



# LEARNING CHORDAL MARKOV NETWORKS BY DYNAMIC PROGRAMMING

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**Motivation:** Structure learning in Markov networks asks for an undirected graph that maximizes a given decomposable scoring function. A special interest is in learning graphs that are *chordal*, since chordal Markov networks (CMNs) of low width admit efficient inference.

**Our contribution:** We present a dynamic programming algorithm that finds optimal CMNs on  $n$  variables in  $O(4^n)$  time. Experiments demonstrate our implementation is competitive with recent algorithms based on constraint satisfaction [1] and linear programming [2].

## INTRODUCTION

### CHORDAL MARKOV NETWORKS

A *Markov network*:

- Undirected graph  $\mathcal{G}$  on  $V = \{1, \dots, n\}$
- Represents a joint distribution

$$p(x_1, \dots, x_n) = \prod_{C \in \mathcal{C}} \psi_C(x_C),$$

where  $\mathcal{C}$  is the set of (maximal) cliques of  $\mathcal{G}$  and  $\psi_C$  are mappings to positive reals.

A *chordal Markov network*:

- Every cycle of length  $\geq 4$  has an edge between two non-consecutive vertices.
- Admits a clique tree decomposition.

### STRUCTURE LEARNING PROBLEM

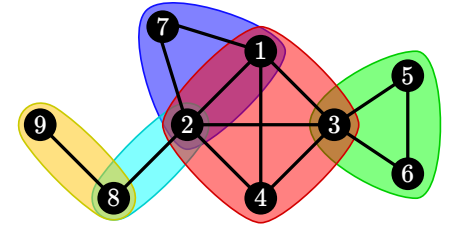
Given data  $D$ , i.e., samples on  $x_1, \dots, x_n$ , a *scoring criterion*  $s_D(\mathcal{G})$  measures how well a chordal graph  $\mathcal{G}$  fits  $D$ .

Common scores (e.g. maximum likelihood, Bayesian Dirichlet) decompose as

$$s_D(\mathcal{G}) = \frac{\prod_{C \in \mathcal{C}} s_D(C)}{\prod_{S \in \mathcal{S}} s_D(S)},$$

where  $\mathcal{S}$  is the (multi)set of *separators*.

Separator: intersection of adjacent cliques in a clique tree decomposition of  $\mathcal{G}$ .



$$\frac{s_D(8,9)s_D(2,8)s_D(1,2,7)s_D(1,2,3,4)s_D(3,5,6)}{s_D(8)s_D(2)s_D(1,2)s_D(3)}$$

**Input:**  $s_D(A)$  for every  $A \subseteq V$ .

**Problem:** find a chordal graph  $\mathcal{G}$  of best fit, i.e., maximizing  $s_D(\mathcal{G})$ .

## RECURRENCE

Chordal graphs admit a recursive characterization of the problem.

For  $S \subset V$  and  $\emptyset \subset R \subseteq V \setminus S$ , let  $f(S, R)$  be the maximum  $s_D(\mathcal{G})$  over chordal  $\mathcal{G}$  on  $S \cup R$  s.t.  $S$  is a proper subset of a clique.

Then, the solution is given by  $f(\emptyset, V)$  and

$$f(S, R) = \max_{\substack{S \subset C \subseteq S \cup R \\ \{R_1, \dots, R_k\} \subseteq R \setminus C \\ S_1, \dots, S_k \subset C}} s_D(C) \prod_{i=1}^k \frac{f(S_i, R_i)}{s_D(S_i)}.$$

Dynamic programming runs in  $O(4^n)$  time and  $O(3^n)$  space on simplified recurrences:

1. Given sets  $S$  and  $R$ , choose a clique  $C$  within  $R$  that contains  $S$  completely:

$$f(S, R) = \max_{S \subset C \subseteq S \cup R} s_D(C) g(C, R \setminus C)$$

2. Partition the remaining vertices into  $R_1, \dots, R_k$ :

$$g(C, U) = \max_{\emptyset \subset R \subseteq U} h(C, R) g(C, U \setminus R)$$

3. For each part  $R$  choose a separator  $S$  contained in  $C$ . Recurse back to step 1:

$$h(C, R) = \max_{S \subset C} f(S, R) / s_D(S)$$

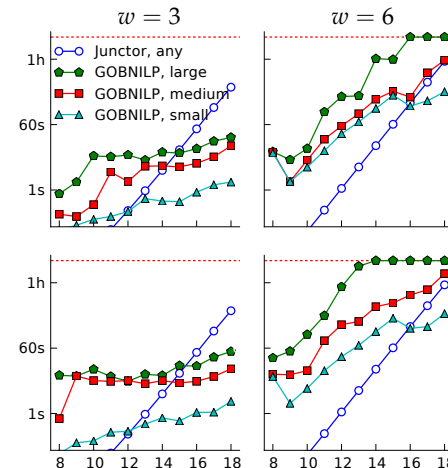
## EXPERIMENTS

Compared to a recent constraint satisfaction based algorithm [1], our C++ implementation, *Junctor* (\*), appears to be faster by several orders of magnitude.

We also compared against the freely available *GOBNILP* (\*\*) on several instances.

### SYNTHETIC INSTANCES

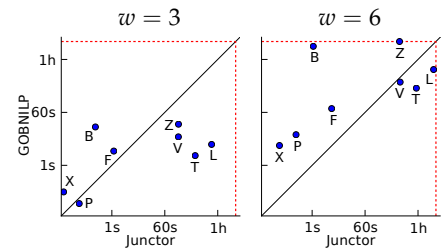
The running times (median for *GOBNILP*) as a function of  $n$ , on sparse (top) and dense (bottom) instances with 100 (“small”), 1000 (“medium”), and 10,000 (“large”) data samples, bounding clique size by  $w$ . The top red line indicates timeout or memout.



### BENCHMARK INSTANCES

The running times on the following benchmark instances from the UCI repository.

Dataset	Abbr.	$n$	Samples
Tic-tac-toe	X	10	958
Poker	P	11	10000
Bridges	B	12	108
Flare	F	13	1066
Zoo	Z	17	101
Voting	V	17	435
Tumor	T	18	339
Lymph	L	19	148



*Junctor* can solve instances of up to 22 variables within a few days for  $w = 4$ .

(\*) *Junctor* is publicly available to download at [www.cs.helsinki.fi/u/jwkangas/junctor/](http://www.cs.helsinki.fi/u/jwkangas/junctor/).

(\*\*) *GOBNILP* by Bartlett and Cussens [2] uses integer linear programming for learning optimal Bayesian networks, but can also be restricted to learning chordal Markov networks.

[1] J. Corander, T. Janhunen, J. Rintanen, H. J. Nyman and J. Pensa. Learning chordal Markov networks by constraint satisfaction. NIPS, pages 1349–1357. 2013.

[2] M. Bartlett and J. Cussens. Advances in Bayesian network learning using integer programming. UAI, pages 182–191. 2013.