu_{c2} & \dots \\ \mu_{c1}\mu_{c2} & \mu_{c2} & \dots \\ \vdots & \vdots & \ddots \\ \mu_{cn} & \dots & \dots \end{pmatrix} - \left\{ \sum \pi_c \begin{pmatrix} \mu_{c1} \\ \vdots \\ \mu_{cn} \end{pmatrix} \right\} \cdot \left\{ \sum \pi_c (\mu_{c1} \dots \mu_{cn}) \right\}$$

From this we can see that the covariance matrix is not diagonal, that shows that the mixture distribution is a "richer" distribution than a single multivariate Bernoulli distribution.

$$\begin{aligned}
4. \log\left(\prod_{t=1}^T q(x(t); \mu_c, \pi_c, c=1, \dots, C)\right) &= \sum_{t=1}^T \log q(x(t); \mu_c, \pi_c) = \\
&= \sum_{t=1}^T \log \sum_{c=1}^C \pi_c p(x(t); \mu_c) \\
&= \sum_{t=1}^T \log \left\{ \sum_{c=1}^C \pi_c \prod_{i=1}^n p(x_i(t); \mu_{ci}) \right\}
\end{aligned}$$

$$\begin{aligned}
5. \log\left(\prod_{t=1}^T q(x(t), \lambda(t); \mu_{\lambda(t)})\right) &= \sum_{t=1}^T \log (q(x(t), \lambda(t); \mu_{\lambda(t)})) \\
&= \sum_{t=1}^T \log \left\{ \pi_{\lambda(t)} p(x(t); \mu_{\lambda(t)}) \right\} = \sum_{t=1}^T \left\{ \log \pi_{\lambda(t)} + \log \prod_{i=1}^n \underbrace{p(x_i(t); \mu_{\lambda(t), i})}_{\substack{x_i(t) \\ \mu_{\lambda(t), i}} \cdot (1 - \mu_{\lambda(t), i})^{(1-x_i(t))}} \right\} \\
&= \sum_{t=1}^T \log \pi_{\lambda(t)} + \sum_{t=1}^T \sum_{i=1}^n \left\{ x_i(t) \log \mu_{\lambda(t), i} + (1 - x_i(t)) \log (1 - \mu_{\lambda(t), i}) \right\} =: \ell
\end{aligned}$$

$$6. q(\lambda(t) = c | x(t)) = \frac{q(x(t), \lambda(t) = c)}{q(x(t))} = \frac{\pi_{\lambda(t)} p(x(t); \mu_{\lambda(t)})}{\sum_{c=1}^C q(x(t), \lambda(t) = c)}$$

$$= \frac{\overset{\pi_c}{\pi_{\lambda(t)}} p(x(t); \overset{\mu_c}{\mu_{\lambda(t)}})}{\sum_{k=1}^C \pi_k p(x(t); \mu_k)}$$

(This is equivalent to Eq. 10.16 in the lecture handout for the Gaussian mixture!)

$$7. E(\ell(\mu_c, \pi_c)) \stackrel{\text{math \& . 1}}{=} \sum_{t=1}^T \sum_{c=1}^C \underbrace{q(\lambda(t) = c | x(t))}_{q_{tc}^*} \cdot \log(q(x(t), \lambda(t); \mu_{\lambda(t)}))$$

$$= \sum_{c=1}^C \sum_{t=1}^T q_{tc}^* \cdot \log \pi_c + \sum_{c=1}^C \sum_{t=1}^T \sum_{i=1}^n q_{tc}^* \cdot (x_i(t) \log \mu_{ci} + (1 - x_i(t)) \log(1 - \mu_{ci}))$$

=:]

$$8. \frac{\partial J}{\partial \mu_{ci}} = 0 + \sum_{t=1}^T q_{tc}^* \left(x_i(t) \cdot \frac{1}{\mu_{ci}} - (1 - x_i(t)) \frac{1}{1 - \mu_{ci}} \right)$$

$$= \frac{1}{\mu_{ci}} \sum_{t=1}^T q_{tc}^* x_i(t) - \frac{1}{1 - \mu_{ci}} \sum_{t=1}^T q_{tc}^* (1 - x_i(t)) \stackrel{!}{=} 0$$

$$\Rightarrow (1 - \mu_{ci}) \sum_{t=1}^T q_{tc}^* x_i(t) = \mu_{ci} \left\{ \sum_{t=1}^T q_{tc}^* - \sum_{t=1}^T q_{tc}^* x_i(t) \right\}$$

$$\sum_{t=1}^T q_{tc}^* x_i(t) - \mu_{ci} \sum_{t=1}^T q_{tc}^* x_i(t) = \mu_{ci} \sum_{t=1}^T q_{tc}^* - \mu_{ci} \sum_{t=1}^T q_{tc}^* x_i(t)$$

$$\Rightarrow \mu_{ci} = \frac{\sum_{t=1}^T q_{tc}^* x_i(t)}{\sum_{t=1}^T q_{tc}^*}$$

use $N_c := \sum_{t=1}^T q_{tc}^*$ and we get $\mu_{ci} = \frac{1}{N_c} \sum_{t=1}^T q_{tc}^* x_i(t)$

$$\Rightarrow \mu_c = \frac{1}{N_c} \sum_{t=1}^T q_{tc}^* x(t)$$

(This is the same update rule as for Gaussian mixtures, compare Eq. 10.17)

$$9. \tilde{J} = J + \lambda \left(1 - \sum_{k=1}^c \pi_k \right)$$

$$\frac{\partial \tilde{J}}{\partial \pi_k} = \underbrace{\sum_{t=1}^T q_{tk}^*}_{N_k} \frac{1}{\pi_k} - \lambda = \frac{N_k}{\pi_k} - \lambda \stackrel{!}{=} 0$$

$$\Rightarrow \pi_k = \frac{N_k}{\lambda}$$

use the constraint to calculate λ :

$$1 = \sum_{k=1}^c \pi_k = \sum_{k=1}^c \frac{N_k}{\lambda} = \frac{1}{\lambda} \sum_{k=1}^c N_k$$

$$\Rightarrow \lambda = \sum_{k=1}^c N_k = \sum_{k=1}^c \sum_{t=1}^T q_{tk}^* = \sum_{t=1}^T \sum_{k=1}^c \frac{\pi_k \rho(x(t); \mu_k)}{\sum_{l=1}^c \pi_l \rho(x(t); \mu_l)}$$

$$= \sum_{t=1}^T \frac{\sum_{k=1}^c \pi_k \rho(x(t); \mu_k)}{\sum_{l=1}^c \pi_l \rho(x(t); \mu_l)} = \sum_{t=1}^T 1 = T$$

$$\Rightarrow \boxed{\pi_k = \frac{N_k}{T}}$$

(This is the same as the update rule for the Gaussian mixture in Eq. 10.19)