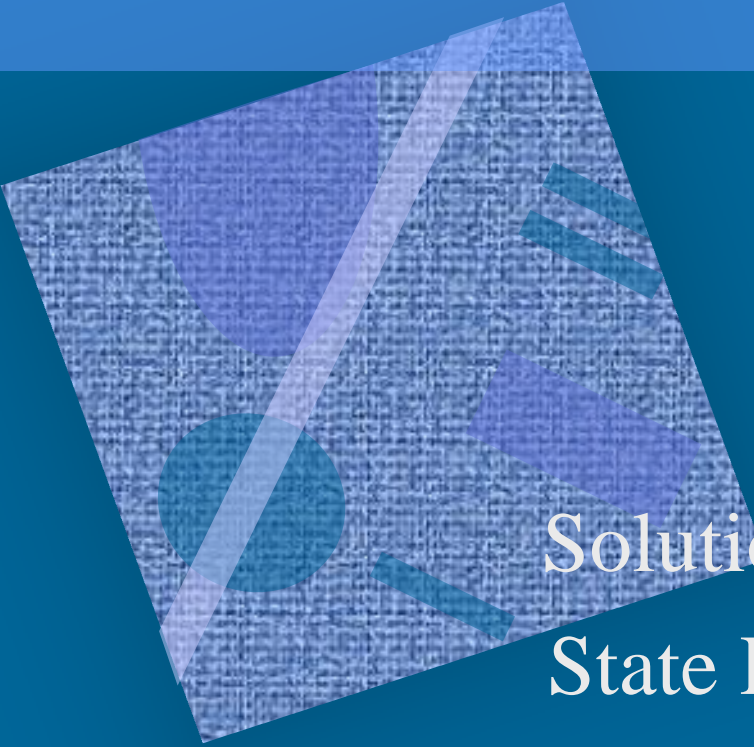


Critical Section Problem

Ch 3 [BenA 06]



Critical Section Problem
Solutions without HW Support
State Diagrams for Algorithms
Busy-Wait Solutions with HW Support

Mutual Exclusion

Real World Example



Fig. Pesutuvan varaus

- How to reserve a laundry room?
 - Housing corporation with many tenants
- Reliable
 - No one else can reserve, once one reservation for given time slot is done
 - One can not remove other's reservations
- Reservation method
 - One can make decision independently (without discussing with others) on whether laundry room is available or not
 - One can have reservation for at most one time slot at a time
- People not needing the laundry room are not bothered
- One should not leave reservation on when moving out
- One should not lose reservation tokens/keys

mutual
exclusion,
i.e., mutex

non-preemptive

keskeyttämätön

distributed/centralized

no simultaneous resource possession

recovery?



PESUTUVAN VARAUS

Taloyhtiön pesutuvan varaus toimii laittamalla varauslukko teille sopivan päivän ja kellonajan kohdalle varaustauluun.

Varauslukko tulee poistaa varauksen jälkeen tai mikäli ette käytä varaamaanne aikaa.

Terveisin

isännöitsijä

Photo P. Niklander

3.11.2008

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3

Concurrent indivisible operations

- Echo

```
char out, in; //globals
procedure echo {
  input (in, keyboard);
  out = in;
  output (out, display);
}
```

- What if *out* and/or *in* local variables?

Process P1

...

input (in,..);

out = in;

...

output(out,..);

Process P2

...

...

input(in,..);

out = in;

output (out,..);

- Data base update

- Name, id, address, salary, annual salary, ...

- How/when/by whom to define granularity for indivisible operations?

Critical Section (CS)

- Mutex (mutual exclusion) solved
- No deadlock: someone will succeed
- No starvation (and no unnecessary delay)
 - Everyone succeeds eventually
- *Protocol* does not use common variables with CS actual work
 - Can use it's own local or shared variables

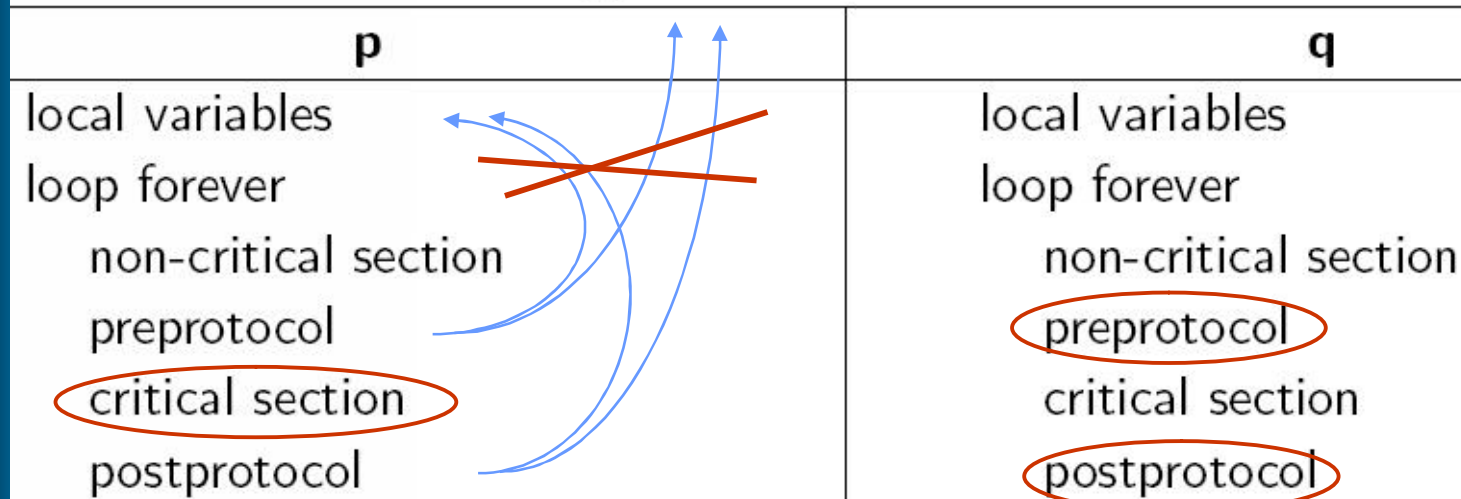
poissulkemisongelma ratk.

ei lukkiutumista

ei nälkiintymistä

Algorithm 3.1: Critical section problem

global variables



Critical Section Assumptions

Algorithm 3.1: Critical section problem	
global variables	
p	q
local variables	local variables
loop forever	loop forever
non-critical section	non-critical section
preprotocol	preprotocol
critical section	critical section
postprotocol	postprotocol

Diagram illustrating the critical section assumptions for two processes, p and q. The diagram shows the execution flow for each process, including local variables, a loop forever, a non-critical section, a preprotocol, a critical section, and a postprotocol. A red double-headed arrow labeled "unsafe zone" spans the non-critical sections of both processes. A blue double-headed arrow labeled "safe zone" spans the critical sections of both processes.

- Preprotocol and postprotocol have no common local/global variables with critical/non-critical sections
 - They do not disturb/affect each other
- Non-critical section may stall or terminate
 - Can not assume it to complete
- Critical section will complete (will not terminate)
 - Postprotocol eventually executed once critical section is entered
- Process will not terminate in preprotocol or postprotocol (!!!)

Critical Section Solution

Algorithm 3.2: First attempt

integer turn \leftarrow 1

p		q	
loop forever		loop forever	
p1:	non-critical section	q1:	non-critical section
p2:	await turn = 1	q2:	await turn = 2
p3:	critical section	q3:	critical section
p4:	turn \leftarrow 2	q4:	turn \leftarrow 1

- How to prove correct? (or incorrect?)
 - Mutex? (functional correct)
 - No deadlock? (eventually someone from many will get in)
 - No starvation? (eventually specific one will get in)

Correctness Proofs

- Prove incorrect
 - Come up with one scenario that does not work
 - Two processes execute in sync?
 - Some other unlikely scenario?
- Prove correct
 - Heuristics: “I did not come up with any proofs (counterexample) for incorrectness and I am smart”
 - I can not prove incorrectness
 - It must be correct...
 - State diagrams
 - Describe algorithm with states:
 - { relevant control pointer (cp) values,
relevant local/global variable values }
 - Analyze state diagrams to prove correctness

often non-trivial

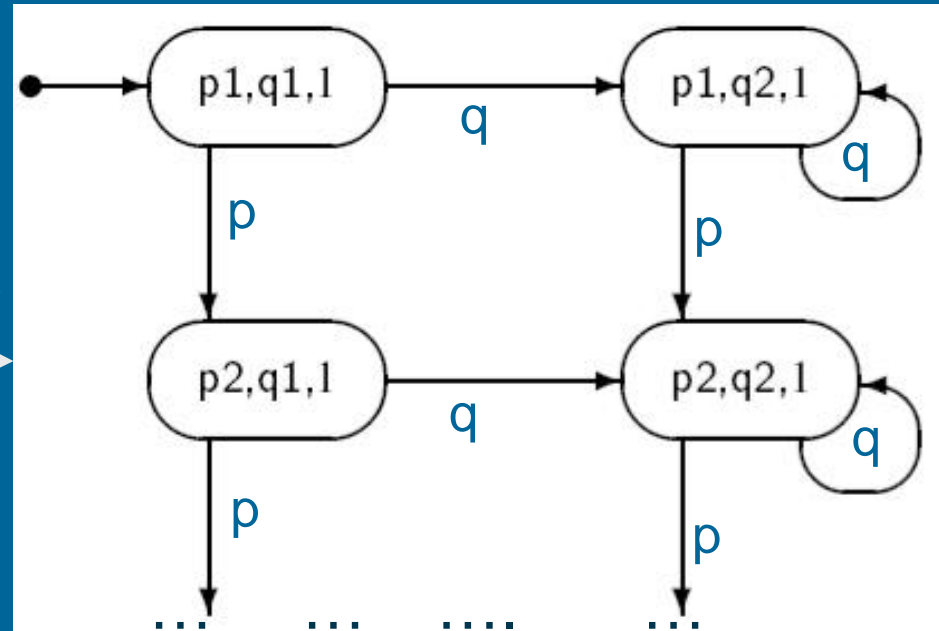
“easy”, unreliable

difficult, reliable

State Diagram for Alg. 3.2

Algorithm 3.2

- State $\{p_i, q_i, \text{turn}\}$
 - Control pointer p_i
 - Control pointer q_i
 - Global variable turn
 - 1st four states



- Mutex ok

- State $\{p3, q3, \text{turn}\}$ not accessible in state diagram?

- No deadlock?

- When many processes try concurrently, one will succeed

- No starvation?

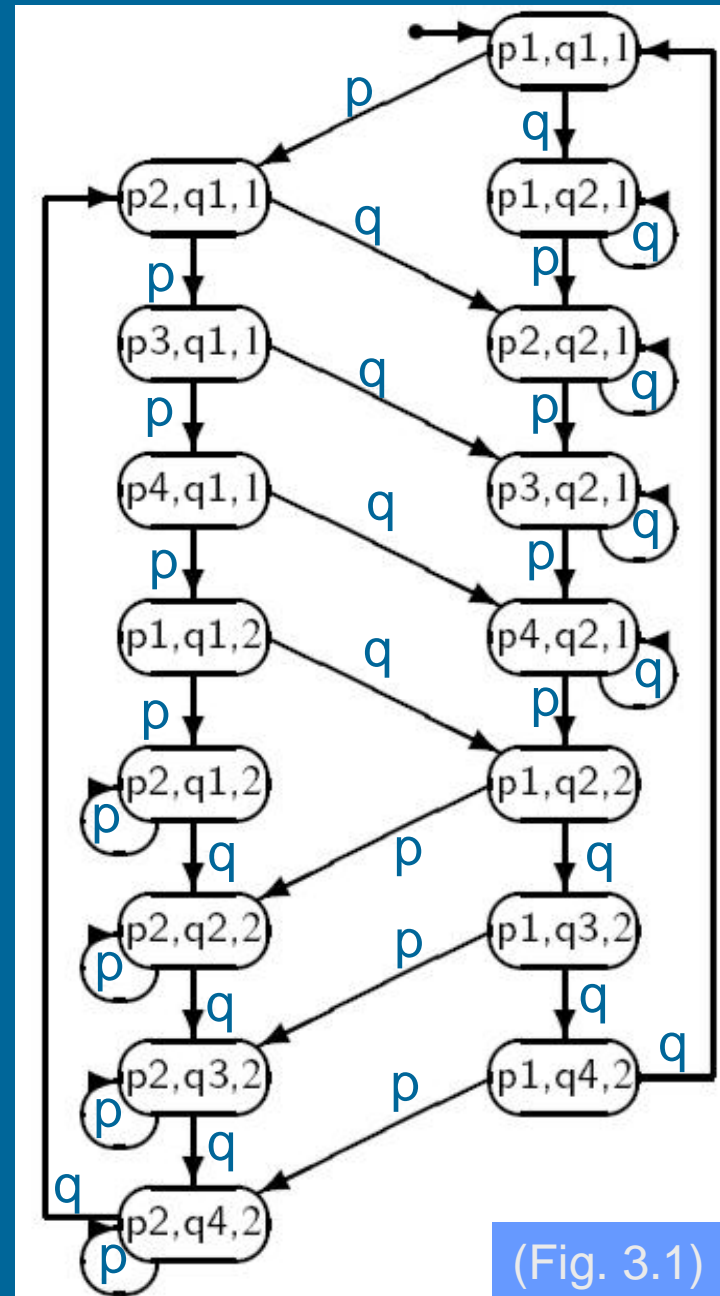
- Whenever any (one) process tries, it will eventually succeed

How to prove it?

State Diagram for Algorithm 3.2

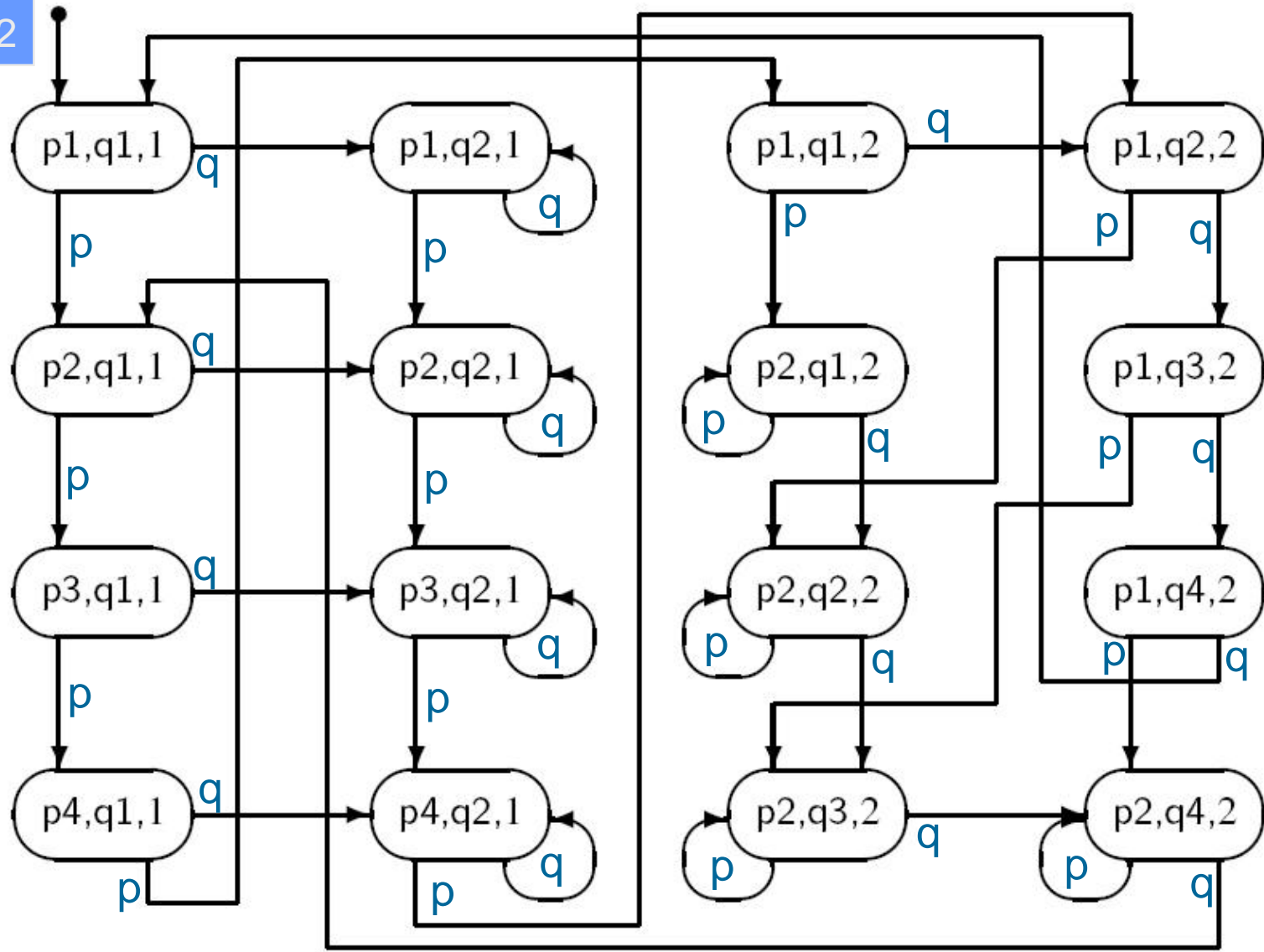
Algorithm 3.2

- Create complete diagram with all accessible states
- No states
 - $\{p3, q3, 1\}$
 - $\{p3, p3, 2\}$
- I.e., mutex secured proof!
- Problem:
 - Too many states?
 - Difficult to create
 - Difficult to analyze



Alternate Layout for Full State Diagram

Alg. 3.2

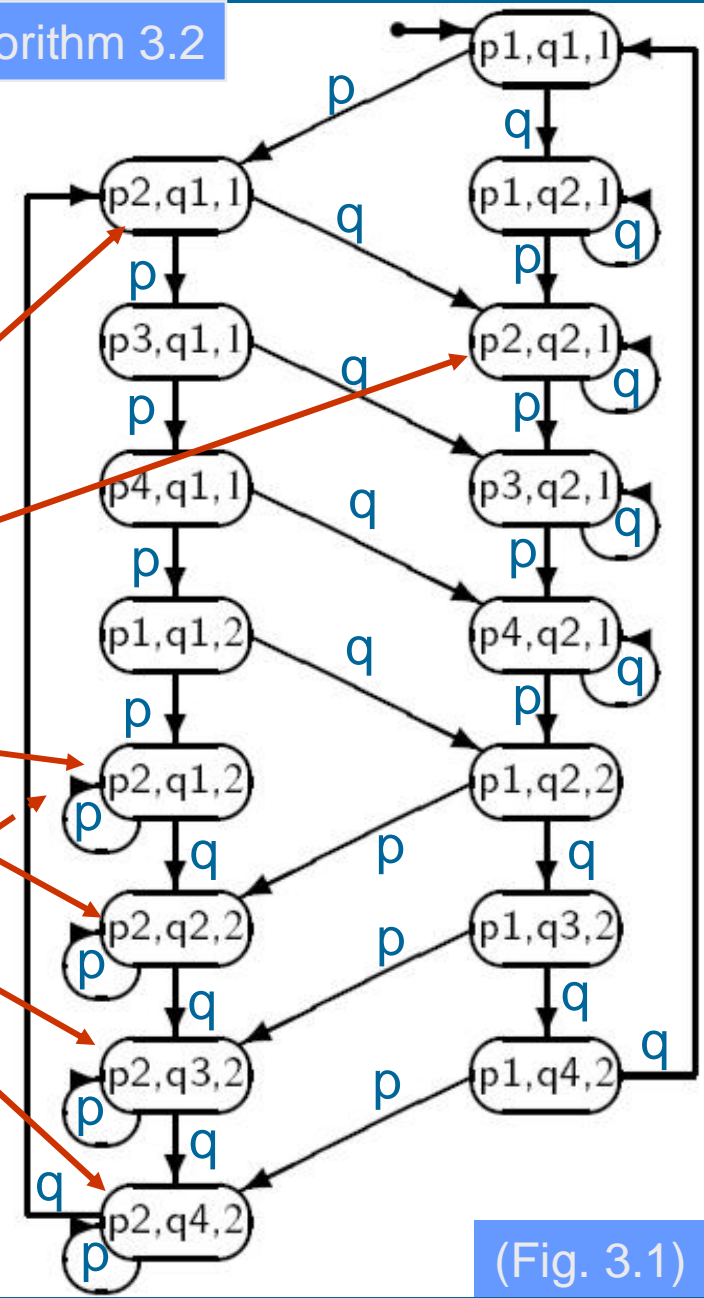


Corretness (3)

Algorithm 3.2

- Mutex?
 - Ok, no state $\{p3, q3, ??\}$
- No deadlock?
 - many try, one can always get in? (into a state with $p3$ or $q3$)
 - $\{p2, q1, 1\}$: P can get in
 - $\{p2, q2, 1\}$: P can get in
 - $\{p2, q1 \text{ tai } q2, 2\}$:
 - Q can get in
 - $\{p2, q3 \text{ tai } q4, 2\}$:
 - P can get in eventually
 - $\{pi, q2, ?\}$ similarly
- No starvation?
 - One tries, it will eventually get in?
 - $\{p2, q1, 2\}$
 - Q dies (ok to die in $q1$), P will starve! **Not good!**

All states with p2



(Fig. 3.1)

Reduced Algorithm for Easier Analysis

Algorithm 3.2: First attempt	
integer turn \leftarrow 1	
p	q
loop forever	loop forever
p1: non-critical section	q1: non-critical section
p2: await turn = 1	q2: await turn = 2
p3: critical section	q3: critical section
p4: turn \leftarrow 2	q4: turn \leftarrow 1

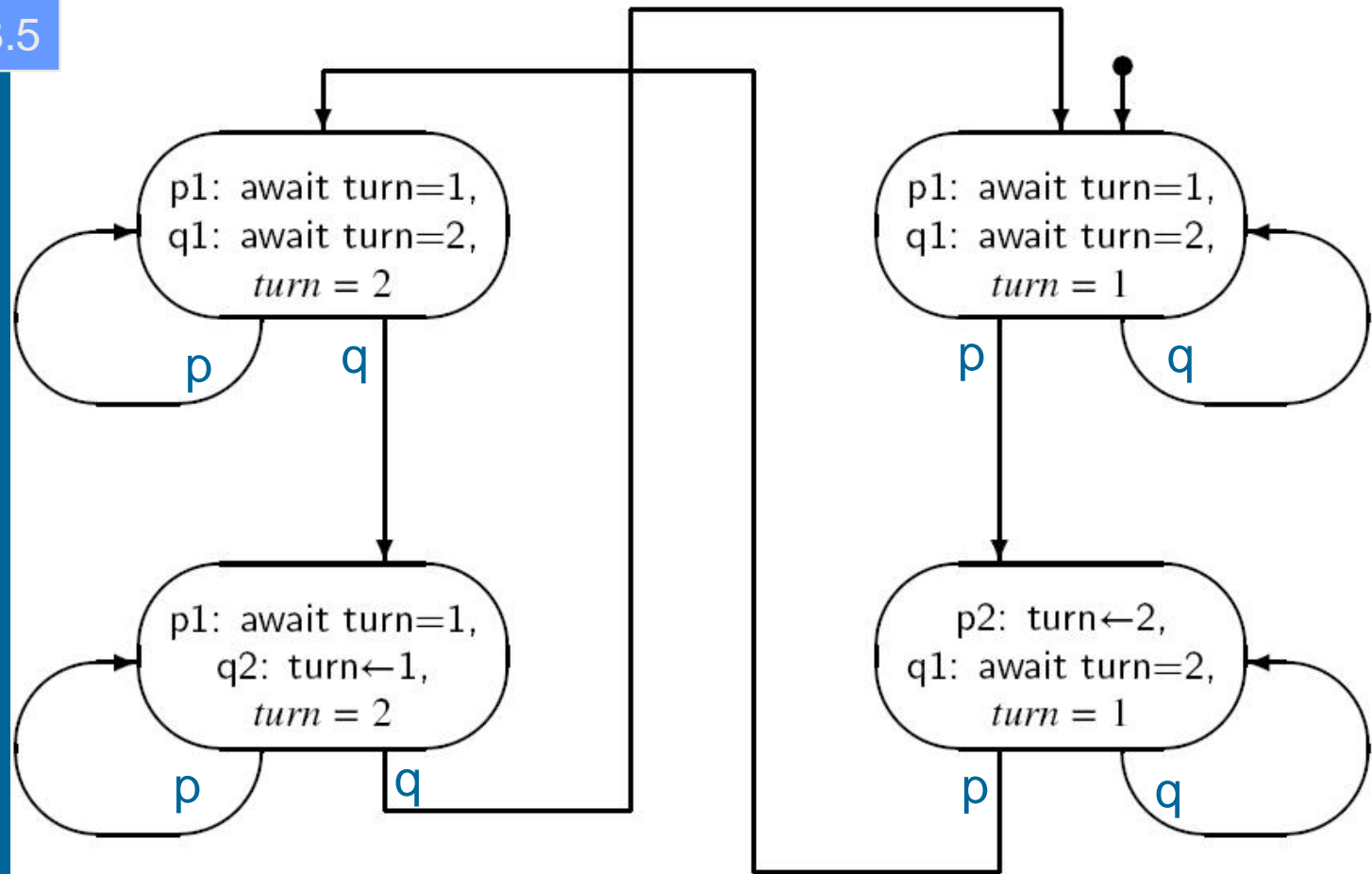
- Reduce algorithm to reduce number of states of state diagrams: leave irrelevant code out
 - Nothing relevant (for mutex) left out?



Algorithm 3.5: First attempt (abbreviated)	
integer turn \leftarrow 1	
p	q
loop forever	loop forever
p1: await turn = 1	q1: await turn = 2
p2: turn \leftarrow 2	q2: turn \leftarrow 1

State Diagram for Reduced Algorithm

Alg. 3.5

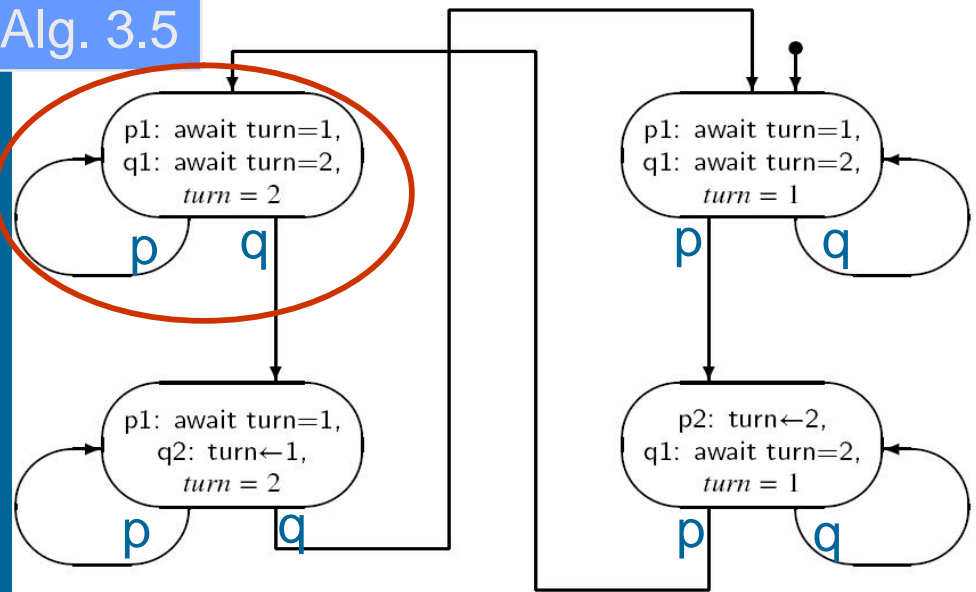


(Fig. 3.2)

- Much fewer states!

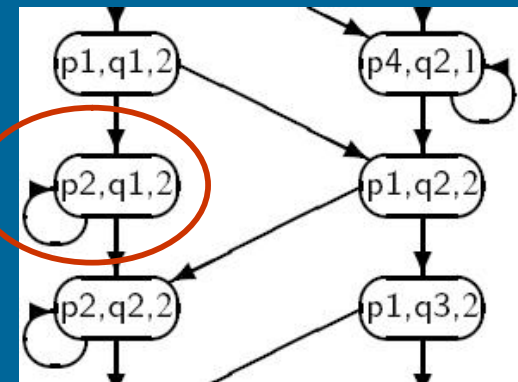
Correctness of Reduced Algorithm (2)

Alg. 3.5



- Mutex? **OK**
 - No state {p2, q2, turn}
- No deadlock: Some are trying, one may get in? **OK**
 - Top left (p & q trying): q will get in
 - Bottom left (p trying): q will eventually execute (assumption!)
 - Top & bottom right: mirror situation
- No starvation? **Not OK**
 - Tricky, reduced too much!
 - NCS combined with await
 - Look at original diagram
 - Problem if Q dies in NCS

should be OK to die in NCS, but not OK to die in protocol



Critical Section Solution #2

Algorithm 3.6: Second attempt

boolean *wantp* \leftarrow false, *wantq* \leftarrow false

p		q	
loop forever		loop forever	
p1:	non-critical section	q1:	non-critical section
p2:	await <i>wantq</i> = false	q2:	await <i>wantp</i> = false
p3:	<i>wantp</i> \leftarrow true	q3:	<i>wantq</i> \leftarrow true
p4:	critical section	q4:	critical section
p5:	<i>wantp</i> \leftarrow false	q5:	<i>wantq</i> \leftarrow false

- Each have their own global variable *wantp* and *wantq*
 - True when process is in critical section
- Process dies in NCS?
 - Starvation problem ok, because it's *want*-variable is false
- Mutex? Deadlock?

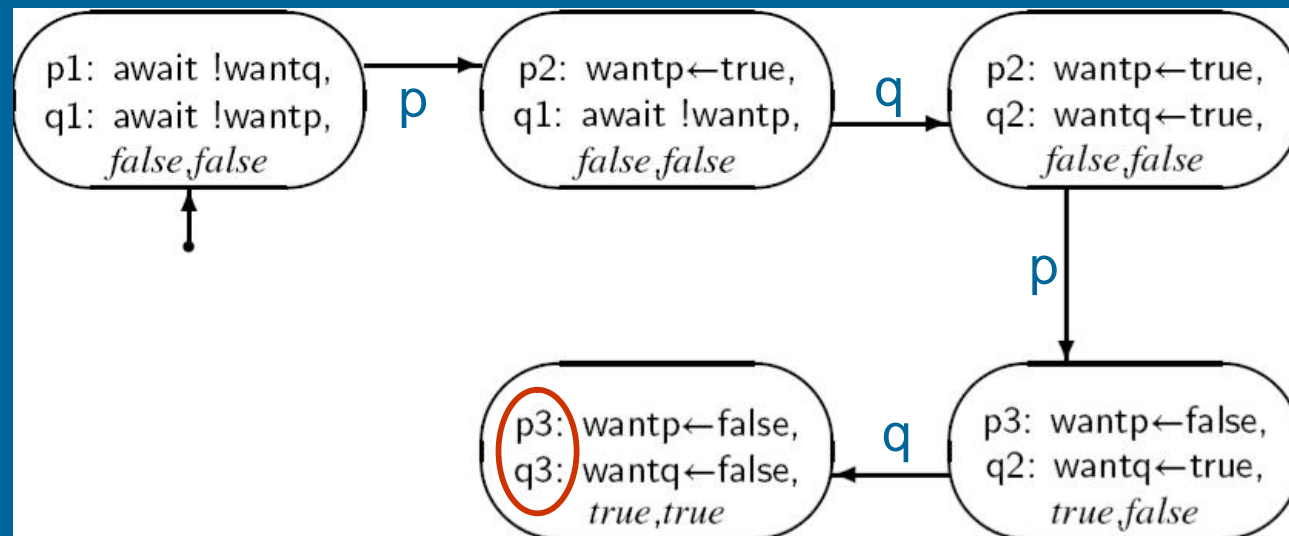
Attempt #2 Reduced

Algorithm 3.7: Second attempt (abbreviated)

boolean wantp ← false, wantq ← false	
p	q
loop forever p1: await wantq = false p2: wantp ← true p3: wantp ← false	loop forever q1: await wantp = false q2: wantq ← true q3: wantq ← false

pro-
to-
col

- No mutex! {p3, q3, ?} reachable
 - Problem: p2 should be part of critical section (but is not!)



Critical Section Solution #3

Algorithm 3.8: Third attempt

boolean wantp \leftarrow false, wantq \leftarrow false

p	q
loop forever	loop forever
p1: non-critical section	q1: non-critical section
p2: wantp \leftarrow true	q2: wantq \leftarrow true
p3: await wantq = false	q3: await wantp = false
p4: critical section	q4: critical section
p5: wantp \leftarrow false	q5: wantq \leftarrow false

- Avoid previous problem, mutex ok
- Deadlock possible: {p3, q3, wantp=true, wantq=true}
- Problem: cyclic wait possible, both insist their turn next
 - No preemption

Algorithm 3.9: Fourth attempt

boolean wantp ← false, wantq ← false

p		q	
loop forever		loop forever	
p1:	non-critical section	q1:	non-critical section
p2:	wantp ← true	q2:	wantq ← true
p3:	while wantq	q3:	while wantp
p4:	wantp ← false	q4:	wantq ← false
p5:	wantp ← true	q5:	wantq ← true
p6:	critical section	q6:	critical section
p7:	wantp ← false	q7:	wantq ← false

- Avoid deadlock by giving away your turn if needed
- Mutex ok: P in p6 only if !wantq (∅ Q is not in q6)
- Deadlock (livelock) possible:
 - {p3, q3, ...} → {p4, q4, ...} → {p5, q5, ...}
 - Unlikely but possible!
 - **Livelock**: both executing all the time, not waiting suspended
 - Neither one advances

elolukko

Algorithm 3.10: Dekker's algorithm

boolean wantp \leftarrow false, wantq \leftarrow false
integer turn \leftarrow 1

p	q
loop forever	loop forever
p1: non-critical section	q1: non-critical section
p2: wantp \leftarrow true	q2: wantq \leftarrow true
p3: while wantq	q3: while wantp
p4: if turn = 2	q4: if turn = 1
p5: wantp \leftarrow false	q5: wantq \leftarrow false
p6: await turn = 1	q6: await turn = 2
p7: wantp \leftarrow true	q7: wantq \leftarrow true
p8: critical section	q8: critical section
p9: turn \leftarrow 2	q9: turn \leftarrow 1
p10: wantp \leftarrow false	q10: wantq \leftarrow false

- Combine 1st and 4th attempt
- 3 global (mutex ctr) variables: shared *turn*, semi-private *want*'s
 - only one process writes to *wantp* or *wantq* (= semi-private)
- *turn* gives you the right to insist, i.e., priority
 - Used only when both want CS at the same time

Algorithm 3.10: Dekker's algorithm

boolean wantp ← false, wantq ← false
integer turn ← 1

p	q
loop forever	loop forever
p1: non-critical section	q1: non-critical section
p2: wantp ← true	q2: wantq ← true
p3: while wantq	q3: while wantp
p4: if turn = 2	q4: if turn = 1
p5: wantp ← false	q5: wantq ← false
p6: await turn = 1	q6: await turn = 2
p7: wantp ← true	q7: wantq ← true
p8: critical section	q8: critical section
p9: turn ← 2	q9: turn ← 1
p10: wantp ← false	q10: wantq ← false

Proof

- Mutex ok: P in p8 only if !wantq (∴ Q can not be in q8)
- No deadlock, because P or Q can continue to CS from {p3, q3, ..}
- No starvation, because
 - If in {p6, ...}, then eventually {p6, q9, ...} and {..., q10, ...}
 - Next time {p3, ...} or {p4, ...} will lead to {p8, ...}

Algorithm 3.10: Dekker's algorithm

boolean wantp \leftarrow false, wantq \leftarrow false
integer turn \leftarrow 1

p	q
loop forever	loop forever
p1: non-critical section	q1: non-critical section
p2: wantp \leftarrow true	q2: wantq \leftarrow true
p3: while wantq	q3: while wantp
p4: if turn = 2	q4: if turn = 1
p5: wantp \leftarrow false	q5: wantq \leftarrow false
p6: await turn = 1	q6: await turn = 2
p7: wantp \leftarrow true	q7: wantq \leftarrow true
p8: critical section	q8: critical section
p9: turn \leftarrow 2	q9: turn \leftarrow 1
p10: wantp \leftarrow false	q10: wantq \leftarrow false

- mutex with no HW-support needed, need only shared memory
- Bad: complex, many instructions
 - Must execute each instruction at a time, in this order
 - Will not work, if compiler optimizes code too much!
 - In simple systems, can do better with HW support
 - Special machine instructions to help with this problem

Mutex with HW Support

- Specific machine instructions for this purpose
 - Suitable for many situations
 - Not suitable for all situations
- Interrupt disable/enable instructions
- Test-and-set instructions
 - Other similar instructions
- Specific memory areas
 - Reserved for concurrency control solutions
 - Lock variables (for test-and-set) in their own cache?
 - Different cache protocol for lock variables?
 - Busy-wait without memory bus use?

```
Disable
-- Critical Section --
Enable
```

```
Lock (L)
-- Critical Section --
Unlock (L)
```

Disable Interrupts

- Environment

- All (competing) processes on same processor
- Not for multiprocessor systems
 - Disabling interrupts does it only for the processor executing that instruction

Disable
Enable

- Disable/enable interrupts

- Prevent process switching during critical sections
 - Good for only very short time
 - Prevents also (other) operating system work while in CS

Disable
-- CS --
Enable

Disable
-- CS --
Enable



Test-and-set locking variables

- Environment

Lukkomuuttujat

- All processes with shared memory
- Should have multiple processors
- Not very good for uniprocessor systems (or synchronizing processes running on the same processor)
 - Wait (busy-wait) while holding the processor!

- Test-and-set *machine instruction*

- Indivisibly read old value and write new value (complex mem-op)

Test-and-set (common, local)

local ← common ; read state

common ← 1 ; mark reserved

shared

local

Test-and-set (shLock, locked);
while (locked)
 Test-and-set (shLock, locked);
-- CS --
shLock = 0;

Test-and-set (shLock, locked);
while (locked)
 Test-and-set (shLock, locked);
-- CS --
shLock = 0;

Other Machine Instructions for Synchronization Problem Busy-Wait Solutions

- Test-and-set

```
Test-and-set (common, local)
  local ← common ; read state
  common ← 1    ; mark reserved
```

Use all in busy-wait loops

- Exchange

```
Exchange (common, local)
  local ↔ common ; swap values
```

- Fetch-and-add

```
Fetch-and-add (common, local, x)
  local ← common ; read state
  common ← common+x ; add x
```

“read-modify-write”
memory bus transaction
(local in HW register)

- Compare-and-swap

```
int Compare-and-swap (common, old, new)
  return_val ← common
  if (common == old)
    common ← new
```

“read-after-write”
memory bus transaction
may also be used