



Controllability of Control Argumentation Frameworks

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Motivation: The study of computational models of argumentation is an active and vibrant area of modern Al research
Control argumentation frameworks recently proposed formalism for reasoning under uncertainty
Computational complexity of controllability not established, no system implementation available

Contributions: Complete complexity map of credulous and skeptical controllability under five central AF semantics

Design of algorithms for solving controllability: QBF encodings and SAT-based CEGAR algorithms

System implementation and empirical evaluation: approaches are complementary

CONTROL ARGUMENTATION FRAMEWORKS -

Argumentation Framework (AF)

A directed graph AF = (A, R):

- *A* is the set of **arguments**
- $R \subseteq A \times A$ is the **attack relation**

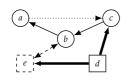
Semantics σ define σ -extensions

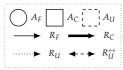
- jointly acceptable sets of arguments
- required to be **conflict-free**
- other desired properties give rise to different semantics: admissible, complete, preferred, stable, grounded

Control Argumentation Framework (CAF)

An AF with three parts:

- (A_F, R_F) : **fixed** part
- $(A_U, R_U, R_U^{\leftrightarrow})$: **uncertain** part
- (A_C, R_C) : **control** part





 $Example\ control\ argumentation\ framework.$

Controllability

Control configuration: subset of arguments $A_{conf} \subseteq A_C$ **Completion:** standard AF with the fixed part, the control configuration, and any uncertain elements

SKEPTICAL CONTROLLABILITY

Is there a **control configuration** such that for all **completions**, target set $T \subseteq A_F$ is included in **every** σ -extension?

ALGORITHMS FOR SOLVING CONTROLLABILITY -

Input: Control AF *CAF*, target set $T \subseteq A_F$.

Basis: SAT Encodings

Boolean variables:

- y_a for each argument a, $r_{a,b}$ for each attack (a,b)
- true iff element included in completion
- x_a for each argument a
- ullet true iff argument included in σ -extension

Propositional formulas:

- $\varphi_{?}(CAF)$ encodes control configurations and completions
- $\varphi_{\sigma}(CAF)$ for $\sigma \in \{adm, com, stb\}$ encodes the semantics

QBF Encodings

Task: Skeptical controllability under $\sigma \in \{com, stb\}$. **Quantifier blocks:** $X = \{y_a \mid a \in A_C\}$, $Y = \{y_a \mid a \in A_U\}$ $\cup \{r_{a,b} \mid (a,b) \in R_U \cup R_U^{\leftrightarrow}\} \cup \{x_a \mid a \in A_F \cup A_U \cup A_C\}$ **2-QBF:**

$$\forall X \exists Y \left(\varphi_?(CAF) \land \varphi_\sigma(CAF) \land \bigvee_{t \in T} \neg x_t \right)$$

false iff CAF is skeptically controllable under σ

SAT-based CEGAR Algorithms

Algorithms where a **SAT solver** is **called iteratively** and incrementally using different assumptions.

Task: Skeptical controllability under $\sigma = com$.

$$\varphi \leftarrow \varphi_?(CAF) \land \varphi_{com}(CAF)$$
 while true do

 $(result, \tau) \leftarrow SAT(\varphi \land \bigwedge_{t \in T} x_t)$ \triangleright Solve abstraction **if** result = unsat **then return** reject

$$(result, \tau) \leftarrow \text{SAT}(\varphi \land \psi(A_{conf}^{\tau}) \land \bigvee_{t \in T} \neg x_t) \rightarrow \text{C.E.?}$$

if
$$result = unsat$$
 then return A_{conf}^{τ}
 $\varphi \leftarrow \varphi \land \text{REFINE}(A_{conf}^{\tau}) \Rightarrow \text{Exclude config}$

 $\varphi \leftarrow \varphi \land \mathsf{REFINE}(A_\mathit{conf}^{\intercal}) \qquad \triangleright \mathsf{Exclude} \ \mathsf{configuration}$ end while

Strong refinement: take into account which atomic changes preserve the counterexample extension of the completion

For $\sigma = stb$: instead of direct *reject*: is there a configuration without a completion with a stable extension?

In paper: 3-QBF and SAT-based CEGAR algorithm for credulous controllability under $\sigma \in \{adm, stb\}$

COMPUTATIONAL COMPLEXITY OF CONTROLLABILITY -

	General CAFs		Simplified CAFs	
Semantics	Credulous	Skeptical	Credulous	Skeptical
admissible	Σ ₃ - c	trivial	NP-c	trivial
complete	Σ_3^{P} -c	Σ_2^{P} -c	NP-c	NP-c
preferred	Σ_3^{P} -c	Σ_3^{P} -c	NP-c	Σ_3^{P} -c
stable	Σ_3^{P} -c	Σ_2^{P} -c	NP-c	Σ_2^{P} -c
grounded	Σ_2^{P} -c	$\Sigma_2^{\bar{P}}$ -c	NP-c	NP-c

- Controllability in **simplified CAFs** corresponds to possible acceptance in **incomplete AFs**
 - Simplified CAF: no uncertain part
- Reduction from possible acceptance
- Some hardness results for general CAFs follow from hardness in simplified CAFs
- The rest via reduction from QBF (in paper)

- EMPIRICAL EVALUATION -

Implementation: TAEYDENNAE

- Solver for incomplete and control AFs
- SAT-based CEGAR algorithms + QDIMACS output
- Available online in open source:

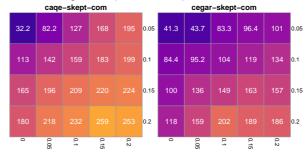
bitbucket.org/andreasniskanen/taeydennae

Benchmark instances

6250 control AFs generated from ICCMA'19 AFs

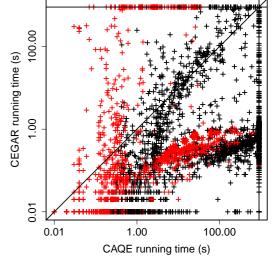
- p_C , four values in [0.05, 0.2]: prob. of control argument
- p_U , five values in [0, 0.02]: prob. of uncertain element

Mean solving times: p_U on rows, p_C on columns



Task: Skeptical controllability under $\sigma = com$

SAT-based CEGAR vs. QBF solver CAQE:



In paper: Empirical results for other variants

REFERENCES

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