



## Preliminary: Probability and tail bound for sketches algorithms

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#### **Basic Probability Theory**

A **probability space** is a triple  $(\Omega, E, P)$  with

- a set  $\Omega$  of elementary events (sample space),
- a family E of subsets of Ω with Ω∈E which is closed under
  ∩, ∪, and with a countable number of operands
  (with finite Ω usually E=2<sup>Ω</sup>), and
- a **probability measure P:**  $\mathbf{E} \rightarrow [0,1]$  with  $P[\Omega]=1$  and  $P[\cup_i A_i] = \sum_i P[A_i]$  for countably many, pairwise disjoint  $A_i$



Properties of P:  $P[A] + P[\neg A] = 1$   $P[A \cup B] = P[A] + P[B] - P[A \cap B]$   $P[\emptyset] = 0$  (null/impossible event)  $P[\Omega] = 1$  (true/certain event)

### Independence of events

• Two events A and B are independent if

 $p(A \cap B) = p(A)p(B)$ 

• Conditional probability: For two events A and B with p(B) > 0, the probability of A conditioned on B is  $p(A|B) = \frac{p(A \cap B)}{p(B)}$ .

### **Random variable**

- A random variable X is a function  $X: \Omega \to R$ .
- $\Pr[X = a] = \sum_{s \in \Omega: X(s) = a} p(s)$ .
- Two random variables *X* and *Y* are independent if

 $\Pr[(X = a) \land (Y = b)] = \Pr[X = a] \Pr[Y = b].$ 



#### Expectation

• Expectation:

$$\mathbf{E}[X] = \sum_{s \in \Omega} p(s)X(s)$$
$$= \sum_{i \in \text{Range}(X)} i \cdot \Pr[X = i]$$

• Linearity of expectation:

 $\mathbf{E}[\sum_{i} X_{i}] = \sum_{i} \mathbf{E}[X_{i}]$ 

no matter whether  $X_i$ 's are independent or not.



• The variance of X is

$$Var[X] = E[(X - E[X])^2] = E[X^2] - E[X]^2$$

• The standard deviation of *X* is

$$\sigma = \sqrt{\mathbf{Var}[X]}$$

### **Concentration and tail bounds**

- In many analysis of randomized algorithms, we need to study how concentrated a random variable X is close to its mean E[X].
  - Many times  $X = X_1 + \dots + X_n$ .
- Upper bounds of

 $\Pr[X \text{ deviates from } E[X] \text{ a lot}]$ 

is called *tail bounds*.



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### Markov's Inequality: when you only know expectation

• [Thm] If  $X \ge 0$ , then

$$\Pr[X \ge a] \le \frac{\mathbf{E}[X]}{a}.$$

In other words, if  $E[X] = \mu$ , then  $\Pr[X \ge k\mu] \le \frac{1}{k}$ .

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### Chebyshev's Inequality: when you also know variance

• [Thm]  $\Pr[|X - \mathbf{E}[X]| \ge a] \le \frac{\operatorname{Var}[X]}{a^2}$ . In other words,

$$\Pr[|X - \mathbf{E}[X]| \ge k \cdot \sqrt{\operatorname{Var}[X]}] \le \frac{1}{k^2}.$$

# Chernoff's Bound

• [Thm] Suppose  $X_i = \begin{cases} 1 & \text{with prob. } p \\ 0 & \text{with prob. } 1 - p \end{cases}$  and let

$$X = X_1 + \dots + X_n.$$

Then

$$\Pr[|X - \mu| \ge \delta\mu] \le 2 e^{-\delta^2 \mu/3},$$

where  $\mu = np = \mathbf{E}[X]$ .

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### Some basic applications: coin tossing

- A fair coin
  - f(x) = 0: with probability 1/2
  - f(x) = 1: with probability 1/2
- Repeatedly toss the coin, Let S<sub>n</sub> be the number of heads from the first n tosses.
- $E(S_n) = n/2$ ,  $Var(S_n) = n/4$
- $E(S_n/n) = 1/2$ ,  $Var(S_n/n) = 1/(4n)$

### Some basic applications: coin tossing

- In terms of Chebyshev's inequality
- $P(|\frac{S_n}{n} 1/2| \ge \epsilon) \le 1 / (4n \epsilon^2)$

• For example 
$$P(|\frac{S_n}{n} - 1/2| \ge 1/4) \le 4/n$$

- But if we use Chernoff bound,  $E(S_n) = n/2$
- $\Pr[|S_n n/2| \ge \delta n/2] \le 2 e^{-\delta^2 n/6}$ ,
- Taking  $\delta = \frac{1}{2}$ ,  $\Pr[|S_n/n 1/2| \ge 1/4] \le 2e^{-\delta^2 n/6} = 2e^{-n/24}$ .



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