

Modeling Energy Constrained Routing in Selfish Ad Hoc Networks

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Introduction

- Nodes in ad hoc networks are energy constrained and potentially selfish \Rightarrow defining rational and optimal behavior is complicated
- the effects of selfishness have been widely studied
- but the effects of energy not
 - intuitively, when nodes condition their behavior on their energy, this leads to a more balanced resource usage
 - thus, energy optimization may well be the rational strategy
 - accordingly, in order to act optimally, a node should try to model the energy of other nodes
- Questions:
 - how to capture this formally?
 - how to build mechanisms that allow nodes to act optimally?

Contribution

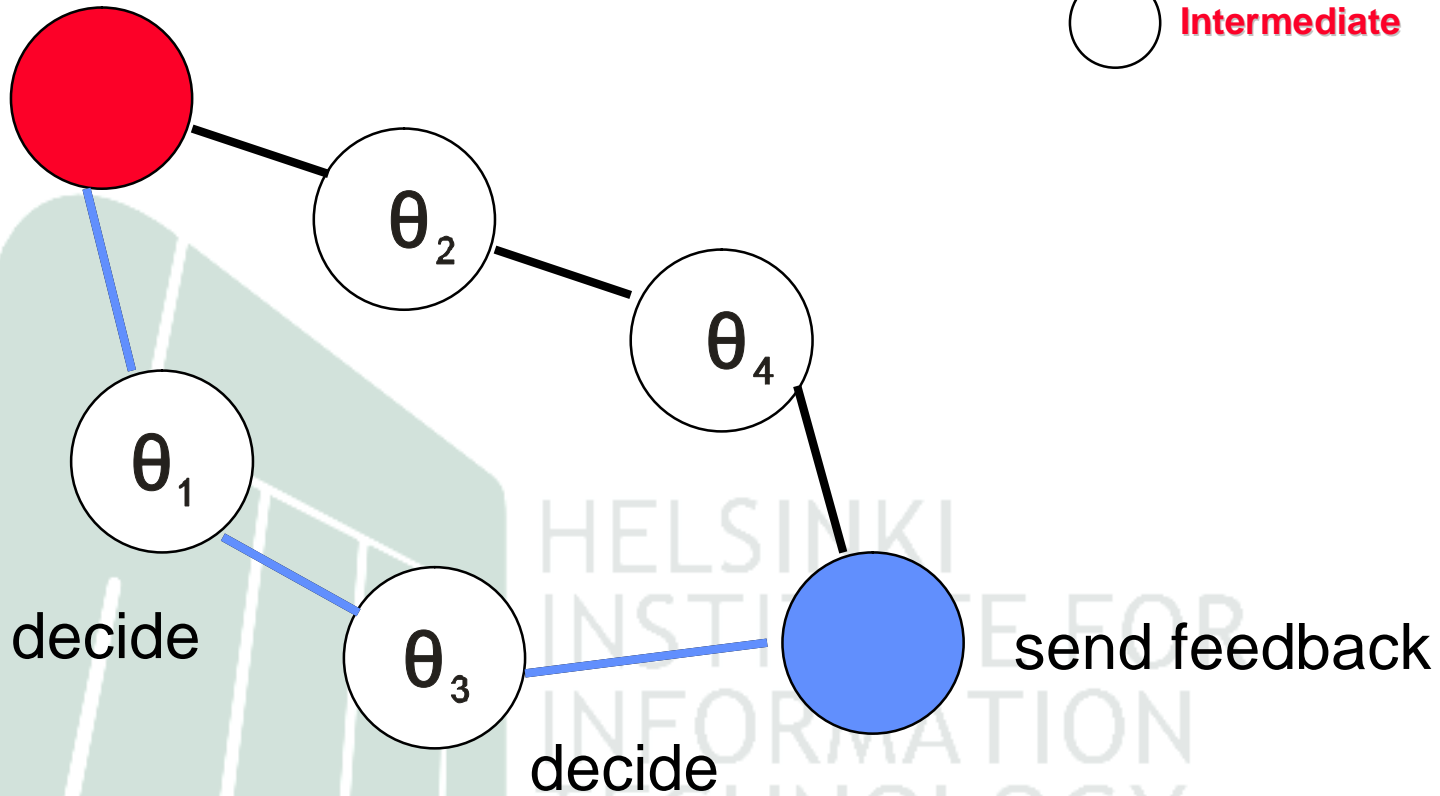
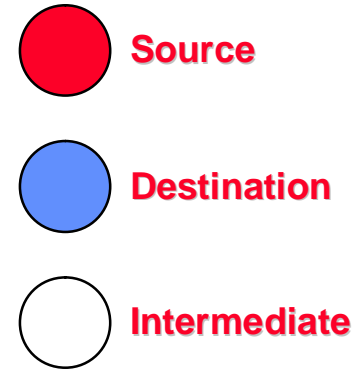
- We present a game theoretic model that
 - models the energy of the nodes and links it with the behavior of nodes
 - models the effect of selfishness
- We also present a mechanism that
 - allows nodes to learn optimal strategies over time
 - is guaranteed to converge to a sequential equilibrium point
- And present simulation results for the model

General Framework

- We consider repeated Bayesian games in an adaptive learning framework
 - agents optimize immediate (single shot) gain
 - thus differs from standard repeated games
 - agents hold theories about parameters of interest
 - in our case selfishness and energy
 - the sequence of theories forms a *learning process* that is *adaptive* if
 - the action selection probabilities of the agents eventually come close to empirical frequencies
 - and the beliefs of the agents converge.
 - closely related to stochastic approximation theory

Model Intuitively

optimize route, decide how many of the packets to send and send them



The Game Structure

- Source node
 1. Discover routes to the destination
 2. Estimate the “goodness” of the routes
 3. Select the route to use
 4. Gather feedback and update theories
- Intermediate node
 - Optimizes an utility function and selects the optimal action as given by the utility function
 - The utility function can utilize estimates about the behavior of the source

Estimating the Goodness of Routes

- Once the source has information about available routes, it calculates a score for each route
- The score combines
 - the energy and selfishness estimates
 - the importance of energy
 - the cost and the value of the packets
- We use the expected utility for a path
 - first we estimate the probability that a given number of packets arrives at the correct destination $\mu(P) = \prod [\alpha \varphi + \beta \psi]$
 - next, we combine this with the utility of the packets
$$u(s, P) = \mu(P) [h(s) - g(s)]$$

Intermediate Nodes

- The behavior strategies of the intermediate nodes are assumed to be
 - weighted linear combinations of the selfishness of the source and the remaining energy of the intermediate node
 - the weights represent importance in the individual components
 - thus we have a punishment mechanism
 - and we also have a part that depends on the current energy of the nodes

$$\sigma = \alpha \varphi + \beta \psi$$

Obtaining Feedback

- In order to update the theories of the nodes, they require feedback
 - i.e., how many packets finally arrived at the destination
 - in order to accomplish this, we need
 - packet timers
 - acknowledgements
 - if the packets are not acknowledged before the timer goes off, they are considered to be dropped

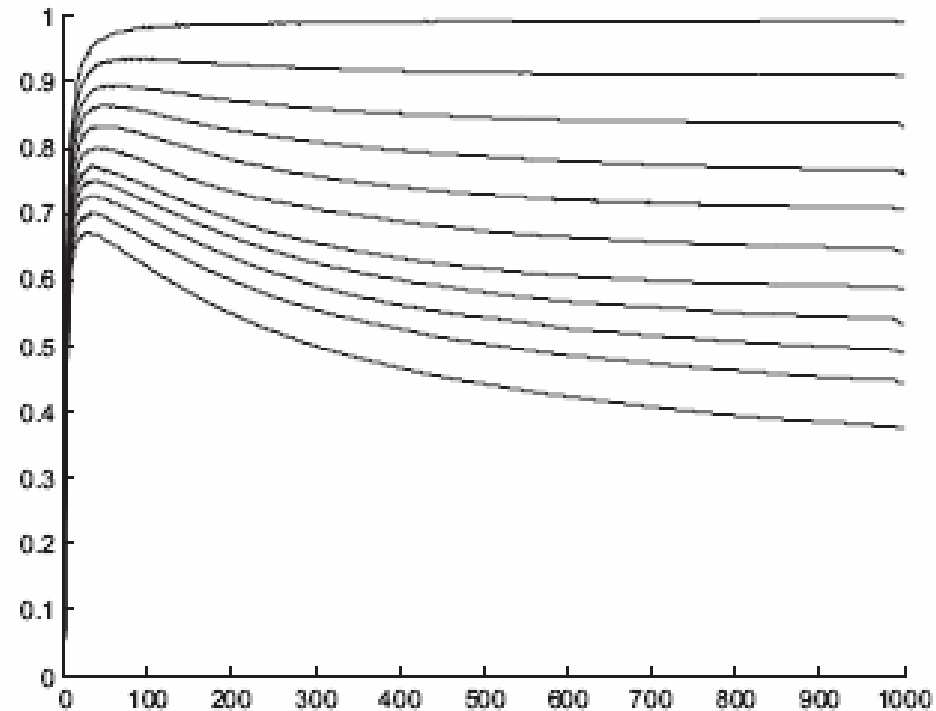
Learning Optimal Strategies

- It turns out that a learning process can be shown to converge to an equilibrium when
 - the beliefs are updated using the Bayes' rule
 - strategies are selected using reinforcement learning rules and random experimentation occurs often enough
- In our case, we use the rule $1/k$, where k is the current iterate, to select suboptimal actions
 - Also other rules possible, large literature on this in the field of reinforcement learning
- For the convergence proof, see the paper.

Experimental Setup

- We tested the model using randomly generated network topologies
 - constrained uniform deployment: nodes were not allowed to be “too close” to each other
 - random waypoint model with constant speed
 - Poisson distributed traffic
- In each setup, the values of the importance parameters were the same for all nodes
 - tested with different initial values of the importance parameters
 - each initial configuration repeated 30 times
- In the experiments we ignore selfishness for clarity

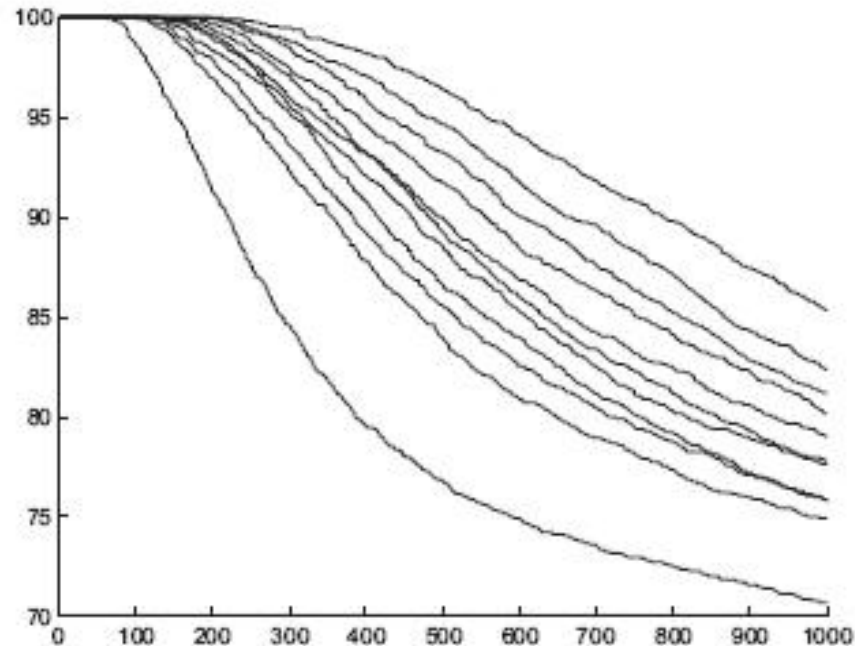
Results 1: Success rate of nodes



- **Success rate of nodes**

- Importance of energy class varied (in steps of 0.1) between 0.0 and 1.0
- Topmost, importance of energy = 0.0
- Subsequent, increase by 0.1

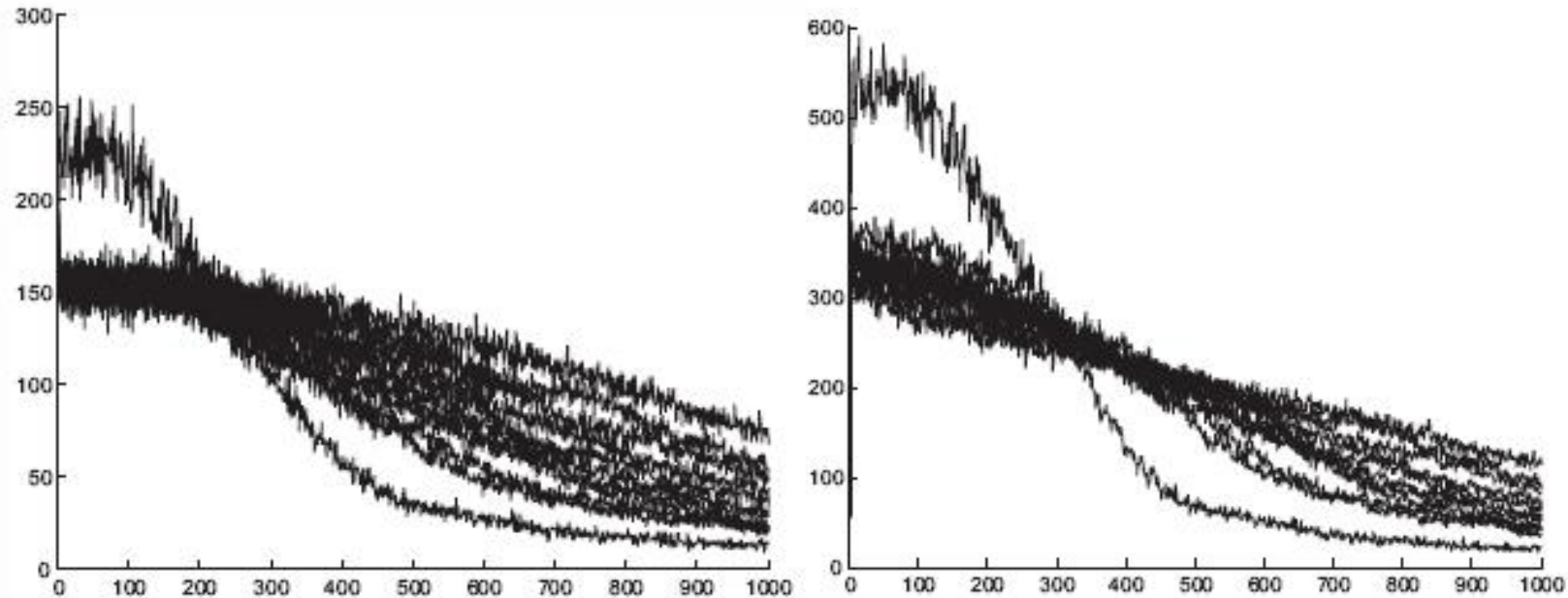
Results 2: Amount of nodes alive



- **Amount of nodes that are alive**

- Importance of energy class varied (in steps of 0.1) between 0.0 and 1.0
- Topmost, importance of energy = 1.0
- Subsequent, decrease by 0.1

Results 3: Packets sent and forwarded



- **Amount of packets sent (left) and forwarded (right)**
 - Importance of energy class varied (in steps of 0.1) between 0.0 and 1.0
 - Steepest descent, importance of energy = 0.0
 - Subsequent, increase by 0.1

Conclusions

- Our simulations indicate that energy optimization in decision making affects network lifetime è this should be the rational choice of the nodes
 - The results also indicate that nodes can learn a reasonable strategy when energy influences decisions
 - Though the results show that this easily results in a decrease of overall performance
- è building mechanisms that are able to model the energy of others can prove useful in highly resource constrained environments

Summary

- We have presented a game theoretic model that captures selfishness and resource constraints of devices
- We presented a mechanism for learning optimal strategies over time
- And we presented simulation results for the model
- Our model shows that:
 - Energy optimization is likely to be the rational choice of nodes
 - But other devices can learn to optimize their behavior also in this kind of settings