

Lesson 7

Semaphore Use In Synchronization

Ch 6 [BenA 06]

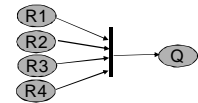
Consumer Producer Revisited
Readers and Writers
Baton Passing
Private Semaphores
Resource Management

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Synchronization with Semaphores



sem gate = -3; # must know number of R's (!)

Process R[i = 1 to 4]
....
V(gate); # signal Q
...

Process Q
....
P(gate)
...
how to prepare for *next time*?
sem_set(gate, -3) ??

sem g[i = 1 to 4] = 0;

Process R[i = 1 to 4]
....
V(g[i]); # signal Q
...

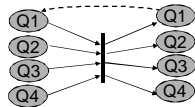
Process Q
....
P(g[1]); P(g[2]); P(g[3]); P(g[4]);
...
Q must know number of R's

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Barrier Synchronization with Semaphores

sem g[i = 1 to 4] = 0;
cont = 0;

Process Q[i = 1 to 4]
....
V(g[i]); # signal others
P(cont); # wait for others
...

Process Barrier
....
P(g[1]); P(g[2]); P(g[3]); P(g[4]); #wait for all
V(cont); V(cont); V(cont); V(cont); #signal all
...
Barrier must know number of Q's

- Barrier is implemented as separate *process*
 - This is just one possibility to implement the barrier
 - Cost of process switches?
 - How many process switches?

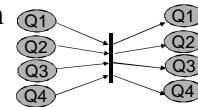
compare costs to using
barrier_wait instruction ?

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Barrier Synchronization with Barrier OS-Primitive



- Specific synchronization primitive in OS
 - Implemented with semaphores...
 - No need for extra process – less process switches

barrier br;

barrier_init(br, 4); # must be done before use

process Q[i = 1 to 4]

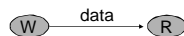
....
barrier_wait(br) # wait until *all* have reached this point
if (pid==1) # is this ok? is this done in time?
barrier_init(br, 4)
...

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Communication with Semaphores

Sem mutex=1, data_ready = 0;
Int buffer; # one data item buffer

Process W
....
P(mutex)
write_buffer(data)
V(mutex)
V(data_ready); # signal Q
...

Process R
....
P(data_ready); # wait for data
P(mutex)
read_buffer(data)
V(mutex)
....

- What is wrong?

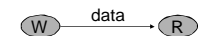
W might rewrite data buffer before R reads it
– Might have extra knowledge that avoids the problem

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Communication with Semaphores Correctly

Sem mutex=1, data_ready = 0, buffer_empty=1;
Int buffer

Process W
....
P(buffer_empty);
P(mutex)
write_buffer(data)
V(mutex)
V(data_ready); # signal Q
....

Process R
....
P(data_ready); # wait for data
P(mutex)
read_buffer(data)
V(mutex)
V(buffer_empty)
....

- Fast W can not overtake R now
- One reader R, one writer W, binary semaphores
- Actual communication with buffer in shared memory
 - Use model: 1 producer – 1 consumer – size 1 buffer

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Producer-Consumer with Binary Semaphores (Liisa Marttinen)

- Binary semaphore has values 0 and 1
 - OS or programming language library
- Semaphore does not keep count
 - Must have own variable *count* (nr of elements in buffer)
 - Protect it with critical section **mutex**
- Two important state changes
 - Empty buffer becomes not empty
 - Consumer may need to be awakened **items**
 - Full buffer becomes not full
 - Producer may need to be awakened **space**

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Simple Solution #1

(Producer-Consumer with Binary Semaphores)

```
typeT buf[n];      /* n element buffer */
int front=0;       /* read from here */
int rear=0;        /* write to this one */
int count=0;       /* nr of items in buf */
sem space=1;       /* need this to write */
int items=0;       /* need this to read */
int mutex=1;       /* need this to update count */
```

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Sol. #1

```
process Producer [i=1 to M] {
  while(true) {
    ... produce data ...
    P(space); /* wait until space to write */
    P(mutex);
    buf[rear] = data; rear = (rear+1) % n; count++;
    if (count == 1) V(items); /* first item to empty buffer */
    if (count < n) V(space); /* still room for next producer */
    V(mutex);
  }
}

process Consumer [i=1 to N] {
  while(true) {
    P(items); /* wait until items to consume */
    P(mutex);
    data = buf[front]; front = (front+1) % n; count--;
    if (count == n-1) V(space); /* buffer was full */
    if (count > 0) V(items); /* still items for next consumer */
    V(mutex);
    ... consume data ...
  }
}
```

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Evaluate Solution #1

- Simple solution
 - Mutex and synchronization ok
 - Mutex inside space or items
 - Get space first and then mutex
- Buffer reserved for one producer/consumer at a time
 - Does not allow for simultaneous buffer use **Not good**
 - Producer inserts item to “rear” **Simultaneously?**
 - Consumer removes item from “front”
- First waiting producer/consumer advances when signalled
 - Queued in semaphores

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Better Solution #2

(Producer-Consumer with Binary Semaphores)

```
typeT buf[n];      /* n element buffer */
int front=0;       /* read from here */
int rear=0;        /* write to this one */
int count=0;       /* nr of items in buf */
sem space=1;       /* need this to write */
int items=0;       /* need this to read */
int mutex=1;       /* need this to update count */
```

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Sol. #2

```
process Producer [i=1 to M] {
  while(true) {
    ... produce data ...
    P(space); /* wait until space to write */
    buf[rear] = data; rear = (rear+1) % n; /* outside mutex, ok? */
    P(mutex);
    count++; /* all of this must be in mutex */
    if (count == 1) V(items); /* first item to empty buffer */
    if (count < n) V(space); /* still room for next producer */
    V(mutex);
  }
}

process Consumer [i=1 to N] {
  while(true) {
    P(items); /* wait until items to consume */
    data = buf[front]; front = (front+1) % n; /* outside mutex, ok? */
    P(mutex);
    count--; /* all of this must be in mutex */
    if (count == n-1) V(space); /* buffer was full */
    if (count > 0) V(items); /* still items for next consumer */
    V(mutex);
    ... consume data ...
  }
}
```

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Evaluate Solution #2

- Relatively simple solution
 - Data copying (insert, remove) outside critical section
 - Protected by a semaphore (*items* and *space*)
- Simultaneous insert and remove ops
 - Producer inserts item to “rear”
 - Consumer removes item from “front”
- First waiting producer/consumer advances when signalled
 - Queued in semaphores

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Another Solution #3

(Producer-Consumer with Binary Semaphores)Ehto-
synkro-
nointi

- Use condition synchronization
 - Do P(space) or P(items) only when needed
 - Expensive op?
 - Requires execution state change (kernel/user)?

```

typeT buff[n]; /* n element buffer */
int front=0, /* read from here */
    rear=0, /* write to this one */
    count=0, /* nr of items in buf */
    cwp=0, /* nr of waiting producers */
    cwc=0, /* nr of waiting consumers */
    sem space=1, /* need this to write */
    items=0, /* need this to read */
    mutex=1; /* need this to update count */

```

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```

process Producer [i=1 to M] {
while(true) {
... produce data ...
P(mutex);
while (count == n) /* usually not true? while, not if !*/
{ cwp++; V(mutex); P(space); P(mutex); cwp-- }
buff[rear] = data; rear = (rear+1) % n; count++;
if (count == 1 && cwc > 0) V(items);
if (count < n && cwp > 0) V(space);
V(mutex);
} }

process Consumer [i=1 to N] {
while(true) {
P(mutex);
while (count == 0) /* while, not if !*/
{ cwc++; V(mutex); P(items); P(mutex); cwc-- }
data=buff[front]; front = (front+1) % n; count--;
if (count == n-1 && cwp > 0) V(space);
if (count > 0 && cwc > 0) V(items);
V(mutex);
... consume data ...
} }

```

Sol.
#3

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Evaluate Solution #3

- No simultaneous insert and remove ops
 - Data copying inside critical section
- In general case, only mutex semaphore operations needed
 - Most of the time?
 - Can they be busy-wait semaphores?
- First waiting producer/consumer does not necessarily advance when signalled
 - Someone else may get mutex first
 - E.g., consumer signals V(space), another producer gets (entry) mutex and places its data in buffer.
 - Need “while” loop in waiting code
 - Unfair solution even with strong semaphores?
 - How to fix?
 - Baton passing (pass critical section to next process)?
 - Not shown now

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Solutions #1, #2, and #3

- Which one is best? Why? When?
- How to maximise concurrency?
 - Separate data transfer (insert, remove) from permission to do it
 - Allow obtaining permission (e.g., code with P(space) and updating count) for one process run concurrently with data transfer for another process (e.g., code with buff[rear] = data; ...)
 - Need new mutexes to protect data transfers and index (rear, front) manipulation
 - Problem: signalling to other producers/consumers should happen in same critical section with updating count, but should happen only after data transfer is completed (i.e., in different critical section ...)

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Readers and Writers Problem

- Shared data structure or data base
- Two types of users: readers and writers
- Readers
 - Many can read at the same time
 - Can not write when someone reads
 - Can not read when someone writes
- Writers
 - Read and modify data
 - Only one can be active at the same time
 - Can be active only when there are no readers

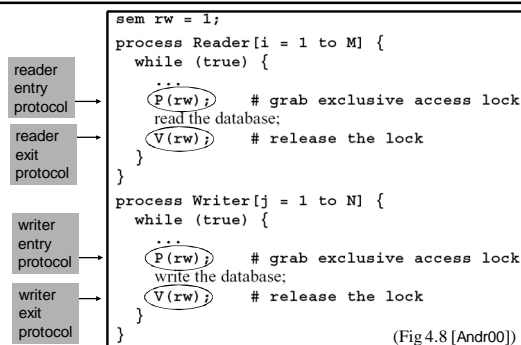


Jeff Magee
example (Imperial College,
London)

http://www.doc.ic.ac.uk/~irm/book/book_applets/ReadersWriters.html
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(Fig 4.8 [Andr00])

- Simple solution
 - Only one reader or writer at a time (not good)

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```
int nr = 0;      # number of active readers
sem rw = 1;     # lock for reader/writer synchronization

process Reader[i = 1 to M] {
  while (true) {
    ...
    nr = nr+1;
    if (nr == 1) P(rw); # if first, get lock
    read the database;
    nr = nr-1;
    if (nr == 0) V(rw); # if last, release lock
  }
}

process Writer[j = 1 to N] {
  while (true) {
    ...
    P(rw);
    write the database;
    V(rw);
  }
}
```

Only the first
reader waits here

Release mutex before P(rw)? (no need, why?)

Writers may starve – not good.
Writers have no chance to cut in between readers.

Jeff Magee example

How should you
adjust the readers to
not starve writers?

(Fig 4.9 [Andr00])

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Readers and Writers with Baton Passing Split Binary Semaphores

- Component semaphores e, r, w $0 \leq e+r+w \leq 1$ perm. to advance in only one
 - Mutex wait in $P(e)$, initially 1 (Fig 4.13 [Andr00])
 - Readers wait in $P(r)$ if needed, initially 0 (Alg. 6.21 [BenA06])
 - Writers wait in $P(w)$ if needed, initially 0
- In critical control areas only one process advances at a time
 - Wait in e, r , or w
- One advances, others wait in e, r or w
 - New reader/writer: wait in $P(e)$
 - Waiting for read turn: $V(e); P(r)$
 - Wait while not holding mutex
 - Waiting for write turn: $V(e); P(w)$
 - Wait while not holding mutex
 - When done, pass the baton (turn) to next one

$P(e) \dots V(e)$

$P(e) \dots V(r)$

$P(e) \dots V(w)$

$P(r) \dots V(r)$

$P(r) \dots V(w)$

$P(w) \dots V(e)$

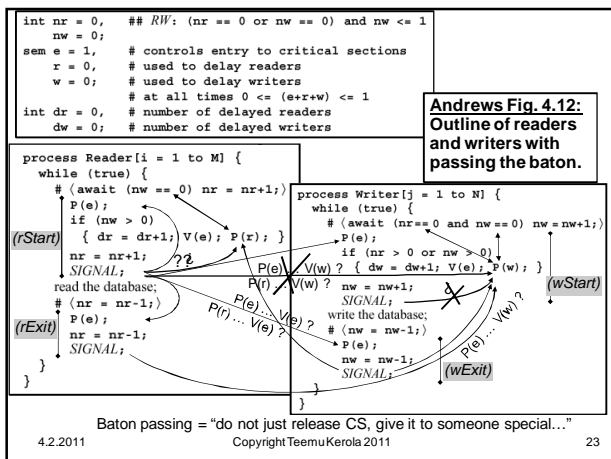
$P(w) \dots V(e)$

$P(w) \dots V(e)$

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Andrews Fig. 4.12:
Outline of readers
and writers with
passing the baton.

Baton passing = "do not just release CS, give it to someone special..."

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Baton passing

- When done your own mutex zone, wake up next ... (one or more semaphores control the same mutex)

SIGNAL()

- If reader waiting and no writers: $V(r)$
 - Do not release mutex (currently reserved e, r , or w)
 - New reader will continue with mutex already locked
 - "pass the mutex baton to next reader"
 - No one else can come to mutex zone in between
- Last waiting reader will close the mutex with $V(e)$
- Can happen concurrently when reading database
- Else if writer waiting and no readers: $V(w)$
 - Do not release mutex, pass baton to writer
- Else (let new process to compete with old ones): $V(e)$
 - Release mutex to let new process in the game (to execute entry or exit protocols)
 - New process gets in mutex only when no old one can be advance
 - Can happen concurrently when reading database

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Baton Passing with SIGNAL

SIGNAL – CS baton passing, priority on readers

```

if (nw == 0 and dr > 0) {
    dr = dr - 1;
    V(r);           # wake up waiting reader
}
else if (nr == 0 and nw == 0 and dw > 0) {
    dw = dw - 1;
    V(w);           # wake up waiting writer
}
else
    V(e);           # let new process to mix
    
```

“pass the baton within CS”

“just complete CS”

not possible in wStart, rExit

not possible in rStart

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```

process Reader[i = 1 to N] {
    while (true) {
        # (await (nw == 0) nr = nr + 1;
        P(e);
        if (nw > 0) { dr = dr + 1; V(e); P(r); }
        nr = nr + 1;
        next reader
        if (dr > 0) { dr = dr - 1; V(r); }
        else V(e);
        read the database;
        # (nr = nr - 1;
        P(e);
        nr = nr - 1;
        if (nr == 0 and dw > 0) {
            dw = dw - 1; V(w); }
        else V(e);
    }
}

process Writer[j = 1 to N] {
    while (true) {
        # (await (nr == 0 and nw == 0) nw = nw + 1;
        P(e);
        if (nr > 0 or nw > 0) {
            dw = dw + 1; V(e); P(w); }
        nw = nw + 1;
        V(e);
        write the database;
        # (nw = nw - 1;
        P(e);
        nw = nw - 1;
        if (dr > 0) { dr = dr - 1; V(r); }
        elseif (dw > 0) { dw = dw - 1; V(w); }
        else V(e);
    }
}
    
```

Fig. 4.13 [Andr00]: readers / writers solution using passing the baton (with SIGNAL code)

1st reader

1st writer

next writer

Still readers first

Unnecessary parts of SIGNAL code was removed

Modify to give writers priority?

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Discuss 26

Resource Management

- Problem
 - Many types of resources
 - N units of given resource
 - Request allocation: K units
 - Wait suspended until resource available
- Solution
 - Semaphore mutex (init 1)
 - Semaphore Xavail
 - init N – wait for available resource
 - init 0 – wait for permission to continue

use printer
use webcam
access database
access CS
allocate memory
allocate buffer
use comm port
get user focus
etc. etc.

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Simple Very Bad Solution

```

sem Xmutex = 1, Xavail = N

Xres_request() # one unit at a time
P(Xmutex)
P(Xavail) # ok if always
            # allocate just 1 unit
take 1 unit # not simple,
            # may take long time?
V(Xmutex);

Xres_release()
P(Xmutex)
return 1 unit
V(Xavail);
V(Xmutex);
    
```

- What is wrong?
 - everything
- Mutex?
- Deadlock?
- Unnecessary delays?
 - Each P() may result in (long) delay?
 - Hold mutex while waiting for resource
 - Very, very bad
 - Others can not get mutex to release resources...

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Another Not So Good Solution

```

sem Xmutex = 1, Xavail = N

Xres_request() # one unit at a time
P(Xavail) # ok if always
            # allocate just 1 unit
P(Xmutex)
take 1 unit # not simple,
            # may take long time?
V(Xmutex);

Xres_release()
P(Xmutex)
return 1 unit
V(Xmutex);
V(Xavail);
    
```

- What is wrong?
 - Works only for resources allocated and freed one unit at a time
- Mutex?
 - Mutex of control data?
 - Mutex of resource allocation data structures?

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Resource Management with Baton Passing Split Semaphore

```

sem Xmutex = 1, Xavail = 0 (not N) ; split semaphore
; (short wait) (long wait)

Xres_request(K) – request K units of given resource
P(Xmutex)
if “not enough free units” { V(Xmutex); P(Xavail); }
take K units ; assume short time
if “requests pending and enough free units” { V(Xavail); }
else V(Xmutex);

Xres_release(K)
P(Xmutex)
return K units
if “requests pending and enough free units” { V(Xavail); }
else V(Xmutex);
    
```

if ok? yes.

CS { }

CS { }

baton passing

baton passing

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Problems with Resource Management

- Need strong semaphores
- Strong semaphores are FIFO
 - What if 1st in line want 6 units, 2nd wants 3 units, and there are 4 units left?
 - What about priorities?
 - Each priority class has its own semaphore
 - Baton passing within each priority class?
 - How to release just some specific process?
 - Strong semaphore releases 1st in line
 - Answer: private semaphores

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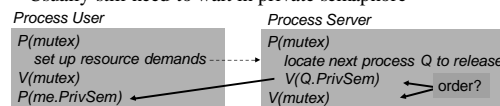
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Private Semaphore

yksityinen semafori

- Semaphore, to which only one process can ever make a P-operation
 - Initialized to 0, belongs to that process
- Usually part of PCB (process control block) for the process
 - Can create own semaphore arrays for this purpose
- Process makes demands, and then waits in private semaphore for turn
- Most often just one process at a time
 - Usually P(mutex) does not lead to process switches
- Usually still need to wait in private semaphore



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Shortest Job Next
(Private Semaphore Use Example)

- Common resource allocation method
 - Here: *time* = amount of resource requested
 - Here: just select next job (with shortest time)
 - Here: just one job (at most) holding the resource at a time
- Use private semaphores

```

CS {
  request(time,id): # requested time, userID
    P(e);
    if (!free) DELAY(); # wait for your turn
    free = false;      # got it!
    V(e);              # not SIGNAL(), only 1 at a time
}

CS {
  release(): ??
    P(e);
    free = true;
    SIGNAL();          # who gets the next one?
                      # pass baton, or release mutex
}

```

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- DELAY:
 - Place delayed process in queue PAIRS (ordered in ascending requested resource amount order) in correct place
 - V(e) – release mutex
 - Wait for your turn in private semaphore P(b[ID])
 - Each process has private semaphore, where only that process waits (initial value 0)
 - PAIRS queue determines order, one always wakes up the process at the head of the queue
 - Priority: smallest resource request first
- SIGNAL (in Release)
 - If someone waiting, take first one (time, ID), and wake up that process: V(b[ID]);
 - o/w V(e)

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PAIRS:	P2	P15	P3	P1	ID
	3	6	17	64	time

Queue can be ordered according to requested cpu-time (requested cpu-time is the resource in this example)

0 1 2 3 n-1
b[n] [] [P1] [] [P3] ... []

Private semaphore b[ID] for each process ID: 0 ..n-1

Process release is dependent on its location in PAIRS. When resource becomes free, the 1st process in line may advance.

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```

bool free = true;
sem e = 1, b[n] = {[n] 0}; # for entry and delay
typedef Pairs = set of (int, int);
Pairs pairs = {};
## S/N: pairs is an ordered set ^ free => (pairs == {})

request(time,id):
  P(e);
  if (!free) {
    insert (time,id) in pairs;
    V(e);          # release entry lock
    P(b[id]);      # wait to be awakened
  }
  free = false;
  V(e);          # optimized since free is false here

release():
  P(e);
  free = true;
  if (P != {}) {
    remove first pair (time,id) from pairs;
    V(b[id]);      # pass baton to process id
  }
  else V(e);

```

Andr00 Fig. 4.14
Shortest job next
(cpu scheduling policy)
allocation using
semaphores.

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Semaphore Feature Summary

- Many implementations and semantics
 - Be careful to use
 - E.g., is the (process) scheduler called after each V()?
 - Which one continues with processor, the process executing V() or the process just woken up?
 - Can critical section continue after V()?
 - Busy wait vs. suspend state?
- Hand coded synchronization solutions
 - Can solve almost any synchronization problem
 - Baton passing is useful and tricky
 - Explicit handover of some resource
 - Be careful to use
 - Do not leave mutex'es open
 - Do not suspend inside mutex
 - Avoid deadlocks
 - Do (multiple) P's and V's in correct order

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