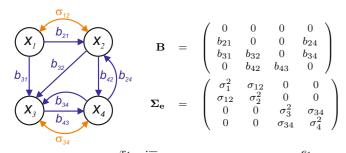
# Causal Discovery for Linear Cyclic Models with Latent Variables

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## Linear Cyclic Model with Latent Variables



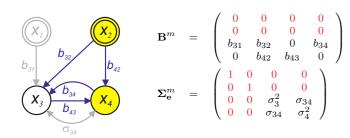
$$\mathbf{x} := \mathbf{B}\mathbf{x} + \mathbf{e} \quad \Leftrightarrow \quad \begin{aligned} x_2 &:= b_{21}x_1 &+ b_{24}x_4 + e_2 \\ x_3 &:= b_{31}x_1 + b_{32}x_2 + b_{34}x_4 + e_3 \\ x_4 &:= b_{42}x_2 + b_{43}x_3 + e_4 \end{aligned}$$

- $\bigstar$  The model is parametrized by B and  $\mathsf{cov}(e) = \Sigma_e.$
- ★ Behaviour at equilibrium:

$$\begin{array}{rcl} \mathbf{x}_t &:= & \mathbf{B}\mathbf{x}_{t-1} + \mathbf{e} & \leftarrow \mathsf{background conditions invariant} \\ \mathbf{x}_\infty &:= & \mathbf{B}^\infty \mathbf{x}_0 + (\mathbf{I} + \mathbf{B} + \mathbf{B}^2 + \cdots) \mathbf{e} \\ \mathbf{x}_\infty &:= & (\mathbf{I} - \mathbf{B})^{-1} \mathbf{e} \\ \mathbf{e} \sim \mathrm{N}(\mathbf{0}, \mathbf{\Sigma}_\mathbf{e}) & \Rightarrow & \mathbf{x}_\infty \sim \mathrm{N}(\mathbf{0}, (\mathbf{I} - \mathbf{B})^{-1} \mathbf{\Sigma}_\mathbf{e} (\mathbf{I} - \mathbf{B})^{-T}) \end{array}$$

- A1 Self cycles are not identifiable from equilibrium data, so assuming  $\forall i: b_{ii} = 0$ .
- A2 The model and all possible manipulated models are assumed stable: absolute of the eigenvalues of  ${\bf B}$  and  ${\bf B}^m$ :s must all be less than 1.

## Interventions & Experimental Effects



$$\mathbf{C}_{x}^{k} = (\mathbf{I} - \mathbf{B}^{m})^{-1} \mathbf{\Sigma}_{\mathbf{e}}^{m} (\mathbf{I} - \mathbf{B}^{m})^{-T} = \begin{array}{c|c} & \text{independent randomizations} \\ \downarrow & \downarrow & \ddots & \downarrow \\ \hline 0 & 1 & \ddots & \ddots \\ \hline t(x_{1} \leadsto x_{3} || \{x_{1}, x_{2}\}) & t(x_{2} \leadsto x_{3} || \{x_{1}, x_{2}\}) & v_{3}^{2} & \ddots \\ \hline t(x_{1} \leadsto x_{4} || \{x_{1}, x_{2}\}) & t(x_{2} \leadsto x_{4} || \{x_{1}, x_{2}\}) & v_{34} & v_{4}^{2} \end{array} \right)$$

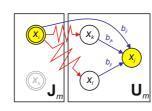
experimental effects

between observed

$$\begin{array}{lll} \mathbf{t}(\mathbf{x_2} \leadsto \mathbf{x_4} || \{\mathbf{x_1}, \mathbf{x_2}\}) & = & \text{Regression coefficient of } x_2 \text{ on } x_4 \\ & = & \text{Sum of all open paths from } x_2 \text{ to } x_4 \\ & = & b_{42} + b_{43}b_{32} + b_{43}b_{34}b_{42} + \cdots \\ & = & (b_{42} + b_{43}b_{32})(1 + b_{43}b_{34} + \cdots) \\ & \text{nonlinear} \rightarrow & = & \frac{b_{42} + b_{43}b_{32}}{1 - b_{43}b_{34}} \\ & = & b_{42} + \frac{b_{32} + b_{34}b_{42}}{1 - b_{43}b_{34}} b_{43} \end{array}$$

 $\mbox{linear} \rightarrow \ = \ b_{42} + t(x_2 {\scriptstyle \leadsto} x_3 || \{x_1, x_2\}) b_{43}$ 

## Linear Equations



$$t(x_i \leadsto x_j || \mathbf{J}_m) = b_{ji} + \sum_{x_k \in \mathbf{U}_m \setminus x_j} t(x_i \leadsto x_k || \mathbf{J}_m) b_{jk}$$

#### Method

- 1. Input covariance matrices  $\mathbf{C}_x^1, \cdots \mathbf{C}_x^k$
- 2. Form linear equations

$$\begin{pmatrix} \mathbf{K}_1 & & \\ & \mathbf{K}_2 & \\ & & \ddots \end{pmatrix} \begin{pmatrix} b_{12} \\ \vdots \\ b_{1n} \\ \hline b_{21} \\ \vdots \end{pmatrix} = \begin{pmatrix} t(x_2 \leadsto x_1 || \bullet) \\ \vdots \\ \frac{t(x_n \leadsto x_1 || \bullet)}{t(x_1 \leadsto x_2 || \bullet)} \\ \vdots \end{pmatrix}$$

- 3. Solve for direct effects  $b_{ij}$ .
- 4. Get the covariances of the error terms  $\sigma_{ij}$  from an experiment where both  $x_i$  and  $x_j$  are observed with the formula

$$\sigma_{ij} = [(\mathbf{I} - \mathbf{B}^m)\mathbf{C}_x^k(\mathbf{I} - \mathbf{B}^m)^T][i, j]$$

## Identifiability & Underdetermination

#### Identifiability theorem

Given a sequence of experiments the model  $(\mathbf{B}, \Sigma_{\mathbf{e}})$  is fully identified by the method **if and only if** for each **ordered** pair of variables  $(x_i, x_j)$  there is

- $\bigstar$  an experiment where  $x_i$  is **intervened on** and  $x_j$  is **observed** (Pair Condition), and
- $\bigstar$  another experiment where both  $x_i$  and  $x_j$  are **observed** (Covariance Condition).
- 1. Say we have done experiments intervening on variables  $\{x_1\}$ ,  $\{x_1, x_2\}$ ,  $\{x_3\}$ .

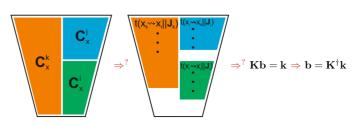
$$\operatorname{PC}: \left( \begin{array}{cccc} \cdot & \times & \checkmark & \times \\ \checkmark & \cdot & \checkmark & \times \\ \checkmark & \checkmark & \cdot & \times \\ \checkmark & \checkmark & \checkmark & \cdot \end{array} \right), \quad \operatorname{COV}: \left( \begin{array}{cccc} \cdot & \cdot & \cdot & \cdot \\ \checkmark & \cdot & \cdot & \cdot \\ \checkmark & \checkmark & \cdot & \cdot \\ \checkmark & \checkmark & \checkmark & \cdot \end{array} \right)$$

2. Which parameters are identified in the general case?

$$\mathbf{B}:\left(egin{array}{cccc} \cdot & imes & imes & imes \ imes & imes & imes & imes & imes \ imes & imes & imes & imes & imes & imes \ imes & imes & imes & imes & imes & imes & imes \ imes & imes$$

- $\bigstar$  Generally, for identifying  $b_{ji}$ , pair condition must be satisfied for all pairs  $(\bullet, j)$ .
- $\bigstar$  If pair condition for (i,j) is not satisfied, then  $b_{ji}$  is never identified

## Completeness



#### Completeness theorem

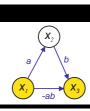
Given the data covariance matrices from a set of experiments, for determining the direct effects  $b_{ji}$ , the identifiability condition (Pair Condition) of the approach is **necessary** for any method.

This hinges on the fact that if two different direct effects matrices  ${\bf B}$  and  $\widehat{\bf B}$  produce the same experimental effects in a given set of experiments, the models  $({\bf B}, \Sigma_{\bf e})$  and  $(\widehat{\bf B}, ({\bf I}-\widehat{\bf B})({\bf I}-{\bf B})^{-1}\Sigma_{\bf e}({\bf I}-{\bf B})^{-T}({\bf I}-\widehat{\bf B})^T)$  can be shown to produce the same covariance matrices for those experiments as well.

## **Assuming Faithfulness**

## Faithfulness in linear models

Any independence relation between variables is not the result of several exactly cancelling pathways.



For every experimental dataset

1. Run a search for finding independencies. Add constraint equations from skeleton rule:

#### Skeleton rule

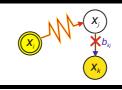
$$\begin{array}{c}
x_i \perp x_j \mid S \\
x_j \notin \mathbf{J}_m \\
b_{ji} = 0
\end{array}$$



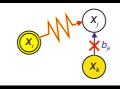
2. Add more constraint equations from orientation rules:

## Orientation rule 1

$$\frac{t(x_i \leadsto x_k || \mathbf{J}_m) = 0}{t(x_i \leadsto x_j || \mathbf{J}_m) \neq 0}$$
$$\frac{b_{kj} = 0}{}$$



## Orientation rule 2



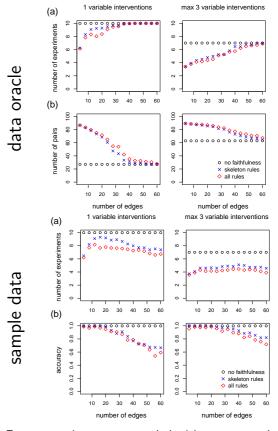
3. Take into account the additional structure found when selecting the next experiment.

## **Experiment Selection**

- 1. Select the experiment that satisfies the pair condition for most new pairs
- If any parameters are identified, consider the pair condition for the corresponding pairs as satisfied.

#### **Test Results**

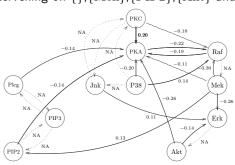
Selecting the experiment in such a way that the model is learned accurately with the fewest number of experiments.



- ★ Fewer experiments are needed with sparse graphs.
- ★ More structure is discovered earlier on with sparse graphs.
- $\bigstar$  With denser graphs the accuracy gets worse.

## Sachs et al Flow Cytometry Data

Learning as much of the structure as possible given only 5 experiments, intervening on  $\{\},\{Mek\},\{PIP2\},\{Akt\}\}$  and  $\{PKC\}$ .



 $\bigstar$  Pair condition was satisfied for only 40/110 of the pairs, yet when assuming faithfulness most of parameters have been identified.

## Summary

- ★ Method for learning linear cyclic models with latent variables using randomized experiments.
- ★ Complete with regard to search space and assumptions.
- ★ Necessary and sufficient identifiability condition.
- ★ Underdetermination characterized.
- ★ Faithfulness incorporated.
- ★ R-code available.