

Bayesian Networks

Brandon Malone

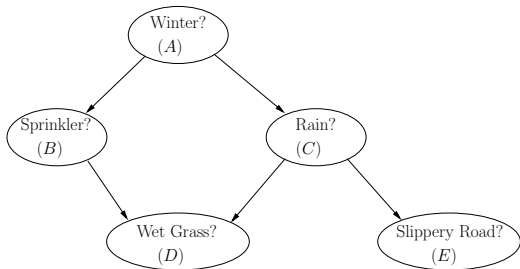
Much of this material is adapted from Chapter 4 of Darwiche's book

January 23, 2014

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- 2 Bayesian Networks
- 3 Graphoid Axioms
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Graph concepts and terminology

We have a **directed acyclic graph** in which the set of **nodes** represent **random variables**, \mathcal{X} .



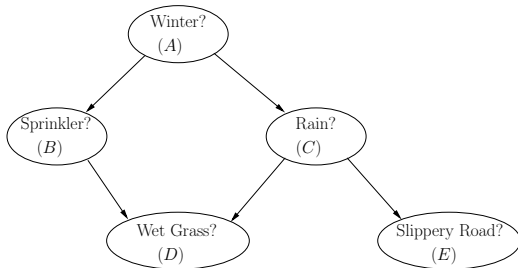
Pa_X : the **parents** of variable/node X

$Desc_X$: the **descendants** of X

$NonDesc_X$: the **non-descendants** of X , $\mathcal{X} \setminus \{X\} \setminus Pa_X \setminus Desc_X$

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Trail or **pipe**. Any sequence of **edges** which connects two variables

Example: *Sprinkler* \rightarrow *Wet Grass* \leftarrow *Rain* \rightarrow *Slippery Road*

N.B. The *direction* of the edge is not considered.

Valve. A variable in a trail

Probability terminology and notation

We have a **conditional probability distribution** represented as a table, called a **conditional probability table**.

A	B	$\Theta_{B A}$
T	T	0.20
T	F	0.80
F	T	0.75
F	F	0.25

Family. The variable X and its parents Pa_X , B and $\{A\}$ here

Parameters. The conditional probability distributions, $Pr(X = x | Pa_X = pa)$, often denoted $\theta_{x|pa}$

Each instantiation of Pa_X gives a different conditional distribution for X , so $\sum_x \theta_{x|pa} = 1$ for each pa .

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Compatibility. A parameter $\theta_{x|pa}$ is compatible with a (partial) instantiation \mathbf{z} if they assign the same value to common variables. We use $\theta_{x|pa} \sim \mathbf{z}$ to indicate compatibility.

Conditional independence. $I(\mathbf{X}, \mathbf{Z}, \mathbf{Y})$ means that \mathbf{X} is independent of \mathbf{Y} given \mathbf{Z} .

Factorized distributions

How can we use chain rule to write $Pr(A, B, C, D, E)$?

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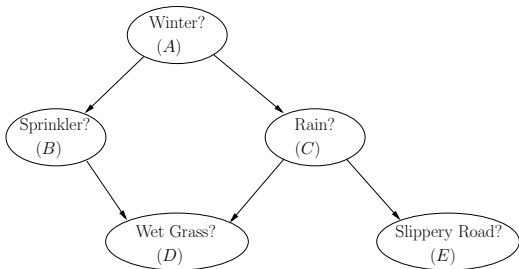
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How many parameters does this require?

Graphical structures as factorized distributions

What is the relationship between the factorized distribution and the graphical structure?

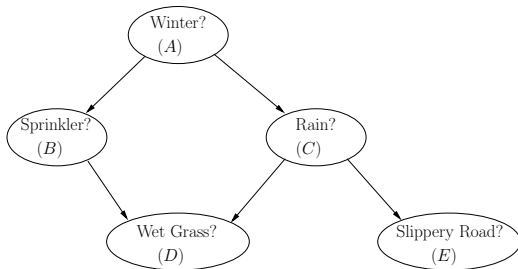
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The graph structure encodes the conditional independencies.

Local Markov property

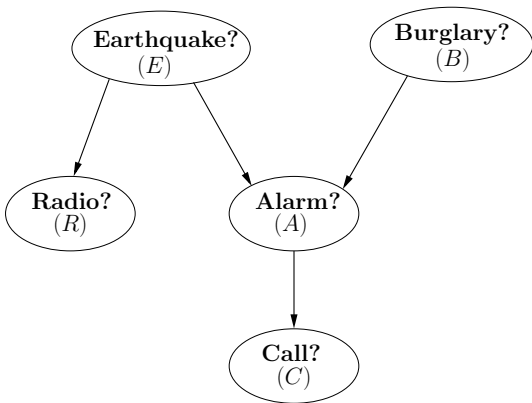
Local Markov property. Given a DAG structure G which encodes conditional independencies, we interpret G to compactly represent the following independence statements:

$$I(X, Pa_X, NonDesc_X) \quad \text{for all variables } X \text{ in DAG } G.$$

These conditional independencies are denoted as $Markov(G)$.

Local Markov property - Simple example

What conditional independencies are implied by the local Markov property for this DAG?



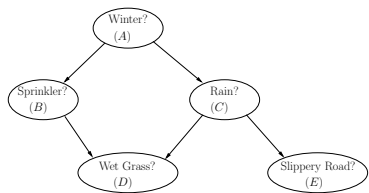
Bayesian network definition

A **Bayesian network** for a set of random variables \mathcal{X} is a pair (G, Θ) where

- G is a DAG over \mathcal{X} , called the *structure*
- Θ is a set of CPDs (always CPTs in this course), one for each $X \in \mathcal{X}$, called the *parameterization*

Sample Bayesian network

Structure



Parameterization

A	Θ_A
T	.6
F	.4

A	B	$\Theta_{B A}$
T	T	.2
T	F	.8
F	T	.75
F	F	.25

C	E	$\Theta_{E C}$
T	T	.7
T	F	.3
F	T	0
F	F	1

A	C	$\Theta_{C A}$
T	T	.8
T	F	.2
F	T	.1
F	F	.9

B	C	D	$\Theta_{D B,C}$
T	T	T	.95
T	T	F	.05
T	F	T	.9
T	F	F	.1
F	T	T	.8
F	T	F	.2
F	F	T	0
F	F	F	1

Chain rule of Bayesian networks

Given a Bayesian network \mathcal{B} and an instantiation \mathbf{z} , then

$$Pr(\mathbf{z}|\mathcal{B}) = \prod_{\theta_{x|pa} \sim \mathbf{z}} \theta_{x|pa}$$

That is, the probability of \mathbf{z} is the probability of each variable given its parents.

In the future, we will typically omit \mathcal{B} unless we need to distinguish between networks.

Class work

Suppose a Bayesian network has n variables, and each variable can take up to d values. Additionally, no variable has more than k parents.

How many parameters does an explicit distribution require?

How many parameters does a Bayesian network require? Use $O(\cdot)$.

Using the network on the handout, compute the following probabilities. Remember marginalization and Bayes' rule.

- $Pr(A = T, B = T, C = F, D = T, E = F)$
- $Pr(A = T, B = T, C = F)$
- $Pr(A = T, B = T | C = F)$
- $Pr(A = T, B = T | C = F, D = T, E = F)$

Graphoid axioms

The local Markov property tells us that

$$I(X, Pa_X, NonDesc_X) \quad \text{for all variables } X \text{ in DAG } G.$$

The **graphoid axioms** allow us to derive *global* independencies based on the graph structure.

- Symmetry
- Decomposition
- Weak union
- Contraction
- Intersection

Symmetry

If learning something about \mathbf{Y} tells us nothing about \mathbf{X} , then learning something about \mathbf{X} tells us nothing about \mathbf{Y} .

$$I(\mathbf{X}, \mathbf{Z}, \mathbf{Y}) \Leftrightarrow I(\mathbf{Y}, \mathbf{Z}, \mathbf{X})$$

Note that conditional independence is always w.r.t. some set of variables \mathbf{Z} as evidence.

Decomposition

If learning something about $\mathbf{Y} \cup \mathbf{W}$ tells us nothing about \mathbf{X} , then learning something about \mathbf{Y} or \mathbf{W} individually tells us nothing about \mathbf{X} .

$$I(\mathbf{X}, \mathbf{Z}, \mathbf{Y} \cup \mathbf{W}) \Rightarrow I(\mathbf{X}, \mathbf{Z}, \mathbf{Y}) \text{ and } I(\mathbf{X}, \mathbf{Z}, \mathbf{W})$$

This allows us to reason about subsets. In particular,

$$I(X, Pa_X, \mathbf{W}) \quad \text{for all } \mathbf{W} \in NonDesc_X.$$

Given the topological ordering on the variables, this axiom proves the chain rule for Bayesian networks.

Weak union

If learning something about $\mathbf{Y} \cup \mathbf{W}$ tells us nothing about \mathbf{X} , then \mathbf{Y} will not make \mathbf{W} relevant.

$$I(\mathbf{X}, \mathbf{Z}, \mathbf{Y} \cup \mathbf{W}) \Rightarrow I(\mathbf{X}, \mathbf{Z} \cup \mathbf{Y}, \mathbf{W})$$

In particular, X is independent of $\mathbf{W} \in \text{NonDesc}_X$ given Pa_X and the other non-descendants.

Contraction

If learning something about \mathbf{W} after learning \mathbf{Y} tells us nothing about \mathbf{X} , then the combined information $\mathbf{Y} \cup \mathbf{W}$ was irrelevant to begin with.

$$I(\mathbf{X}, \mathbf{Z}, \mathbf{Y}) \text{ and } I(\mathbf{X}, \mathbf{Z} \cup \mathbf{Y}, \mathbf{W}) \Rightarrow I(\mathbf{X}, \mathbf{Z}, \mathbf{Y} \cup \mathbf{W})$$

Intersection

If \mathbf{W} is irrelevant given \mathbf{Y} and \mathbf{Y} is irrelevant given \mathbf{W} , then both \mathbf{Y} and \mathbf{W} were irrelevant to begin with*.

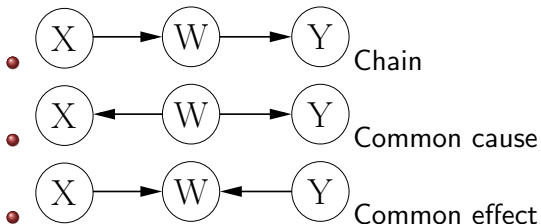
$$I(\mathbf{X}, \mathbf{Z} \cup \mathbf{W}, \mathbf{Y}) \text{ and } I(\mathbf{X}, \mathbf{Z} \cup \mathbf{Y}, \mathbf{W}) \Rightarrow I(\mathbf{X}, \mathbf{Z}, \mathbf{Y} \cup \mathbf{W})$$

* This holds only when the distribution is strictly positive.

Paths and valves

A **pipe** is a path from one variable to another.

Three types of **valves** compose a pipe.

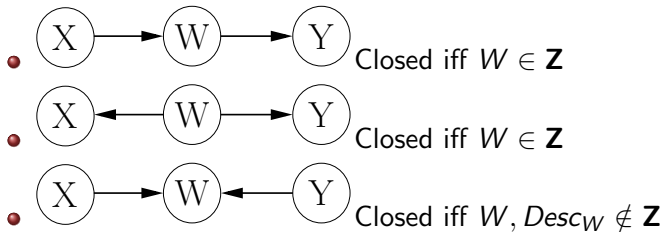


The “common effect” is often referred to as a “v-structure” when X and Y are not connected.

Open and closed valves

We can consider independence as “flow” through a pipe.

In particular, \mathbf{X} and \mathbf{Y} are independent given \mathbf{Z} if all pipes between them are closed. A pipe is closed if any of its valves are closed.



Formally, this is called **d-separation** and is written $dsep(\mathbf{X}, \mathbf{Z}, \mathbf{Y})$.

Complexity of d-separation

How many paths are there between nodes in **X** and **Y**?

So is d-separation practically useful?

Complexity of d-separation

How many paths are there between nodes in \mathbf{X} and \mathbf{Y} ?

So is d-separation practically useful?

Testing $dsep(\mathbf{X}, \mathbf{Z}, \mathbf{Y})$ is equivalent to testing if \mathbf{X} and \mathbf{Y} are connected in a new graph.

- Delete outgoing edges from nodes in \mathbf{Z}
- (Recursively) Delete any leaf which does not belong to $\mathbf{X} \cup \mathbf{Y} \cup \mathbf{Z}$

So we can determine d-separation in linear time and space.

Markov blanket

The **Markov blanket** for a variable X is a set of variables \mathbf{B} such that $X \notin \mathbf{B}$ and $I(X, \mathbf{B}, \mathbf{V} \setminus \mathbf{B} \setminus \{X\})$.

Which variables \mathbf{B} d-separate a variable X from all of the other variables ($\mathbf{V} \setminus \mathbf{B} \setminus \{X\}$)?

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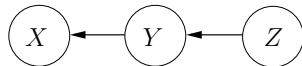
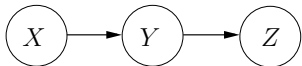
The parents, children and spouses.

Soundness, completeness and equivalence

Every independence found by d-separation is true for any distribution which factorizes according to the BN.

There *could* be independencies that d-separation cannot find (because it only uses the structure).

What are the independencies given by these networks?



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Different network structures can result in the same independencies. These networks are **Markov equivalent**.

Terminology for d-separation

A BN is an **independence map** (I-MAP) of Pr if every independence declared by d-separation holds in Pr .

An I-MAP is **minimal** if it ceases to be an I-MAP when any edge is deleted.

A BN is a **dependency map** (D-MAP) of Pr if the lack of d-separation implies a dependence in Pr .

Class work

Use the network on the handout (the Asian network) to answer the following independence questions.

- List the Markov blanket of all variables.
- $dsep(P, \{A, T, C, S, B, D\}, X)$
- $dsep(P, \{T, C\}, \{A, S\})$
- $dsep(P, \{C, D\}, B)$
- $dsep(B, S, P)$
- $dsep(\{B, C\}, S, P)$
- $dsep(\{B, C\}, P, \{A, T, X\})$

Class work

Use the network on the handout (the Asian network) to answer the following independence questions.

- List the Markov blanket of all variables.
- $dsep(P, \{A, T, C, S, B, D\}, X)$ No
- $dsep(P, \{T, C\}, \{A, S\})$ Yes
- $dsep(P, \{C, D\}, B)$ No
- $dsep(B, S, P)$ Yes
- $dsep(\{B, C\}, S, P)$ No
- $dsep(\{B, C\}, P, \{A, T, X\})$ No

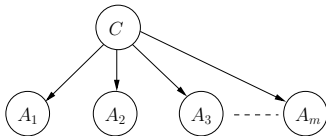
Recap

During this class, we discussed

- Basic terminology and notation for probability and graphs
- Bayesian networks as a parameterized model
- BNs as a factorization of a joint probability distribution
- BNs as a concise representation of conditional independencies based on d-separation
- Equivalence among BNs based on induced independencies

Next time in probabilistic models

- Discriminative vs. generative learning
- Multinomial naive Bayes for document classification



- Hidden Markov models for gene prediction

