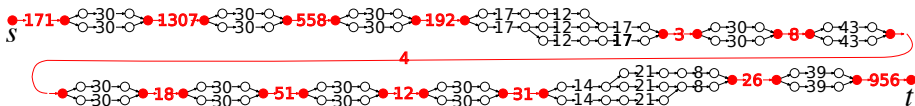# Safely filling gaps
with partial solutions common to all solutions
WABI 2016

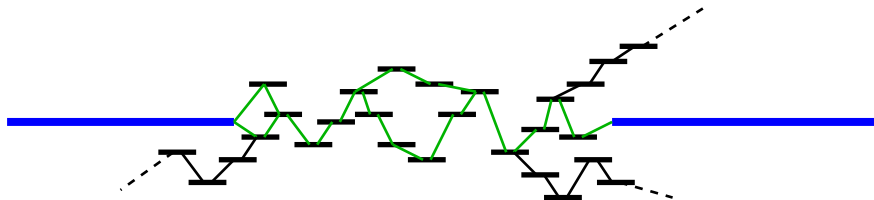Leena Salmela   Alexandru I. Tomescu

University of Helsinki

August 23rd, 2016

Gap filling

- ▶ Gap filling is the last phase in genome assembly
- ▶ Input: Scaffolds (=linearly ordered contigs) and reads
- ▶ Output: Scaffolds where gaps between contigs have been filled

Gap filling
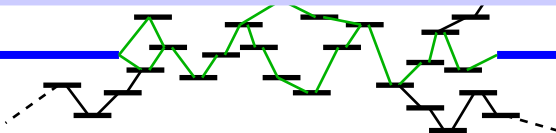
- Gap filling is the last phase in genome assembly
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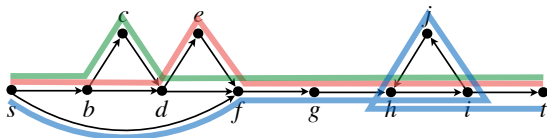**What if there are multiple paths?**

Safe and complete solutions

An algorithm is

- safe: it returns only partial solutions that are common to all solutions
- complete: it returns all safe solutions

We give a gap filling algorithm that is safe.

Previous work on safe solutions for gap filling

- ▸ Wetzel et al. 2011
  - ▸ Unique paths
  - ▸ Unique shortest paths
- ▸ Konnector (Vandervalk et al. 2014)
  - ▸ Exhaustive enumeration of all *s*-*t* paths (up to a threshold)
  - ▸ Fill a gap only when there are at most a given number of paths
  - ▸ Form multiple alignment
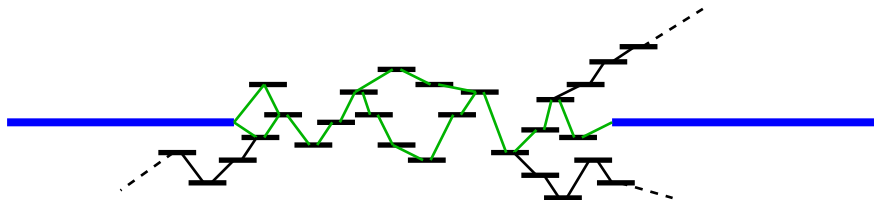 - ▸ Use consensus sequence with IUPAC codes

Gap filling problem

Given

- an (overlap or de Bruijn) graph $G = (V, E)$ of the whole read set
- a cost function $c : E \mapsto \mathbb{Z}_+$
- two vertices s and t representing the flanks of the contigs
- estimate of the gap length d

find an s-t path $P = v_1, v_2, \ldots, v_k$ such that
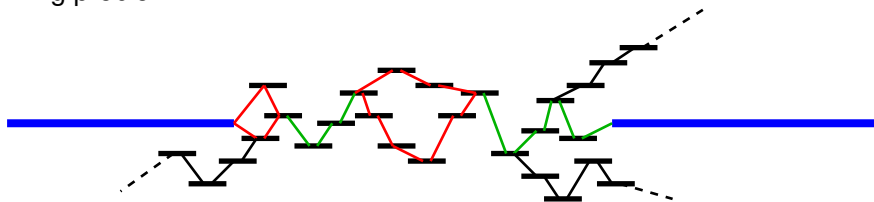
$$cost(P) = \sum_{i=1}^{k-1} c(v_i, v_{i+1}) = d.$$

Safe and complete gap filling problem

Given

- an (overlap or de Bruijn) graph $G = (V, E)$ of the whole read set
- a cost function $c : E \mapsto \mathbb{Z}_+$
- two vertices s and t representing the flanks of the contigs
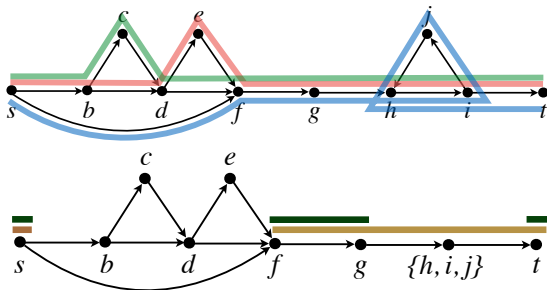- estimate of the gap length d

find all maximal paths in G that are sub-paths of all solutions to the gap filling problem.

...GTTTACGtggGATCgacggggGAGCTACTAGACGGTA...
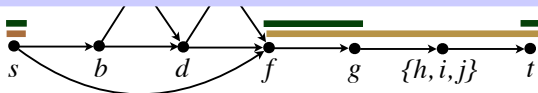
Safe (but not complete) algorithm for gap filling

- Determine the graph G_d made up of all edges and vertices on some *s-t* path in *G* of length *d*
- Compute the graph G_d^{SCC} of strongly connected components $\implies$ DAG!
- Find all maximal paths that are sub-paths of all *s-t* paths in G_d^{SCC} $\iff$ Find bridges and cut vertices
- The corresponding paths in G_d are also sub-paths of all *s-t* paths in G_d

Safe (but not complete) algorithm for gap filling

- Determine the graph G_d made up of all edges and vertices on some *s-t* path in G of length d: $O(d|E|)$
- Compute the graph G_d^{SCC} of strongly connected components $\implies$ DAG!: $O(|V| + |E|)$
- Find all maximal paths that are sub-paths of all *s-t* paths in G_d^{SCC} $\iff$ Find bridges and cut vertices: $O(|E|)$
- The corresponding paths in G_d are also sub-paths of all *s-t* paths in G_d

$$\implies O(d|E|)$$

Experimental setup

Algorithms considering the safety notion:

- ▶ Gap2Seq Safe (this work)
- ▶ Gap2Seq Unique (only unique paths are safe)
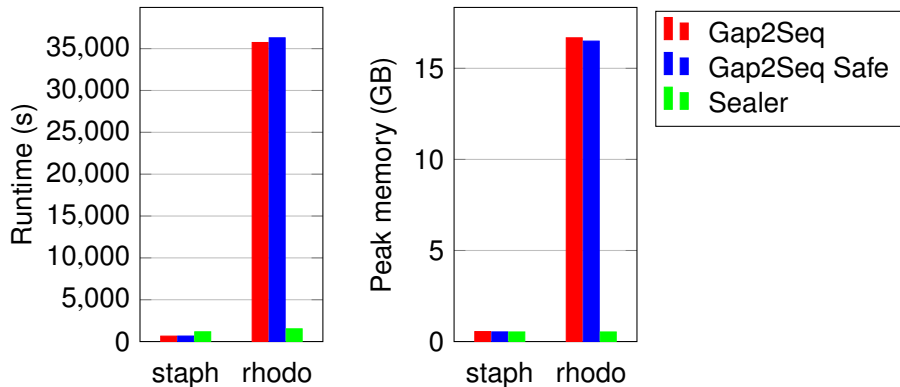- ▶ Sealer (Paulino et al. 2015)

Other algorithms:

- ▶ Gap2Seq (Salmela et al. 2015)
- ▶ GapFiller with Bowtie (Boetzer and Pirovano 2012)
- ▶ GapFiller with BWA (Boetzer and Pirovano 2012)
- ▶ SOAPdenovo GapCloser (Luo et al. 2012)

Data sets:

- ▶ All *S. aureus* and *R. sphaeroides* assemblies from GAGE

Runtime and memory usage

- Experiments run on all 8 GAGE assemblies.
- We show aggregates over all assemblies.

Precision and recall

Align the filled scaffolds against the reference and
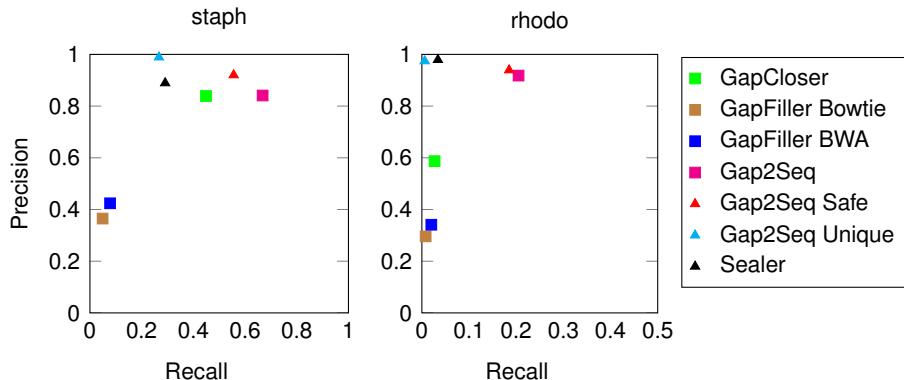compute for aligned filled sequences:

- Precision:

$$\frac{\#\text{correct safe bases}}{\#\text{safe bases}}$$

- Recall:

$$\frac{\#\text{correct safe bases}}{\#\text{total gap bases}}$$

For algorithms that do not differentiate between safe and nonsafe bases
all bases were considered safe.

Precision and recall

- Experiments run on all 8 GAGE assemblies.
- We show aggregates over all assemblies.

Conclusions

- We introduced the safe and complete gap filling problem
- We gave an algorithm for gap filling which is safe
- Open problem:
  Existence of an efficient safe and complete algorithm for gap filling

Thanks!

Questions?

http://www.cs.helsinki.fi/u/lmsalmel/Gap2Seq/