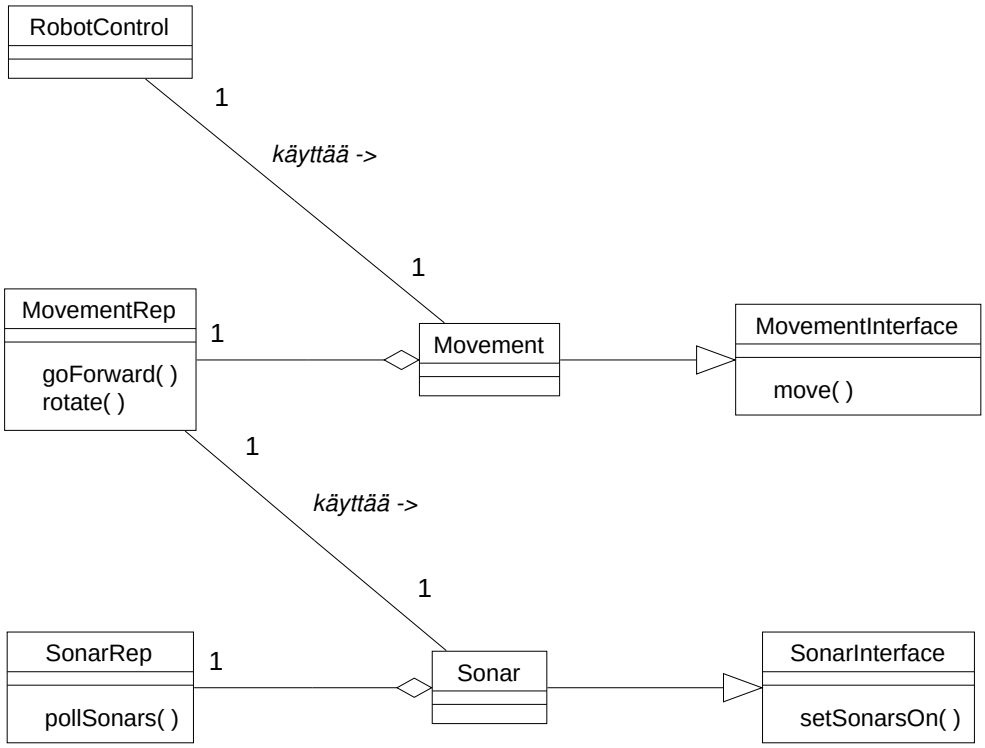
RobotControl
1
käyttää ->
1
MovementRep
goForward( )
rotate( )
1
Movement
MovementInterface
move( )
1
käyttää ->
1
SonarRep
pollSonars( )
1
Sonar
SonarInterface
setSonarsOn( )