Causal Discovery of Linear Cyclic Models from Multiple Experimental Data Sets with Overlapping Variables

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- No joint causal sufficiency: there may be latent confounders not measured in any of the data sets
- The underlying structure may be **cyclic**
- Causal relations restricted to be linear

Background: Linear Cyclic Model with Latent Variables

• Over the joint set of variables in the overlapping experiments

F

$$\mathbf{x} := b(y \to x)y + b(z \to x)z + e_x$$

$$y := b(x \to y)x + b(z \to y)z + e_y$$

$$z := b(x \to w)x + b(y \to z)y + e_z$$

$$\mathbf{x} := \mathbf{B}\mathbf{x} + \mathbf{e}, \quad \mathbf{e} \sim \mathcal{N}(\mathbf{0}, \mathbf{\Sigma}_{\mathbf{e}})$$

$$\mathbf{B} = \begin{pmatrix} 0 & b(y \to x) & b(z \to x) \\ b(x \to y) & 0 & b(z \to y) \\ b(x \to z) & b(y \to z) & 0 \end{pmatrix} \mathbf{\Sigma}_{\mathbf{e}} = \begin{pmatrix} \sigma_x^2 & \sigma_{xy} & \sigma_{xz} \\ \sigma_{xy} & \sigma_y^2 & \sigma_{yz} \\ \sigma_{xz} & \sigma_{yz} & \sigma_z^2 \end{pmatrix}$$

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Latent confounding represented by correlated disturbancesGenerated distribution

F

$$\begin{split} \mathbf{x} &= (\mathbf{I} - \mathbf{B})^{-1} \mathbf{e} \\ \mathbf{x} &\sim \quad \mathcal{N}(\mathbf{0}, \mathbf{\Sigma}_{\mathbf{x}}), \text{ where } \mathbf{\Sigma}_{\mathbf{x}} = (\mathbf{I} - \mathbf{B})^{-1} \mathbf{\Sigma}_{\mathbf{e}} (\mathbf{I} - \mathbf{B})^{-T} \end{split}$$

Problem Formalization



Experiment 1		
x	У	Z
-0.3	-0.7	?
:	÷	÷
int.	obs.	unobs.

 \Rightarrow **B** =?

 $\mathbf{x} := \mathbf{B}\mathbf{x} + \mathbf{e}, \quad \mathbf{e} \sim \mathcal{N}(\mathbf{0}, \mathbf{\Sigma}_{\mathbf{e}})$

Experiment 2		
		7
^	у	2
?	-0.1	0.2
:	:	÷
unobs.	obs.	int.

- Given multiple data sets
 - in which some variables are surgically intervened on, some are (passively) observed and some are unobserved
 - generated by a (manipulated) linear cyclic model with latent variables (B, Σ_e) over the joint set of variables in the experiments
- Identify as many causal relations among the joint set of variables in the experiments, i.e. entries in **B**, such as $b(x \rightarrow y)$, as possible.

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intervened variable observed variable

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$$t(x \leftrightarrow y) || f(y)$$

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$$t(x \leftrightarrow y || \mathcal{V} \setminus y) = b(x \rightarrow y)$$

$$t(x \leftrightarrow y || x) = (b(x \rightarrow y) + b(x \rightarrow z)b(z \rightarrow y))$$

$$\cdot (1 + b(y \rightarrow z)b(z \rightarrow y) + \cdots)$$

$$= \frac{b(x \rightarrow y) + b(x \rightarrow z)b(z \rightarrow y)}{1 - b(y \rightarrow z)b(z \rightarrow y)}$$

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From an experiment where x and w are intervened on and y is observed the following exp. effects can be estimated by regression

$$t(x \rightarrow y || x, w) = 0.227$$
 $t(w \rightarrow y || x, w) = -0.345$

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• When can we infer coeffs $b(x \rightarrow y)$ from the observed exp. effects?

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- A sufficient condition for fully identifying **B** is the pair condition: for each ordered pair of variables $x \quad y \quad z$ (u, v) there is an experiment such that $y \quad \checkmark \quad \checkmark$ u is intervened on and v is (passively) observed. $z \quad \checkmark \quad \checkmark$ • A sufficient condition for fully identifying **B** is **the** u is intervened on and v is (passively) observed.



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- Their learning algorithm is still Complete: Without further assumptions on the model space, the algorithm extracts all available information about \mathbf{B} .

- We can extend the identifiability results given by Eberhardt et al. (2010) for experimental data sets sharing the same variables:
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- Also Worst Case Necessary: If the pair condition is not satisfied for some ordered pair of variables, there exist distinct Bs that have identical distributions for the given experiments.
- Their learning algorithm is still Complete: Without further assumptions on the model space, the algorithm extracts all available information about **B**.
- Usually, the overlapping experiments will not satisfy the pair condition and very little will be learned, so further assumptions are needed.

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- No exactly canceling paths



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- If we observe $x \perp y$:
 - Directed paths

 $t(x \rightarrow y||x) = 0, \quad t(y \rightarrow x||y) = 0$

- Paths through specific variables $t(x \leftrightarrow z || x) t(z \leftrightarrow y || z) = 0, \quad t(y \leftrightarrow z || y) t(z \leftrightarrow x || z) = 0$
- Paths to each variable from a possible confounder $t(z \rightsquigarrow x || z) t(z \rightsquigarrow y || z) = 0$



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These apply for all supersets of the intervention sets. For example:

$$\underbrace{t(x \rightsquigarrow y || x)}_{\text{paths from x to } y} = 0 \implies \underbrace{t(x \rightsquigarrow y || x, z)}_{\text{not through } z} = 0$$



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paths from x to y

not through z

• Other rules extensions to cyclic models from Claassen et al. (2011)



Some 'observed' experimental effects.

$$t(x \rightarrow z || x, w) = 0.654, \quad t(w \rightarrow y || x, w) = -0.345, \quad \dots$$

Some equations implied by faithfulness & detected independencies:

$$t(x \rightsquigarrow y || x, w) = 0, \quad t(x \rightsquigarrow z || x, w) t(z \rightsquigarrow y || x, z, w) = 0, \quad \dots$$

• Output the known coefficients $b(x \rightarrow y)$

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A. Hyttinen Causal Discovery of Linear Cyclic Models from Multiple Experimental Data Sets with Overlapping Var 17.8.2012 8 / 11

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- Generate all **constraint** equations relating exp. effects.

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- Rerun: more equations might become linear!
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Toy Example



$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Experiment 1		
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	x	y	W
$\frac{ \vdots \vdots \vdots}{t(x \rightsquigarrow y x) = 0.5}$ $\frac{t(x \rightsquigarrow y x) = 0.15}{t(x \rightsquigarrow w x) = 0.15}$	-0.2	0.8	1.2
$\overline{t(x \rightsquigarrow y x)} = 0.5$ $t(x \rightsquigarrow w x) = 0.15$:	:	÷
$x \perp w y x$			

Experiment 2			
У	Z	W	
-0.3	-0.7	1.4	
÷	÷	:	
y ⊥ z			
y⊥z∣w			

Toy Example



Experiment 1 х w **-0.2** 0.8 1.2. . . $t(x \rightsquigarrow y || x) = 0.5$ $t(x \rightsquigarrow w || x) = 0.15$ $x \perp w | y | | x$

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	У	Z	W	
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	:	:	÷	
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y <u>↓</u> z w				

N.a. faithfulness:



(double-headed edges not shown here)

Toy Example



Experiment 2			
y	Z	W	
-0.3	-0.7	1.4	
:	:	÷	
y⊥⊥z			
<i>y</i> <u>↓</u> <i>z</i> <i>w</i>			

Linear Inference:



(double-headed edges not shown here)

Simulations

- 100 random models with 6 obs. variables, 5 random exp. settings
- 624 present links (20%), 2376 absences of links



- EHS: Algorithm shown complete when NOT assuming faithfulness.
- HEH: Utilizing faithfulness for data sets sharing the same variables.
- BILIN: Another method in the article, cut out of the presentation.
- LININF: Linear Inference -algorithm just presented.

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- Which of the unidentified links are inherently undetermined?

Conclusion

General learning setting:

- Multiple completely or partially overlapping data sets
- Experimental or non-experimental data
- Cycles, No joint causal sufficiency, Linear causal relations



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Contributions:

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- Faithfulness constraints decoded with exp. effects
- Linear Inference -algorithm by overparametrizing, generalizing previous constraint equations, and enforcing only the linear equations

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