On Probabilistic Modeling and Bayesian Networks

Petri Myllymäki, Ph.D., Academy Research Fellow Complex Systems Computation Group (CoSCo) Helsinki Institute for Information Technology (HIIT) Finland

Petri.Myllymaki@hiit.FI, http://www.hiit.FI/Petri.Myllymaki/

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Uncertain reasoning and data mining

- Real-world environments are complex
 - pure logic is not a feasible tool for describing the underlying stochastic rules
- It is possible to learn about the underlying uncertain dependencies via observations
 - as shown by the success of some human experts
- Obtaining and communicating this type of deep knowledge is difficult
 - the objective: to develop clever algorithms and methods that help people in these tasks

Different approaches to uncertain reasoning

- (Bayesian) probability theory
- neural networks
- fuzzy logic
- possibility measures
- · case-based reasoning
- kernel estimators
- support vector machines
- etc....



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Two perspectives on probability

- The classical frequentist approach (Fisher, Neyman, Cramer, ...)
 - probability of an event is the long-run frequency with which it happens
 - but what then is the probability that the world ends tomorrow?
 - the goal is to find "the true model"
 - hypothesis testing, classical orthodox statistics
- The modern subjectivist approach (Bernoulli, Bayes, Laplace, Jeffreys, Lindley, Jaynes, ...)
 - probability is a degree of belief
 - models are believed to be true with some probability ("All models are false, but some are useful")
 - ⇒ Bayesian networks



The Bayes rule







Data D



Thomas Bayes (1701-1761)

$$P(M|D) = \frac{P(D|M)P(M)}{P(D)} \propto P(D|M)P(M)$$

- "The probability of a model M after observing data D is proportional to the likelihood of the data D assuming that M is true, times the prior probability of M."
- Bayesianism = subjective probability theory

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Advantages of the Bayesian approach

- A consistent calculus for uncertain reasoning
 - the Cox theorem: constructing a non-Bayesian consistent calculus is difficult
- Decision theory offers a theoretical framework for optimal decision-making
 - requires probabilities!
- Transparency
 - A "white box": all the model parameters have a clear semantic interpretation
 - The certainty associated to probabilistic predictions is intuitively understandable
 - cf. "black boxes" like neural networks

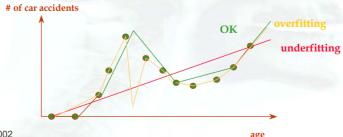
More advantages of Bayesianism

- Versatility
 - Probabilistic inference: compute P(what you want to know | what you already know).
 - cf. single-purpose models like decision trees
- An elegant framework for learning models from data
 - Works with any size data sets
 - Can be combined with prior expert knowledge
 - Incorporates an automatic Occam's razor principle, avoids overfitting

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The Occam's razor principle

- "If two models of different complexity both fit the data approximately equally well, then the simpler one usually is a better predictive model in the future."
- Overfitting: fitting an overly complex model to the observed data



Bayesian metric for learning

$$P(M|D) = \frac{P(D|M)P(M)}{P(D)} \propto P(D|M)P(M)$$

- P(D) is constant with respect to different models, so it can be considered constant.
- Prior P(M) can be determined by experts, or ignored if no prior knowledge is available.
- The evidence criterion (data marginal likelihood) P(D|M) is an integral over the model parameters, which causes the criterion to automatically penalize too complex models.



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Probability theory in practice

- Bayesian networks: a family of probabilistic models and algorithms enabling computationally efficient
 - 1. Probabilistic inference
 - 2. Automated learning of models from sample data
- Based on novel discoveries made in the last two decades by people like Pearl, Lauritzen, Spiegelhalter and many others
- Commercial exploitation growing fast, but still in its infant state

Bayesian networks

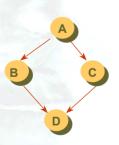
- A Bayesian network is a model of probabilistic dependencies between the domain variables.
- The model can be described as a list of dependencies, but is is usually more convenient to express them in a graphical form as a directed acyclic network.
- The nodes in the network correspond to the domain variables, and the arcs reveal the underlying dependencies, i.e., the hidden structure of the domain of your data.
- The strengths of the dependencies are modeled as conditional probability distributions (not shown in the graph).



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Dependencies and Bayesian networks

- The Bayesian network on the right represents the following list of dependencies:
 - A and B are dependent on each other no matter what we know and what we don't know about C or D (or both).
 - A and C are dependent on each other no matter what we know and what we don't know about B or D (or both).
 - B and D are dependent on each other no matter what we know and what we don't know about A or C (or both).
 - C and D are dependent on each other no matter what we know and what we don't know about A or B (or both).
 - A and D are dependent on each other if we do not know both B and C.
 - B and C are dependent on each other if we know D or if we do not know D and also do not know A.



Bayesian networks: the textbook definition

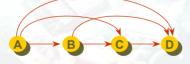
• A Bayesian (belief) network representation for a probability distribution P on a domain $(X_1,...,X_n)$ is a pair (G,θ) , where G is a directed acyclic graph whose nodes correspond to the variables $X_1,...,X_n$, and whose topology satisfies the following: each variable X is conditionally independent of all of its non-descendants in G, given its set of parents F_X , and no proper subset of F_X satisfies this condition. The second component θ is a set consisting of all the conditional probabilities of the form $P(X|F_X)$.

 $\theta = \{P(+a), P(+b|+a), P(+b|-a), P(+c|+a), P(+c|-a), P(+d|+b,+c), P(+d|-b,+c), P(+d|+b,-c), P(+d|-b,-c)\}$

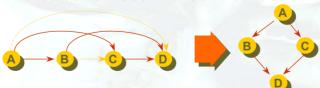
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A more intuitive description

• From the axioms of probability theory, it follows that P(a,b,c,d)=P(a)P(b|a)P(c|a,b)P(d|a,b,c)



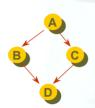
• Assume: P(c|a,b)=P(c|a) and P(d|a,b,c)=P(d|b,c)



$$P(x_1,...,x_n) = \prod_{i=1}^n P(x_i|F_{X_i})$$

Why does it work?

- simple conditional probabilities are easier to determine than the full joint probabilities
- in many domains, the underlying structure corresponds to relatively sparse networks, so only a small number of conditional probabilities is needed



 $\begin{array}{l} P(+a,+b,+c,+d) = P(+a)P(+b|+a)P(+c|+a)P(+d|+b,+c) \\ P(-a,+b,+c,+d) = P(-a)P(+b|-a)P(+c|-a)P(+d|+b,+c) \\ P(-a,-b,+c,+d) = P(-a)P(-b|-a)P(+c|-a)P(+d|-b,+c) \\ P(-a,-b,-c,+d) = P(-a)P(-b|-a)P(-c|-a)P(+d|-b,-c) \\ P(-a,-b,-c,-d) = P(-a)P(-b|-a)P(-c|-a)P(-d|-b,-c) \\ P(+a,-b,-c,-d) = P(+a)P(-b|+a)P(-c|+a)P(-d|-b,-c) \end{array}$

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Computing the evidence

• Under certain natural technical assumptions, the *evidence* criterion P(D|M) for a given BN structure M and database D can be computed exactly in feasible time:



$$P(D|M) = \int P(D|M,\theta)P(\theta)d\theta = \prod_{i=1}^{n} \prod_{j=1}^{q_i} \frac{\Gamma(N'_{ij})}{\Gamma(N'_{ij}+N_{ij})} \prod_{k=1}^{r_i} \frac{\Gamma(N'_{ijk}+N_{ijk})}{\Gamma(N'_{ijk})},$$

where: n is the number of variables in M,

 q_i is the number of predecessors of X_i

 r_i is the number of possible values for X_i

 N_{iik} is the number of cases in D, where $X_i = x_{ik}$ and $F_i = f_{ii}$

 N_{ii}^{jk} is the number of cases in D where $F_i = f_{ij}$

 N_{ijk}^{y} is the Dirichlet exponent of θ_{ijk} , "a prior number of cases" identical to

the N_{iik} in D.

 N_{ii} is the "prior number of cases" identical to the N_{ij} in D.

