

Probabilistic models for big data

Fall 2014: Introductory lecture

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Probabilistic models for big data

Course code: 58314301

Credit points: 3

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Office hours: Please make an appointment by email

Prerequisites: Probabilistic Models, Scientific writing

Moodle: "58314301 Seminar in Probabilistic Models for
Big Data, autumn 2014"

Registration code: stochastic

Schedule

- ▶ Today: Introduction, papers
- ▶ Next week: Choosing the topic, instructions for presentations etc
- ▶ Article summaries:
 1. October 19th: Submission deadline
 2. November 5th: Review deadline
 3. November 25th: Final version
- ▶ Presentations between early November and Mid December (6-7 sessions)

Data analysis with probabilistic models

The modeling task:

- ▶ Construct a (often general-purpose) probabilistic model by specifying a set of probability distributions
- ▶ Observe data
- ▶ Fit the model to the data, learning the probability distribution of the model parameters given the data
- ▶ Make predictions (e.g. class labels of future observations) by averaging over that distribution

Big data

- ▶ Big data: Any data collection that is large enough to be difficult to process with “traditional” technique
- ▶ A lot of hype in the business world, but the practical challenges are real
- ▶ Computational neuroscience: Typical session with fMRI produces around 3 gigabytes of data (activities of ~ 1 M brain voxels every few seconds)
- ▶ Computational biology: A typical high-throughput sequencing run yields 30M-100M sequencing reads of ~ 100 nt, some GBs per sample
- ▶ Big business players (Amazon, FB etc) have hundreds of millions of customers requiring real-time predictions (e.g. recommender engines, search)

Big data at our department (examples)

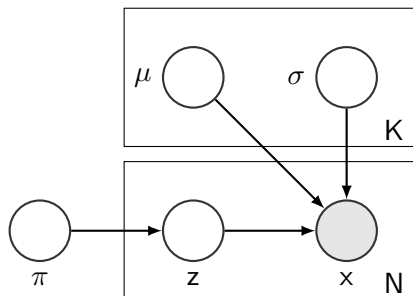
- ▶ Helsinki Privacy Experiment (50 terabytes of video and audio of home surveillance)
- ▶ 200M text documents covering editorial and social media of the past year, 60M scientific articles covering the history of human scientific progress
- ▶ Several genomics data sets with 100s high-throughput sequencing samples, multiple terabytes each set

Probabilistic models for big data

- ▶ Probabilistic models often considered to be computationally heavy; classical papers on MCMC often have only a few parameters and the sampling chains are long
- ▶ **This course:** What can probabilistic modeling offer for big data applications?
 - ▶ Scaling up variational inference
 - ▶ More efficient samplers, distributed sampling
 - ▶ Implementation issues not covered: GPU computing or other forms of scaling up the computational resources, distributed computing frameworks such as Hadoop, Spark, ...

Probabilistic graphical models

- ▶ Graph illustrates independencies, data generation described with a set of probability distributions
- ▶ Notation: $\mathcal{D} = \{\mathbf{x}\}$ is data, θ are the parameters



$$\pi \sim \text{Dirichlet}(\alpha)$$

$$z_n \sim \text{Categorical}(\pi)$$

$$\mu_k \sim N(\mu_0, \sigma_0)$$

$$\sigma_k^{-2} \sim \text{Gamma}(\alpha_0, \beta_0)$$

$$x_n \sim N(\mu_k, \sigma_k)$$

Bayesian inference

- ▶ Model: $p(\mathcal{D}, \theta) = p(\mathcal{D}|\theta)p(\theta) = p(\theta) \prod_n p(\mathbf{x}_n|\theta)$
- ▶ Given a model, we are typically interested in predictions
 $p(\mathbf{x}|\mathcal{D}) = \int p(\mathbf{x}|\theta)p(\theta|\mathcal{D})d\theta$
- ▶ The posterior distribution $p(\theta|\mathcal{D})$ hence summarizes the model
- ▶ Bayes' rule $p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta)p(\theta)}{p(\mathcal{D})}$
- ▶ In principle easy, in practice the quantity
 $p(\mathcal{D}) = \int p(\mathcal{D}|\theta)p(\theta)d\theta$ necessitates approximative inference
- ▶ On this course: (Mostly) Markov chain Monte Carlo and variational inference

Variational inference basics

- ▶ Idea: approximate the posterior distribution $p(\theta|\mathcal{D})$ with another distribution $q(\theta)$ that is analytically tractable
- ▶ Learn the approximation by minimizing the distance between $q(\theta)$ and $p(\theta|\mathcal{D})$
- ▶ The distance is measured by the Kullback-Leibler divergence $D(q||p) = \int q(\theta) \log \frac{q(\theta)}{p(\theta|\mathcal{D})} d\theta$
- ▶ ...and the minimization is often converted into maximizing a lower bound on the marginal likelihood (ELBO):
$$L = \int q(\theta) \log \frac{p(\mathcal{D}, \theta)}{q(\theta)} d\theta = p(\mathcal{D}) - D(q||p)$$
- ▶ Predictions then made by replacing $\int p(\mathbf{x}|\theta)p(\theta|\mathcal{D})d\theta$ by $\int p(\mathbf{x}|\theta)q(\theta)d\theta$

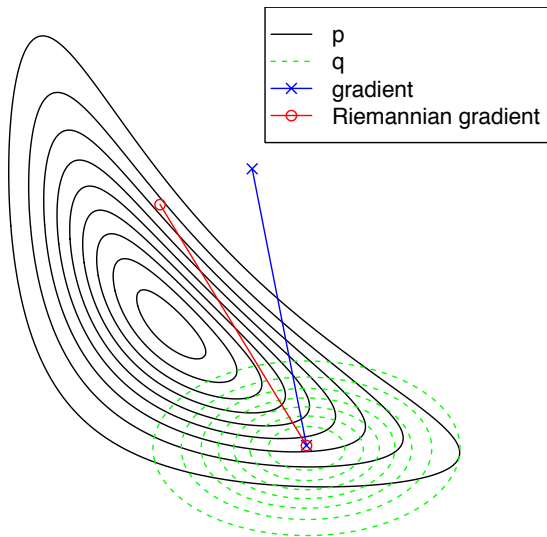
Mean-field variational inference

- ▶ Often $q(\theta)$ is factorized as $\prod_i q(\theta_i)$, so that we can optimize one factor at a time
- ▶ Differentiating wrt to $q(\theta_i)$ and setting the derivative to zero provides a closed-form update
$$\log q(\theta_i) = \int q(\theta_{-i}) \log p(\mathcal{D}, \theta) d\theta_{-i} + C$$
- ▶ The expectation over all other factors is typically easy to compute for exponential family distributions with conjugate priors (and much harder for everything else)
- ▶ Leads to an algorithm closely resembling expectation maximization

Towards more scalable variational inference

- ▶ Given a parametric form $q(\theta|\phi)$ VB is an optimization problem:
$$L(\phi) = \int q(\theta|\phi) \log \frac{p(\mathcal{D}, \theta)}{q(\theta|\phi)} d\theta$$
- ▶ Gradient-based optimization generally applicable:
$$\phi \leftarrow \phi + \delta \nabla L(\phi)$$
- ▶ Natural gradient speeds up convergence: Replace $\nabla L(\phi)$ with $F^{-1}(\phi) \nabla L(\phi)$, where $F(\phi)$ is the Fisher information matrix consisting of expectations of second derivatives of $\log q(\theta|\phi)$ (Honkela et al., JMLR 2010)
- ▶ Stochastic gradients applicable (Hoffman et al., JMLR 2013); more about this during the seminar

Variational inference example



Approximate inference by sampling

- ▶ A lot of Bayesian inference boils down to computing integrals

$$E[f(\theta)] = \int_{\theta} f(\theta) p(\theta|\mathcal{D}) d\theta$$

- ▶ Model predictions, posterior statistics of parameters, ...
- ▶ θ is often high-dimensional which makes these very difficult
- ▶ Stochastic approximation:

$$E[f(\theta)] \approx \frac{1}{N} \sum_{i=1}^N f(\theta_i),$$

when $\theta_i \sim p(\theta|\mathcal{D})$

- ▶ How to simulate samples following a given distribution?

MCMC basics (Metropolis et al., 1953; Hastings, 1970)

- ▶ Idea: construct a Markov chain, whose stationary distribution is the distribution of interest $p(\theta|\mathcal{D})$
- ▶ Requires an *unnormalised* $p^*(\theta|\mathcal{D}) \propto p(\theta|\mathcal{D})$
- ▶ In the Bayesian setting typically

$$p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta)p(\theta)}{p(\mathcal{D})}$$

which easily yields the unnormalised density

$$p^*(\theta|\mathcal{D}) = p(\mathcal{D}|\theta)p(\theta)$$

- ▶ To define the Markov chain, we need to specify a transition distribution $q(\theta'|\theta)$
- ▶ The Markov chain is guaranteed to converge if it satisfies sufficient regularity conditions and the *detailed balance* condition

$$q(\theta'|\theta)p(\theta|\mathcal{D}) = q(\theta|\theta')p(\theta'|\mathcal{D})$$

Metropolis–Hastings algorithm

- ▶ The most widely used MCMC algorithm is the Metropolis–Hastings algorithm
- ▶ Accept–reject mechanism, proposals are accepted with probability

$$f(\theta'|\theta) = \min \left(1, \frac{q(\theta|\theta')p(\theta'|\mathcal{D})}{q(\theta'|\theta)p(\theta|\mathcal{D})} \right)$$

- ▶ This satisfies the detailed balance because

$$\begin{aligned} f(\theta'|\theta)q(\theta'|\theta)p(\theta|\mathcal{D}) &= \min(q(\theta'|\theta)p(\theta|\mathcal{D}), q(\theta|\theta')p(\theta'|\mathcal{D})) \\ &= \min(q(\theta|\theta')p(\theta'|\mathcal{D}), q(\theta'|\theta)p(\theta|\mathcal{D})) \\ &= f(\theta|\theta')q(\theta|\theta')p(\theta'|\mathcal{D}) \end{aligned}$$

Gradients in MCMC

- ▶ Standard MCMC is based on proposal distributions whose shape is essentially *independent of the target*
 - ▶ E.g. fixed multivariate Gaussian proposals
- ▶ Target distribution gradients would allow utilising local shape
- ▶ Common algorithms:
 - ▶ Langevin dynamics MCMC
 - ▶ Hamiltonian Monte Carlo (a.k.a. hybrid Monte Carlo)
- ▶ Both based on constructing a suitable dynamical system and simulating it

Demo time

<http://nbviewer.ipython.org/630ec3bc0d4bbaa94d03>

Stochastic gradients

Papers: MCMC I

- M1. S. Ahn, A. Korattikara, M. Welling, **Bayesian posterior sampling via stochastic gradient Fisher scoring**, ICML 2012 and M. Welling, Y.W.Teh, **Bayesian Learning via Stochastic Gradient Langevin Dynamics**, ICML 2011.
- M2. S.Patterson, Y. W. Teh, **Stochastic Gradient Riemannian Langevin Dynamics on the Probability Simplex**, NIPS 2013.
- M3. S. Ahn, B. Shahbaba, M. Welling, **Distributed stochastic gradient MCMC**, ICML 2014.
- M4. T. Chen, E. Fox, C. Guestrin, **Stochastic Gradient Hamiltonian Monte Carlo**, ICML 2014.

Papers: MCMC II

- M5. A. Korattikara, Y. Chen, M. Welling, **Austerity in MCMC Land: Cutting the Metropolis-Hastings Budget**, ICML 2014.
- M6. D. Maclaurin, R.P. Adams, **Firefly Monte Carlo: Exact MCMC with Subsets of Data**, UAI 2014.
- M7. W. Neiswanger, E. Xing, C. Wang, **Asymptotically Exact, Embarrassingly Parallel MCMC**, UAI 2014; S.L. Scott, A.W. Blocker, F.V. Bonassi, H.A. Chipman, E.I. George, R.E. McCulloch, **Bayes and Big Data: The Consensus Monte Carlo Algorithm**, Bayes 250, 2013; and T. Campbell, J. How, **Approximate Decentralized Bayesian Inference**, UAI 2014.

Papers: Variational

- V1. M.D. Hoffman, D.M. Blei, C. Wang, J. Paisley. **Stochastic Variational Inference**, JMLR 2013 (Sections 1-2 and 5)
- V2. ... (Sections 3-4) and R. Ranganath, C. Wang, D.M. Blei, E. Xing, **An Adaptive Learning Rate for Stochastic Variational Inference**, ICML 2013.
- V3. M. Titsias, M. Lazaro-Gredilla, **Doubly Stochastic Variational Bayes for non-Conjugate Inference**, ICML 2014.
- V4. D.J. Rezende, S. Mohamed, D. Wierstra, **Stochastic Backpropagation and Approximate Inference in Deep Generative Models**, ICML 2014.
- V5. J. Hensman, N. Fusi, N.D. Lawrence, **Gaussian Processes for Big Data**, UAI 2013.
- V6. J. M. Hernandez-Lobato, N. Houlsby, Z. Ghahramani, **Stochastic Inference for Scalable Probabilistic Modeling of Binary Matrices**, ICML 2014.

Papers: Other

- 01. H. Rue, S. Martino, **Approximate Bayesian Inference for Latent Gaussian Models by Using Integrated Nested Laplace Approximations**, JRSS:B, 2009.
- 02. M. Schmidt, N. Le Roux, F. Bach, **Minimizing Finite Sums with the Stochastic Average Gradient**, arXiv 2013.
 - Own suggestions?

Next steps

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For next week:

1. Check the paper list (Moodle or course web page) and have a look at the papers
2. Mark all papers you are interested in on Moodle by Tuesday 9 September
 - ▶ Expressed preferences may be used to pre-allocate papers
3. Come to the next session on 10 September with a list of preferred papers and open mind for non-favourites too!